- ► The third midterm is on this Friday, November 17.
  - ► The exam covers §§3.1, 3.2, 5.1, 5.2, 5.3, and 5.5.
  - About half the problems will be conceptual, and the other half computational.
- ▶ There is a practice midterm posted on the website. It is identical in format to the real midterm (although there may be  $\pm 1$ –2 problems).
- Study tips:
  - ► There are lots of problems at the end of each section in the book, and at the end of the chapter, for practice.
  - Make sure to learn the theorems and learn the definitions, and understand what they mean. There is a reference sheet on the website.
  - Sit down to do the practice midterm in 50 minutes, with no notes.
  - Come to office hours!
- ▶ WeBWorK 5.3, 5.5 are due Wednesday at 11:59pm.
- ▶ Double Rabinoffice hours this week: Monday, 1–3pm; Tuesday, 9–11am; Thursday, 9–11am; Thursday, 12–2pm.
- Suggest topics for Wednesday's lecture on Piazza.

#### **Theorem**

Let A be a  $2\times 2$  matrix with complex (non-real) eigenvalue  $\lambda$ , and let v be an eigenvector. Then

$$A = PCP^{-1}$$

where

$$P = \begin{pmatrix} | & | \\ \operatorname{Re} v & \operatorname{Im} v \\ | & | \end{pmatrix} \quad \text{and} \quad C = \begin{pmatrix} \operatorname{Re} \lambda & \operatorname{Im} \lambda \\ -\operatorname{Im} \lambda & \operatorname{Re} \lambda \end{pmatrix}.$$

The matrix C is a composition of rotation by  $-\arg(\lambda)$  and scaling by  $|\lambda|$ :

$$C = \begin{pmatrix} |\lambda| & 0 \\ 0 & |\lambda| \end{pmatrix} \begin{pmatrix} \cos(-\arg(\lambda)) & -\sin(-\arg(\lambda)) \\ \sin(-\arg(\lambda)) & \cos(-\arg(\lambda)) \end{pmatrix}.$$

A  $2\times 2$  matrix with complex eigenvalue  $\lambda$  is similar to (rotation by the argument of  $\overline{\lambda}$ ) composed with (scaling by  $|\lambda|$ ). This is multiplication by  $\overline{\lambda}$  in  $\mathbf{C}\sim\mathbf{R}^2$ .

# Geometric Interpretation of Complex Eigenvalues 2 × 2 example

What does 
$$A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$
 do geometrically?

▶ The characteristic polynomial is

$$f(\lambda) = \lambda^2 - \text{Tr}(A) \lambda + \text{det}(A) = \lambda^2 - 2\lambda + 2.$$

The roots are

$$\frac{2\pm\sqrt{4-8}}{2}=1\pm i.$$

▶ Let  $\lambda = 1 - i$ . We compute an eigenvector v:

$$A - \lambda I = \begin{pmatrix} i & -1 \\ \star & \star \end{pmatrix} \iff v = \begin{pmatrix} 1 \\ i \end{pmatrix}.$$

▶ Therefore,  $A = PCP^{-1}$  where

$$P = \left( \operatorname{Re} \begin{pmatrix} 1 \\ i \end{pmatrix} & \operatorname{Im} \begin{pmatrix} 1 \\ i \end{pmatrix} \right) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$C = \left( \begin{array}{cc} \operatorname{Re} \lambda & \operatorname{Im} \lambda \\ -\operatorname{Im} \lambda & \operatorname{Re} \lambda \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

## Geometric Interpretation of Complex Eigenvalues

 $2 \times 2$  example, continued

$$A = C = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \qquad \lambda = 1 - i$$

▶ The matrix C = A scales by a factor of

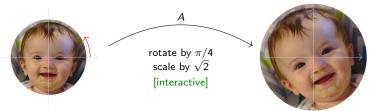
$$|\lambda| = \sqrt{1^2 + 1^2} = \sqrt{2}.$$

▶ The argument of  $\lambda$  is  $-\pi/4$ :



Therefore C = A rotates by  $+\pi/4$ .

• (We already knew this because  $A = \sqrt{2}$  times the matrix for rotation by  $\pi/4$  from before.)



## Geometric Interpretation of Complex Eigenvalues Another 2 × 2 example

What does 
$$A = \begin{pmatrix} \sqrt{3} + 1 & -2 \\ 1 & \sqrt{3} - 1 \end{pmatrix}$$
 do geometrically?

