

Schauder estimates/heat kernel.

given some kernel K that "improves regularity by $\beta=2$ ", we want to construct a lift $\kappa: \mathcal{D}^{\alpha} \rightarrow \mathcal{D}^{\alpha+\beta}$ such that

$$R\kappa f = K * Rf$$

Assumption 1. The regularity structure contains a sector $T_{\text{poly}} \subseteq T$ such that T_{poly} is isomorphic to the polynomial RS.

Assumption 2. There is a sector $V \subseteq T$ and a linear map $\tilde{\mathcal{I}}: V \rightarrow T$ such that $\tilde{\mathcal{I}}(V \cap T_{\alpha}) \subseteq T_{\alpha+\beta}$ and for every $\Gamma \in G$, $\tau \in T$, $\Gamma \tilde{\mathcal{I}}\tau - \tilde{\mathcal{I}}\Gamma\tau \in T_{\text{poly}}$.

How should this play with the model?

Given a β -regularizing kernel K and a RS T satisfying the last two assumptions, we say that a model (Π, Γ) is admissible if

$$(\Pi_x \underline{x}^k)(y) = (y-x)^k.$$

and

$$\Pi_x(\mathcal{I}\tau) = K * \Pi_x \tau - \Pi_x g_x \tau$$

where for $\tau \in T_{\alpha}$,

$$g_x \tau = \sum_{|k| < \alpha + \beta} \frac{\underline{x}^k}{k!} \int (\Pi^k K)(x-y) \cdot (\Pi_x \tau)(dy).$$

typical ex: $\alpha = -3/2$, $\beta = 2$.

then $g_x \tau = \mathbb{1} \cdot (K * (\Pi_x \tau))(x)$.

Given this setup, we can define the operator $K: \mathcal{D}^\gamma \rightarrow \mathcal{D}^{\gamma+\beta}$.

$$(Kf)(x) = I(f(x)) + g_x(f(x)) + (Nf)(x)$$

where

$$(Nf)(x) = \sum_{|k| < \gamma + \beta} \frac{x^k}{k!} \int \mathbb{D}^k K(x-y) (Rf - \Pi_x f)(y) dy$$

Theorem. Let K be a β -regularizing kernel, τ be a RS satisfying the assumptions, and let (Π, Γ) be an admissible model. Then for every $f \in \mathcal{D}^\gamma$ (w/ some technical assumptions on γ e.g. $\gamma + \beta \in \mathbb{N}$), we have

$Kf \in \mathcal{D}^{\gamma+\beta}$, and $R(Kf) = K(Rf)$.
 $\hookrightarrow$ "multilevel Schauder estimate".

Let's give a proof of the last part in the case where the model consists of continuous functions, so $Rf(x) = (\Pi_x f(x))(x)$.

In that case,

$$(RKf)(x) = \Pi_x(If(x) + g_x f(x))(x) + (\Pi_x(Nf)(x))(x)$$

For the first term,

$$\begin{aligned} \Pi_x(If(x) + g_x f(x))(x) \\ = K * \Pi_x f(x). \end{aligned} \quad \leftarrow \text{cancel}$$

For the second term, only $k=0$ contributes, so

$$\begin{aligned} (\Pi_x(Nf)(x))(x) &= \int K(x-y) (Rf - \Pi_x f)(x) dy \\ \text{so } (RKf)(x) &= (K * Rf)(x). \end{aligned}$$

KP2 Equation

How can we use this to set up solutions to the KP2 equation?

$$\partial_t h - \frac{1}{2} \Delta h = \frac{1}{2} (\partial_x h)^2 + \xi$$

First remark: we need to use "parabolic rescaling"

$$\varphi_{(s,x)}^\lambda(t,y) = \lambda^{-3} \varphi(\lambda^{-2}(t-s), \lambda^{-1}(y-x))$$

and when we count the degree of a polynomial, time counts as degree 2.

$$\text{e.g. } \deg(\underline{t}^4 \underline{x}^3) = 2 \cdot 4 + 1 \cdot 3 = 11.$$

w/ this way of measuring, one can check that w.p.1, $\xi \in C^\alpha$ for every $\alpha < -\frac{3}{2}$.
since $(E \langle \xi, \varphi_x^\lambda \rangle^2)^{1/2} = \|\varphi_x^\lambda\|_{L^2} \sim \lambda^{-3/2}$.

