# Math 1553 Worksheet §§2.1, 2.2, 2.3 Solutions

**1.** If *A* is a  $3 \times 5$  matrix and *B* is a  $3 \times 2$  matrix, which of the following are defined?

- **a)** *A*−*B*
- **b)** *AB*
- **c)**  $A^T B$
- **d)**  $B^T A$
- **e)** *A*<sup>2</sup>

# Solution.

Only (c) and (d).

- **a)** A-B is nonsense. In order for A-B to be defined, A and B need to have the same number or rows and same number of columns.
- **b)** *AB* is undefined since the number of columns of *A* does not equal the number of rows of *B*.
- **c)**  $A^T$  is 5 × 3 and *B* is 3 × 2, so  $A^T B$  is a 5 × 2 matrix.
- **d)**  $B^T$  is 2 × 3 and A is 3 × 5, so  $B^T A$  is a 2 × 5 matrix.
- e)  $A^2$  is nonsense (can't multiply  $3 \times 5$  with another  $3 \times 5$ ).
- **2.** Consider the following linear transformations:

 $T: \mathbf{R}^3 \longrightarrow \mathbf{R}^2$  *T* projects onto the *xy*-plane, forgetting the *z*-coordinate  $U: \mathbf{R}^2 \longrightarrow \mathbf{R}^2$  *U* rotates clockwise by 90°

- $V: \mathbf{R}^2 \longrightarrow \mathbf{R}^2$  V scales the x-direction by a factor of 2.
- Let A, B, C be the matrices for T, U, V, respectively.
  - **a)** Compute *A*, *B*, and *C*.
- **b)** Compute the matrix for  $V \circ U \circ T$ .
- **c)** Compute the matrix for  $U \circ V \circ T$ .
- **d)** Describe  $U^{-1}$  and  $V^{-1}$ , and compute their matrices.

## Solution.

a) We plug in the unit coordinate vectors:

$$T(e_{1}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad T(e_{2}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad T(e_{3}) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \implies A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$
$$U(e_{1}) = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \quad U(e_{2}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \implies B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} .$$
$$V(e_{1}) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \quad V(e_{2}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \implies C = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$$
$$b) \quad CBA = \begin{pmatrix} 0 & 2 & 0 \\ -1 & 0 & 0 \end{pmatrix}$$
$$c) \quad BCA = \begin{pmatrix} 0 & 1 & 0 \\ -2 & 0 & 0 \end{pmatrix}$$

**d)**  $U^{-1}$  is counterclockwise rotation by 90°, and  $V^{-1}$  scales the *x*-direction by a factor of 1/2. Their matrices are, respectively,

$$B^{-1} = \frac{1}{0 \cdot 0 - (-1) \cdot 1} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

and

$$C^{-1} = \frac{1}{2 \cdot 1 - 0 \cdot 0} \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 1/2 & 0 \\ 0 & 1 \end{pmatrix}.$$

**3.** Solve AB = BC for A, assuming A, B, C are  $n \times n$  matrices and B is invertible. Be careful!

#### Solution.

$$AB = BC$$
  $AB(B^{-1}) = BC(B^{-1})$   $AI_n = BCB^{-1}$   $A = BCB^{-1}$ 

It is very important that we multiplied by  $B^{-1}$  on the same side in each equation, since matrix multiplication generally is not commutative. Had we multiplied by  $B^{-1}$  on the left for each side, we would have found  $B^{-1}AB = C$ .

- **4.** True or false (justify your answer). Answer true if the statement is *always* true. Otherwise, answer false.
  - a) If *A* is an  $m \times n$  matrix and *B* is an  $n \times p$  matrix, then each column of *AB* is a linear combination of the columns of *A*.
  - **b)** If *A* and *B* are  $n \times n$  and both are invertible, then the inverse of *AB* is  $A^{-1}B^{-1}$ .
  - c) If  $A^T$  is not invertible, then A is not invertible.
  - **d)** If *A* is an  $n \times n$  matrix and the equation Ax = b has at least one solution for each *b* in  $\mathbb{R}^n$ , then the solution is *unique* for each *b* in  $\mathbb{R}^n$ .
  - e) If *A* and *B* are invertible  $n \times n$  matrices, then A + B is invertible and  $(A + B)^{-1} = A^{-1} + B^{-1}$ .

