

21. Chapter 5: Determinants  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$   
can be any F

Thm:  $\exists!$  function  $\det: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$  satisfying

- alternating 1.  $\det A = 0$  if  $A$  has two equal adjacent rows  $\rightarrow$   $\det \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} = 0$
- 2.  $\det A' = c \det A$  if  $A'$  is obtained by multiplying a row of  $A$  by  $c$ .  $\rightarrow$   $\det \begin{bmatrix} \text{---} \\ cR \\ \text{---} \\ \text{---} \end{bmatrix} = c \det \begin{bmatrix} \text{---} \\ R \\ \text{---} \\ \text{---} \end{bmatrix}$
- 3.  $\det A = \det A' + \det A''$  if  $A, A', A''$  agree in all rows except row  $i$ , where  $A_i = A'_i + A''_i$ .  $\rightarrow$   $\det \begin{bmatrix} \text{---} \\ + \\ \text{---} \\ \text{---} \end{bmatrix} = \det \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} + \det \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$
- 4.  $\det I_n = 1$ .

multilinear

We've seen bilinear:  $\langle \cdot, \cdot \rangle$   
 linear in each variable

Def:  $\det A$  is the determinant of  $A$ .

Pf:  $\exists$  uses cofactors - next class.

!: assume  $\det: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$  is some function satisfying #1 - #4.

Lemma:  $\det A' = -\det A$  if  $A'$  has two rows swapped from  $A$ .

Pf:

$$0 \stackrel{\#1}{=} \det \begin{bmatrix} \vdots \\ -x+y \\ -x+y \\ \vdots \end{bmatrix} \stackrel{\#3}{=} \det \begin{bmatrix} \vdots \\ -x \\ -x+y \\ \vdots \end{bmatrix} + \det \begin{bmatrix} \vdots \\ -y \\ -x+y \\ \vdots \end{bmatrix}$$

$$\stackrel{\#3}{=} \cancel{\det \begin{bmatrix} \vdots \\ -x \\ -x \\ \vdots \end{bmatrix}} + \det \begin{bmatrix} \vdots \\ -x \\ -y \\ \vdots \end{bmatrix} + \det \begin{bmatrix} \vdots \\ -y \\ -x \\ \vdots \end{bmatrix} + \cancel{\det \begin{bmatrix} \vdots \\ -y \\ -y \\ \vdots \end{bmatrix}}$$

so done if swapped rows adjacent. If not adjacent, then

$$i \begin{bmatrix} \vdots \\ -A_i \\ \vdots \\ -A_j \\ \vdots \end{bmatrix} \xrightarrow{j-i \text{ steps}} i+1 \begin{bmatrix} \vdots \\ -A_i \\ \vdots \\ -A_j \\ \vdots \end{bmatrix} \xrightarrow{1 \text{ step}} i+1 \begin{bmatrix} \vdots \\ -A_j \\ \vdots \\ -A_i \\ \vdots \end{bmatrix} \xrightarrow{j-i \text{ steps}} j \begin{bmatrix} \vdots \\ -A_j \\ \vdots \\ -A_i \\ \vdots \end{bmatrix}$$

and  $(-1)^{2(j-i)+1} = -1. \square$

Cor:  $\det A = 0$  if any two rows are equal.

Pf: Swap 'til you drop.  $\square$

Prop 1.4:  $\det(EA) = \det E \det A$  if  $E$  is elementary.

Pf:  $E$  swaps rows:  $\det(EA) = -\det A = \det E \det A$   
*Lemma #4 + Lemma*

$E$  multiplies row by scalar  $c$ :  $\det(EA) = c \det A = \det E \det A$   
*#2 #2 + #4*

$E$  replaces  $A_i$  with  $A_i + cA_j$ :  
 $\det \begin{bmatrix} \vdots \\ A_i + cA_j \\ \vdots \\ -A_j \\ \vdots \end{bmatrix} \stackrel{\#3}{=} \det \begin{bmatrix} \vdots \\ -A_i \\ \vdots \\ -A_j \\ \vdots \end{bmatrix} + \det \begin{bmatrix} \vdots \\ cA_j \\ \vdots \\ -A_j \\ \vdots \end{bmatrix}$   
 $\stackrel{\#2}{=} \det A + c \det \begin{bmatrix} \vdots \\ -A_j \\ \vdots \\ -A_j \\ \vdots \end{bmatrix}$  *0 by Cor.*

$A = I_n \Rightarrow \det E = 1 (!) \Rightarrow \det A = \det E \det A. \square$

Thm 1.2:  $A \in \mathbb{R}^{n \times n}$  singular  $\Leftrightarrow \det A = 0$ .