Mild solution formula:

$$h = G \underset{\substack{\uparrow \\ \text{spatial} \\ \text{conv.}}}{*} h_0 + G \underset{\substack{\uparrow \\ \text{spatial} \\ \text{conv.}}}{*} \left[\frac{1}{2} (\partial_x h)^2 + \xi \right]$$

goal: lift this to an equation of modeled distributions of the form

$$\underline{H} = \underline{G}_t \underset{\substack{\uparrow \\ \text{polynomial lift}}}{*} h_0 + \underline{G} \underset{\substack{\uparrow \\ \text{lifted} \\ \text{noise}}}{*} \left[\frac{1}{2} (\partial_x \underline{H})^2 + \underline{\xi} \right]$$

First question: what terms should we include in the RS besides polynomials?

RHS: $G[\frac{1}{2}(\partial H)^2 + \Sigma]$
 $H = \text{poly}^+$

Fix $K > 0$
 very small.
 iteration

First, we should add $\Sigma = \bullet$

Then add $\mathcal{I}\mathcal{T} = \text{wavy line}$. Add 2 to $\text{deg}(\bullet)$

Next, $\partial \mathcal{I}\mathcal{T} = \mathcal{I}'\mathcal{T} = \text{dot}$

Multiply $\text{dot} \star \text{dot} = \text{V}$. Then get wavy line , V .

Also have $\mathcal{I}(\underline{1} \cdot \text{dot}) = \text{hook}$, $\mathcal{I}'(\underline{1} - \text{dot}) = \text{hook}$

why can we stop here? It suffices to truncate the regularity structure at a degree δ such that our PDE is well-posed in $\mathcal{D}^\delta$.
 Let's figure out what that δ should be.

noise	nonlinearity	solution	solution'
$\bullet$	$\text{V}, \text{hook}, \text{hook}, \text{hook}$	$\text{wavy line}, \text{V}, \text{hook}, \text{hook}$	$\text{dot}, \text{V}, \text{hook}$
let's construct solution' in $\mathcal{D}^{\frac{1}{2} + 10K}$ $-\frac{1}{2} - K$			

$\mathcal{T}$	$\text{deg}(\mathcal{T})$
$\bullet$	$-3/2 - K$
wavy line	$1/2 - K$
dot lollipop	$-1/2 - K$
V cherry	$-1 - 2K$
hook	$1 - 2K$
hook	$-2K$
hook	$3/2 - K$
hook	$1/2 - K$
hook elk	$-1/2 - 3K$
hook claw	$-2K$
hook candelabra	$-4K$
hook	$3/2 - 3K$
hook	$1/2 - 3K$

$\mathcal{T}$	$\text{deg} \mathcal{T}$
hook moose	$-4K$

$$H = \text{poly} + G\left(\frac{1}{2}(\partial H)^2 + \frac{2}{3}\right), \quad \underline{U} = \partial H$$

$$\underline{U} = \text{poly} + \partial G\left[\frac{1}{2}U^2 + \frac{2}{3}\right] \tau$$

noise	nonlinearity	solution	solution'
•			

let's construct solution' in $\mathcal{D}^{\frac{1}{2}+10K}_{-\frac{1}{2}-K}$

$$\star: \mathcal{D}^{\frac{1}{2}+10K}_{-\frac{1}{2}-K} \times \mathcal{D}^{\frac{1}{2}+10K}_{-\frac{1}{2}-K} \rightarrow \mathcal{D}^{9K}_{-1-2K} = 1-4K$$

so construct the nonlinearity in $\mathcal{D}^{9K}_{-1-2K}$

Then when we integrate and then differentiate,
we get $\partial G[(\partial H)^2] \in \mathcal{D}^{1+9K}_{-2K}$.

$$\underline{\text{OTDH}}: \partial G \frac{2}{3} \in \mathcal{D}^{\infty}_{-\frac{1}{2}-K}.$$

$$\text{so altogether get solution}' \in \mathcal{D}^{1+9K}_{-\frac{1}{2}-K}$$

$$\subseteq \mathcal{D}^{\frac{1}{2}+10K}_{-\frac{1}{2}-K}.$$

two main points: ① can close the argument.
② $9K > 0$ so can reconstruct the forcing = noise + nonlinearity

	$\deg(\tau)$
	$-3/2 - K$
	$1/2 - K$
lollipop	$-1/2 - K$
cherry	$-1 - 2K$
	$1 - 2K$
	$-2K$
	$3/2 - K$
	$1/2 - K$
elk	$-1/2 - 3K$
claw	$-2K$
candelabra	$-4K$
	$3/2 - 3K$
	$1/2 - 3K$

τ	$\deg \tau$
	$-4K$
MOOSE	

Next time: how to build the model
(& the structure group).

(at that point we will need
to renormalize)