Announcements

Monday, October 16

- The second midterm is on **this Friday, October 20**.
  - The exam covers §§*1.7, 1.8, 1.9, 2.1, 2.2, 2.3, 2.8, and 2.9.*
  - About half the problems will be conceptual, and the other half computational.
  - Note that this midterm covers **more material** than the first!
- There is a practice midterm posted on the website. It is identical in format to the real midterm (although there may be ±1–2 problems).
- Study tips:
  - There are lots of problems at the end of each section in the book, and at the end of the chapter, for practice.
  - Make sure to learn the theorems and learn the definitions, and understand what they mean. There is a reference sheet on the website.
  - Sit down to do the practice midterm in 50 minutes, with no notes.
  - Come to office hours!
- WeBWorK 2.8, 2.9 are due Wednesday at 11:59pm.
- **Double Rabinoffice hours this week**: Monday, 1–3pm; Tuesday, 9–11am; Thursday, 9–11am; Thursday, 12–2pm.
- **TA review session**: Wednesday, 7:15–9pm, Culc 144.
- Suggest topics for Wednesday's lecture on Piazza.

Section 2.9

Dimension and Rank

Coefficients of Basis Vectors

Recall: a **basis** of a subspace V is a set of vectors that *spans* V and is *linearly independent*.

Lemma ← like a theorem, but less substantial

If $\mathcal{B} = \{v_1, v_2, \dots, v_m\}$ is a basis for a subspace V, then any vector x in V can be written as a linear combination

$$x = c_1 v_1 + c_2 v_2 + \cdots + c_m v_m$$

for *unique* coefficients $c_1, c_2, \dots, c_m$.

Bases as Coordinate Systems

The unit coordinate vectors $e_1, e_2, \ldots, e_n$ form a basis for $\mathbf{R}^n$. Any vector is a unique linear combination of the e_i:

$$v = \begin{pmatrix} 3 \\ 5 \\ -2 \end{pmatrix} = 3\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + 5\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - 2\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = 3e_1 + 5e_2 - 2e_3.$$

Observe: the *coordinates* of v are exactly the *coefficients* of e_1, e_2, e_3.

We can go backwards: given any basis $\mathcal{B}$, we interpret the coefficients of a linear combination as "coordinates" with respect to $\mathcal{B}$.

Definition

Let $\mathcal{B} = \{v_1, v_2, \ldots, v_m\}$ be a basis of a subspace V. Any vector x in V can be written uniquely as a linear combination $x = c_1v_1 + c_2v_2 + \cdots + c_mv_m$. The coefficients $c_1, c_2, \ldots, c_m$ are the **coordinates of** x **with respect to** $\mathcal{B}$. The $\mathcal{B}$**-coordinate vector of** x is the vector

$$[x]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix} \quad \text{in } \mathbf{R}^m.$$

In other words, a basis gives a *coordinate system* on V.

Bases as Coordinate Systems

Example 1

Let $v_1 = \begin{pmatrix}1\\0\\1\end{pmatrix}$, $v_2 = \begin{pmatrix}1\\1\\1\end{pmatrix}$, $\quad \mathcal{B} = \{v_1, v_2\}, \quad V = \text{Span}\{v_1, v_2\}$.

Verify that $\mathcal{B}$ is a basis:

Question: If $[w]_{\mathcal{B}} = \binom{5}{2}$, then what is w? [interactive]

Question: Find the $\mathcal{B}$-coordinates of $w = \begin{pmatrix}5\\3\\5\end{pmatrix}$. [interactive]

Bases as Coordinate Systems

Example 2

Let $v_1 = \begin{pmatrix}2\\3\\2\end{pmatrix}$, $v_2 = \begin{pmatrix}-1\\1\\1\end{pmatrix}$, $v_3 = \begin{pmatrix}2\\8\\6\end{pmatrix}$, $\quad V = \mathrm{Span}\{v_1, v_2, v_3\}$.

Question: Find a basis for V. [interactive]

Question: Find the $\mathcal{B}$-coordinates of $x = \begin{pmatrix}4\\11\\8\end{pmatrix}$. [interactive]

If $\mathcal{B} = \{v_1, v_2, \ldots, v_m\}$ is a basis for a subspace V and x is in V, then

$$[x]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix} \quad \text{means} \quad x = c_1 v_1 + c_2 v_2 + \cdots + c_m v_m.$$

Finding the $\mathcal{B}$-coordinates for x means solving the vector equation

$$x = c_1 v_1 + c_2 v_2 + \cdots + c_m v_m$$

in the unknowns $c_1, c_2, \ldots, c_m$. This (usually) means row reducing the augmented matrix

$$\left(\begin{array}{cccc|c} | & | & & | & | \\ v_1 & v_2 & \cdots & v_m & x \\ | & | & & | & | \end{array}\right).$$

Question: What happens if you try to find the $\mathcal{B}$-coordinates of x *not* in V?