► The characteristic polynomial is

$$f(\lambda) = \lambda^2 - \text{Tr}(A) \lambda + \text{det}(A) = \lambda^2 - 2\sqrt{3} \lambda + 4.$$

The roots are

$$\frac{2\sqrt{3} \pm \sqrt{12 - 16}}{2} = \sqrt{3} \pm i.$$

Let  $\lambda = \sqrt{3} - i$ . We compute an eigenvector v:

$$A - \lambda I = \begin{pmatrix} 1+i & -2 \\ \star & \star \end{pmatrix} \land v = \begin{pmatrix} 1-i \\ 1 \end{pmatrix}.$$

▶ It follows that  $A = PCP^{-1}$  where

$$\begin{split} P &= \left( \, \operatorname{Re} \begin{pmatrix} 1-i \\ 1 \end{pmatrix} \quad \operatorname{Im} \begin{pmatrix} 1-i \\ 1 \end{pmatrix} \right) = \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \\ C &= \begin{pmatrix} \operatorname{Re} \lambda & \operatorname{Im} \lambda \\ -\operatorname{Im} \lambda & \operatorname{Re} \lambda \end{pmatrix} = \begin{pmatrix} \sqrt{3} & -1 \\ 1 & \sqrt{3} \end{pmatrix}. \end{split}$$

## Geometric Interpretation of Complex Eigenvalues

Another  $2 \times 2$  example, continued

$$A = \begin{pmatrix} \sqrt{3} + 1 & -2 \\ 1 & \sqrt{3} - 1 \end{pmatrix} \qquad C = \begin{pmatrix} \sqrt{3} & -1 \\ 1 & \sqrt{3} \end{pmatrix} \qquad \lambda = \sqrt{3} - i$$

▶ The matrix *C* scales by a factor of

$$|\lambda| = \sqrt{(\sqrt{3})^2 + (-1)^2} = \sqrt{4} = 2.$$

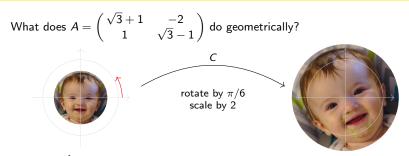
▶ The argument of  $\lambda$  is  $-\pi/6$ :

$$\frac{\pi}{\sqrt{3}}$$

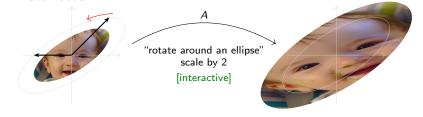
Therefore C rotates by  $+\pi/6$ .

## Geometric Interpretation of Complex Eigenvalues

Another  $2 \times 2$  example: picture



 $A = PCP^{-1}$  does the same thing, but with respect to the basis  $\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \end{pmatrix} \right\}$  of columns of P:



# Classification of $2 \times 2$ Matrices with a Complex Eigenvalue $_{\text{Triptych}}$

Let A be a real matrix with a complex eigenvalue  $\lambda$ . One way to understand the geometry of A is to consider the difference equation  $v_{n+1} = Av_n$ , i.e. the sequence of vectors  $v, Av, A^2v, \ldots$ 

$$A = \frac{1}{\sqrt{2}} \begin{pmatrix} \sqrt{3} + 1 & -2 \\ 1 & \sqrt{3} - 1 \end{pmatrix} \qquad A = \frac{1}{2} \begin{pmatrix} \sqrt{3} + 1 & -2 \\ 1 & \sqrt{3} - 1 \end{pmatrix} \qquad A = \frac{1}{2\sqrt{2}} \begin{pmatrix} \sqrt{3} + 1 & -2 \\ 1 & \sqrt{3} - 1 \end{pmatrix}$$

$$\lambda = \frac{\sqrt{3} - i}{\sqrt{2}} \qquad \qquad \lambda = \frac{\sqrt{3} - i}{2\sqrt{2}}$$

$$|\lambda| > 1 \qquad \qquad |\lambda| = 1 \qquad \qquad |\lambda| < 1$$
"spirals out" "rotates around an ellipse" "spirals in" [interactive]

## Complex Versus Two Real Eigenvalues

#### Theorem

Let A be a  $2 \times 2$  matrix with complex eigenvalue  $\lambda = a + bi$  (where  $b \neq 0$ ), and let v be an eigenvector. Then

$$A = PCP^{-1}$$

where

$$P = \begin{pmatrix} | & | \\ \operatorname{Re} v & \operatorname{Im} v \\ | & | \end{pmatrix}$$
 and  $C = (\operatorname{rotation}) \cdot (\operatorname{scaling}).$ 

This is very analogous to diagonalization. In the  $2 \times 2$  case:

#### **Theorem**

Let A be a  $2\times 2$  matrix with linearly independent eigenvectors  $v_1,v_2$  and associated eigenvalues  $\lambda_1,\lambda_2$ . Then

$$A = PDP^{-1}$$

where

$$P = \begin{pmatrix} | & | \\ v_1 & v_2 \\ | & | \end{pmatrix} \quad \text{and} \quad D = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

scale x-axis by  $\lambda_1$ 

## Picture with 2 Real Eigenvalues

We can draw analogous pictures for a matrix with 2 real eigenvalues.