**f)** If *A* and *B* are  $n \times n$  matrices and ABx = 0 has a unique solution, then Ax = 0 has a unique solution.

### Solution.

- a) True.
- **b)** False.  $(AB)^{-1} = B^{-1}A^{-1}$ .
- c) True. Part of the Invertible Matrix Theorem.
- **d)** True. The first part says T(x) = Ax is onto. Since *A* is  $n \times n$ , this is the same as saying *A* is invertible, so *T* is one-to-one and onto. Therefore, the equation Ax = b has exactly one solution for each *b* in  $\mathbb{R}^n$ .
- e) False. A + B might not be invertible in the first place. For example, if  $A = I_2$  and  $B = -I_2$  then A + B = 0 which is not invertible. Even in the case when A + B is invertible, it still might not be true that  $(A + B)^{-1} = A^{-1} + B^{-1}$ . For example,  $(I_2 + I_2)^{-1} = (2I_2)^{-1} = \frac{1}{2}I_2$ , whereas  $(I_2)^{-1} + (I_2)^{-1} = I_2 + I_2 = 2I_2$ .
- **f)** True. According to the Invertible Matrix Theorem, the product *AB* is invertible. This implies *A* is invertible, with inverse  $B(AB)^{-1}$ :

$$A \cdot B(AB)^{-1} = (AB)(AB)^{-1} = I_n.$$

**5.** Consider the matrix

$$A = \begin{pmatrix} 4 & 3 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

- **a)** Compute  $A^{-1}$ .
- **b)** Express  $A^{-1}$  as a product of elementary matrices.
- c) Express *A* as a product of elementary matrices.

## Solution.

**a)** We row-reduce  $(A^{-1} | I_3)$ :

$$\begin{pmatrix} 4 & 3 & 0 & | & 1 & 0 & 0 \\ 1 & 2 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 0 & | & 0 & 1 & 0 \\ 4 & 3 & 0 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{array}{c} R_2 = R_2 - 4R_1 \\ R_2 = R_2 \leftrightarrow -5 \\ R_2 = R_2 \div -5 \\ R_2 = R_2 \div -5 \\ R_1 = R_1 - 2R_2 \\ R_1 = R_1 - \frac{2R_2}{1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

Therefore,

$$A^{-1} = \begin{pmatrix} \frac{2}{5} & -\frac{3}{5} & 0\\ -\frac{1}{5} & \frac{4}{5} & 0\\ 0 & 0 & 1 \end{pmatrix}.$$

**b)** The elementary matrices corresponding to the four row operations are, in order,

$$E_{1} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad E_{2} = \begin{pmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$E_{3} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{5} & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad E_{4} = \begin{pmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

We have  $E_4 E_3 E_2 E_1 A = I_3$ , so

$$A^{-1} = E_4 E_3 E_2 E_1 I_3 = \begin{pmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{5} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

**c)** First note

$$A = (A^{-1})^{-1} = (E_4 E_3 E_2 E_1)^{-1} = E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1}.$$

The inverse of an elementary matrix is the elementary matrix for the inverse row operation:

$$E_{1}^{-1} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad (R_{1} \leftrightarrow R_{2})$$
$$E_{2}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad (R_{2} = R_{2} + 4R_{1})$$
$$E_{3}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -5 & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad (R_{2} = R_{2} \times -5)$$
$$E_{4}^{-1} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \qquad (R_{1} = R_{1} + 2R_{2})$$

Therefore,

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -5 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$