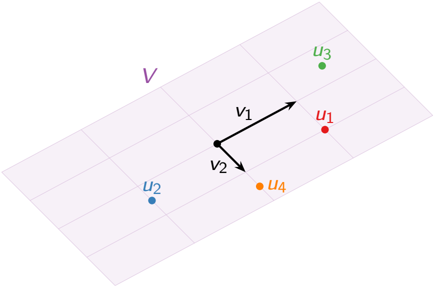
Let

$$v_1 = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \quad v_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

These form a basis $\mathcal{B}$ for the plane

$$V = \mathrm{Span}\{v_1, v_2\}$$

in $\mathbf{R}^3$.



Question: Estimate the $\mathcal{B}$-coordinates of these vectors: [interactive]

$[u_1]_{\mathcal{B}} =$ $[u_2]_{\mathcal{B}} =$ $[u_3]_{\mathcal{B}} =$ $[u_4]_{\mathcal{B}} =$

Choosing a basis $\mathcal{B}$ and using $\mathcal{B}$-coordinates lets us label the points of V with element of $\mathbf{R}^2$.

The Rank Theorem

Recall:

- The **dimension** of a subspace V is the number of vectors in a basis for V.
- A basis for the column space of a matrix A is given by the pivot columns.
- A basis for the null space of A is given by the vectors attached to the free variables in the parametric vector form.

Definition

The **rank** of a matrix A, written $\operatorname{rank} A$, is the dimension of the column space $\operatorname{Col} A$.

Observe:

$$\begin{aligned} \operatorname{rank} A = \dim \operatorname{Col} A &= \text{the number of columns with pivots} \\ \dim \operatorname{Nul} A &= \text{the number of free variables} \\ &= \text{the number of columns without pivots.} \end{aligned}$$

Rank Theorem

If A is an $m \times n$ matrix, then

$$\operatorname{rank} A + \dim \operatorname{Nul} A = n = \text{the number of columns of } A.$$

In other words, [interactive 1] [interactive 2]

(dimension of column span) + (dimension of solution set) = (number of variables).

The Rank Theorem

Example

$$A = \begin{pmatrix} 1 & 2 & 0 & -1 \\ -2 & -3 & 4 & 5 \\ 2 & 4 & 0 & -2 \end{pmatrix} \xrightarrow{\text{rref}} \begin{pmatrix} 1 & 0 & -8 & -7 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

basis of Col A (first two columns of A)

free variables (last two columns of the rref)

Poll

The Basis Theorem

Basis Theorem

Let V be a subspace of dimension m. Then:

- Any m linearly independent vectors in V form a basis for V.
- Any m vectors that span V form a basis for V.

Upshot

If you *already* know that $\dim V = m$, and you have m vectors $\mathcal{B} = \{v_1, v_2, \ldots, v_m\}$ in V, then you only have to check *one* of

1. $\mathcal{B}$ is linearly independent, *or*
2. $\mathcal{B}$ spans V

in order for $\mathcal{B}$ to be a basis.

Example: any three linearly independent vectors form a basis for $\mathbf{R}^3$.

The Invertible Matrix Theorem

Let A be an $n \times n$ matrix, and let $T\colon \mathbf{R}^n \to \mathbf{R}^n$ be the linear transformation $T(x) = Ax$. The following statements are equivalent.

1. A is invertible.
2. T is invertible.
3. A is row equivalent to I_n.
4. A has n pivots.
5. $Ax = 0$ has only the trivial solution.
6. The columns of A are linearly independent.
7. T is one-to-one.
8. $Ax = b$ is consistent for all b in $\mathbf{R}^n$.
9. The columns of A span $\mathbf{R}^n$.
10. T is onto.
11. A has a left inverse (there exists B such that $BA = I_n$).
12. A has a right inverse (there exists B such that $AB = I_n$).
13. A^T is invertible.
14. The columns of A form a basis for $\mathbf{R}^n$.
15. $\operatorname{Col} A = \mathbf{R}^n$.
16. $\dim \operatorname{Col} A = n$.
17. $\operatorname{rank} A = n$.
18. $\operatorname{Nul} A = \{0\}$.
19. $\dim \operatorname{Nul} A = 0$.

These are equivalent to the previous conditions by the Rank Theorem and the Basis Theorem.

Summary

- If $\mathcal{B}$ is a basis for a subspace, we can write a vector in the subspace as a linear combination of the basis vectors, with *unique* coefficients:

$$x = c_1 v_1 + c_2 v_2 + \cdots + c_m v_m.$$

- The coefficients are the $\mathcal{B}$-**coordinates** of x:

$$[x]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix}.$$

- Finding the $\mathcal{B}$-coordinates means solving the vector equation above.
- The **rank theorem** says the dimension of the column space of a matrix, plus the dimension of the null space, is the number of columns of the matrix.
- The **basis theorem** says that if you already know that $\dim V = m$, and you have m vectors in V, then you only have to check if they span *or* they're linearly independent to know they're a basis.
- There are more conditions of the Invertible Matrix Theorem.