*If one row is a linear combination of the others, expanding by multilinearity yields 0 in every summand by alternation (#1).*

Pf: Write  $U = E_k \cdots E_1 A$  reduced echelon form.

$$\begin{aligned} \det U &= \det E_k \det(E_{k-1} \cdots E_1 A) \text{ by Prop 1.4.} \\ &= \det E_k \det E_{k-1} \det(E_{k-2} \cdots E_1 A) \\ &\vdots \\ &= \det E_k \det E_{k-1} \det E_{k-2} \cdots \det E_1 \det A. \end{aligned}$$

*any function  $\mathbb{R}^{n \times n} \rightarrow \mathbb{R}$  satisfying #1 - #4*

$A$  singular  $\Rightarrow U$  has zero-row  $U_n$  (bottom row)

$\Rightarrow \det U = 0 \Rightarrow \det A = 0$  by #2:  $U_n = 0 U_n$ . But

$$\det E = \begin{cases} -1 & \text{if } E \text{ has type (i)} \\ c & \text{(ii)} \\ 1 & \text{(iii)} \\ \neq 0 & \end{cases} \Rightarrow \det A = 0.$$

$A$  nonsingular  $\stackrel{\#4}{\Rightarrow} 1 = \det U = \det E_k \det E_{k-1} \det E_{k-2} \cdots \det E_1 \det A$   
 $\Rightarrow \det A \neq 0. \square$

To finish proof of !,  $\det A = 0$  if  $A$  singular

*At most one function can do this. Given that one exists, there only be one.*

$\det A = \frac{\det I_n}{\det E_k \cdots \det E_1}$  if  $A$  nonsingular.  $\square$

E.g.  $\det \begin{bmatrix} 2 & 4 & 6 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \stackrel{(i)}{=} -\det \begin{bmatrix} 1 & 0 & 1 \\ 2 & 1 & 0 \\ 2 & 4 & 6 \end{bmatrix} \stackrel{(iii)}{=} -\det \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 4 & 4 \end{bmatrix} \stackrel{(iii)}{=} -\det \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 12 \end{bmatrix} \stackrel{(ii)}{=} -12 \det \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$   
 $\stackrel{(iii)}{=} -12 \det I_3 = -12.$

Consequences (of  $\exists!$ , etc.)

Thm 1.5:  $A, B \in \mathbb{R}^{n \times n} \Rightarrow \det(AB) = \det A \det B$ .

Pf:  $A$  singular  $\Rightarrow \det A = 0 \Rightarrow \det A \det B = 0$ .

$\downarrow$   
 $L(A) \neq 0 \Rightarrow L(AB) \neq 0$  since  $L(AB) \geq L(A)$ :  $\boxed{A} = 0 \Rightarrow \boxed{A} \boxed{B} = 0$   
 $\Rightarrow AB$  singular  $\Rightarrow \det(AB) = 0$ .  $\checkmark$

$A$  nonsingular  $\Rightarrow \det(AB) = \det(E'_1 \dots E'_k B)$   
 $= \det E'_1 \dots \det E'_k \det B$   
 $= \det A \det B$ .  $\square$

Cor 1.6:  $\det(A^{-1}) = \frac{1}{\det A}$ .

Pf:  $\det(A) \det(A^{-1}) = \det(AA^{-1}) = \det I = 1$ .  $\square$

Cor:  $A$  similar to  $A' \Rightarrow \det A = \det A'$ .

Note: not  $\Leftrightarrow!$  e.g.  $A \sim I \Rightarrow A = ?$

Pf:  $\det(PAP^{-1}) = \det P \det A \det P^{-1}$   
 $= \det A$ .  $\square$

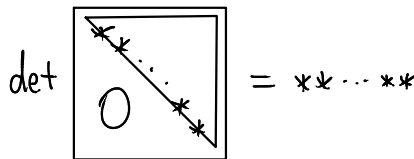
but  $\det E = 1$  for type (iii)

Prop 1.7:  $\det A^T = \det A$ .

Pf: Check for elementary matrices when  $A$  is nonsingular:  $E$  has same type as  $E^T$ .

Both = 0 if  $A$  is singular.  $\square$

Prop 1.3:  $A$  upper-triangular  $\Rightarrow \det A = a_{11} \dots a_{nn} =$  product of main diagonal entries.  
or lower -



Pf:  $A$  nonsingular  $\Rightarrow A \rightsquigarrow I_n$  by pulling out factors  $a_{11}, \dots, a_{nn}$  and then type (iii) operations, which have  $\det 1$ .

$A$  singular  $\Leftrightarrow < n$  pivots  $\Leftrightarrow a_{ii} = 0$  for some  $i$ .  $\square$