Example: Let  $A = \frac{1}{4} \begin{pmatrix} 5 & 3 \\ 3 & 5 \end{pmatrix}$ .

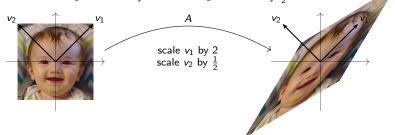
This has eigenvalues  $\lambda_1=2$  and  $\lambda_2=\frac{1}{2}$ , with eigenvectors

$$v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
 and  $v_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ .

Therefore,  $A = PDP^{-1}$  with

$$P = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$
 and  $D = \begin{pmatrix} 2 & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$ .

So A scales the  $v_1$ -direction by 2 and the  $v_2$ -direction by  $\frac{1}{2}$ .



## Picture with 2 Real Eigenvalues

We can also draw a picture from the perspective a difference equation: in other words, we draw  $v, Av, A^2v, \dots$ 

$$A = \frac{1}{4} \begin{pmatrix} 5 & 3 \\ 3 & 5 \end{pmatrix} \qquad \begin{array}{c} \lambda_1 = 2 \\ |\lambda_1| > 1 \end{array} \qquad |\lambda_1| < 1$$

$$A^3 \qquad \qquad A^3 \qquad \qquad \begin{bmatrix} \text{interactive} \end{bmatrix}$$

Exercise: Draw analogous pictures when  $|\lambda_1|, |\lambda_2|$  are any combination of <1,=1,>1.

### The Higher-Dimensional Case

#### **Theorem**

Let A be a real  $n \times n$  matrix. Suppose that for each (real or complex) eigenvalue, the dimension of the eigenspace equals the algebraic multiplicity. Then  $A = PCP^{-1}$ , where P and C are as follows:

- 1. C is **block diagonal**, where the blocks are  $1 \times 1$  blocks containing the real eigenvalues (with their multiplicities), or  $2 \times 2$  blocks containing the matrices  $\begin{pmatrix} \operatorname{Re} \lambda & \operatorname{Im} \lambda \\ -\operatorname{Im} \lambda & \operatorname{Re} \lambda \end{pmatrix}$  for each non-real eigenvalue  $\lambda$  (with multiplicity).
- 2. The columns of P form bases for the eigenspaces for the real eigenvectors, or come in pairs (Re  $v \, \text{Im} \, v$ ) for the non-real eigenvectors.

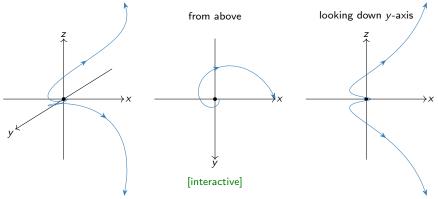
For instance, if A is a  $3\times 3$  matrix with one real eigenvalue  $\lambda_1$  with eigenvector  $v_1$ , and one conjugate pair of complex eigenvalues  $\lambda_2, \overline{\lambda}_2$  with eigenvectors  $v_2, \overline{v}_2$ , then

$$P = \begin{pmatrix} | & | & | \\ v_1 & \operatorname{Re} v_2 & \operatorname{Im} v_2 \\ | & | & | \end{pmatrix} \quad C = \begin{pmatrix} \boxed{\lambda_1} & 0 & 0 \\ 0 & \operatorname{Re} \lambda_2 & \operatorname{Im} \lambda_2 \\ 0 & -\operatorname{Im} \lambda_2 & \operatorname{Re} \lambda_2 \end{pmatrix}$$

# The Higher-Dimensional Case Example

Let 
$$A = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$
. This acts on the  $xy$ -plane by rotation by  $\pi/4$  and

scaling by  $\sqrt{2}$ . This acts on the z-axis by scaling by 2. Pictures:



Remember, in general  $A = PCP^{-1}$  is only *similar* to such a matrix C: so the x, y, z axes have to be replaced by the columns of P.

### Summary

 $\blacktriangleright$  There is a procedure analogous to diagonalization for matrices with complex eigenvalues. In the 2  $\times$  2 case, the result is

$$A = PCP^{-1}$$

where C is a rotation-scaling matrix.

- Multiplication by a  $2 \times 2$  matrix with a complex eigenvalue  $\lambda$  spirals out if  $|\lambda| > 1$ , rotates around an ellipse if  $|\lambda| = 1$ , and spirals in if  $|\lambda| < 1$ .
- ▶ There are analogous pictures for  $2 \times 2$  matrices with real eigenvalues.
- For larger matrices, you have to combine diagonalization and "complex diagonalization". You get a block diagonal matrix with scalars and rotation-scaling matrices on the diagonal.