

**MATH 1553**  
**PRACTICE MIDTERM 3 (VERSION B)**

<b>Name</b>		<b>GT Email</b>	
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Please **read all instructions** carefully before beginning.

- Please leave your GT ID card on your desk until your TA matches your exam.
- Each problem is worth 10 points. The maximum score on this exam is 50 points.
- You have 50 minutes to complete this exam.
- There are no aids of any kind (notes, text, etc.) allowed.
- Please show your work.
- You may cite any theorem proved in class or in the sections we covered in the text.
- Good luck!

This is a practice exam. It is similar in format, length, and difficulty to the real exam. It is not meant as a comprehensive list of study problems. I recommend completing the practice exam in 50 minutes, without notes or distractions.

The exam is not designed to test material from the previous midterm on its own. However, knowledge of the material prior to chapter 3 is necessary for everything we do for the rest of the semester, so it is fair game for the exam as it applies to chapters 3 and 5.

We'll be using an online system to help grade the exams this time, and the QR codes allow the scanner to match each page to you. Don't mess them up!

## Problem 1.

[2 points each]

In this problem, if the statement is always true, circle **T**; otherwise, circle **F**.

- a) **T**    **F**    If  $A$  is row equivalent to  $B$ , then  $A$  and  $B$  have the same eigenvalues.
- b) **T**    **F**    If  $A$  is similar to  $B$ , then  $A$  and  $B$  have the same characteristic polynomial.
- c) **T**    **F**    If  $A$  is similar to  $B$ , then  $A$  and  $B$  have the same eigenvectors.
- d) **T**    **F**    If  $A$  is diagonalizable, then  $A$  has  $n$  distinct eigenvalues.
- e) **T**    **F**    Row operations do not change the determinant of a matrix.

## Solution.

- a) **False:** for instance, the matrices  $\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$  and  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  are row equivalent, but have different eigenvalues.
- b) **True.**
- c) **False:** for instance, if  $A$  is diagonalizable, then  $A = PDP^{-1}$  for  $D$  diagonal. The unit coordinate vectors are eigenvectors of  $D$ , but the columns of  $P$  are eigenvectors of  $A$ .
- d) **False:** for instance,  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  is diagonal but has only one eigenvalue.
- e) **False:** row swaps and row scaling do change the determinant; only row replacements preserve it.

## Problem 2.

In this problem, you need not explain your answers; just circle the correct one(s).

Let  $A$  be an  $n \times n$  matrix.

a) [3 points] Which **one** of the following statements is correct?

1. An eigenvector of  $A$  is a vector  $v$  such that  $Av = \lambda v$  for a nonzero scalar  $\lambda$ .
2. An eigenvector of  $A$  is a nonzero vector  $v$  such that  $Av = \lambda v$  for a scalar  $\lambda$ .
3. An eigenvector of  $A$  is a nonzero scalar  $\lambda$  such that  $Av = \lambda v$  for some vector  $v$ .
4. An eigenvector of  $A$  is a nonzero vector  $v$  such that  $Av = \lambda v$  for a nonzero scalar  $\lambda$ .

b) [3 points] Which **one** of the following statements is **not** correct?

1. An eigenvalue of  $A$  is a scalar  $\lambda$  such that  $A - \lambda I$  is not invertible.
2. An eigenvalue of  $A$  is a scalar  $\lambda$  such that  $(A - \lambda I)v = 0$  has a solution.
3. An eigenvalue of  $A$  is a scalar  $\lambda$  such that  $Av = \lambda v$  for a nonzero vector  $v$ .
4. An eigenvalue of  $A$  is a scalar  $\lambda$  such that  $\det(A - \lambda I) = 0$ .

c) [4 points] Which of the following  $3 \times 3$  matrices are necessarily diagonalizable over the real numbers? (Circle all that apply.)

1. A matrix with three distinct real eigenvalues.
2. A matrix with one real eigenvalue.
3. A matrix with a real eigenvalue  $\lambda$  of algebraic multiplicity 2, such that the  $\lambda$ -eigenspace has dimension 2.
4. A matrix with a real eigenvalue  $\lambda$  such that the  $\lambda$ -eigenspace has dimension 2.

## Solution.

a) Statement 2 is correct: an eigenvector must be nonzero, but its eigenvalue may be zero.

b) Statement 2 is incorrect: the solution  $v$  must be nontrivial.

c) The matrices in 1 and 3 are diagonalizable. A matrix with three distinct real eigenvalues automatically admits three linearly independent eigenvectors. If a matrix  $A$  has a real eigenvalue  $\lambda_1$  of algebraic multiplicity 2, then it has another real eigenvalue  $\lambda_2$  of algebraic multiplicity 1. The two eigenspaces provide three linearly independent eigenvectors.

The matrices in 2 and 4 need not be diagonalizable.

### Problem 3.

Consider the matrix

$$A = \begin{pmatrix} -1 & -4 & 0 \\ 1 & 3 & 0 \\ 7 & 10 & 2 \end{pmatrix}.$$

- [4 points] Find the eigenvalues of  $A$ , and compute their algebraic multiplicities.
- [4 points] For each eigenvalue of  $A$ , find a basis for the corresponding eigenspace.
- [2 points] Is  $A$  diagonalizable? If so, find an invertible matrix  $P$  and a diagonal matrix  $D$  such that  $A = PDP^{-1}$ . If not, why not?

### Solution.

- a) We compute the characteristic polynomial by expanding along the third column:

$$\begin{aligned} f(\lambda) &= \det \begin{pmatrix} -1-\lambda & -4 & 0 \\ 1 & 3-\lambda & 0 \\ 7 & 10 & 2-\lambda \end{pmatrix} \\ &= (2-\lambda)((-1-\lambda)(3-\lambda) + 4) \\ &= (2-\lambda)(\lambda^2 - 2\lambda + 1) \\ &= (2-\lambda)(\lambda-1)^2 \end{aligned}$$

The roots are 1 (with multiplicity 2) and 2 (with multiplicity 1).

- b) First we compute the 1-eigenspace by solving  $(A-I)x = 0$ :

$$A-I = \begin{pmatrix} -2 & -4 & 0 \\ 1 & 2 & 0 \\ 7 & 10 & 1 \end{pmatrix} \xrightarrow{\text{rref}} \begin{pmatrix} 1 & 0 & 1/2 \\ 0 & 1 & -1/4 \\ 0 & 0 & 0 \end{pmatrix}$$

The parametric vector form of the general solution is  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = z \begin{pmatrix} -1/2 \\ 1/4 \\ 1 \end{pmatrix}$ , so a basis

for the 1-eigenspace is  $\left\{ \begin{pmatrix} -1/2 \\ 1/4 \\ 1 \end{pmatrix} \right\}$ .

Next we compute the 2-eigenspace by eyeballing it. Clearly  $Ae_3 = 2e_3$  because the third column of  $A$  is  $2e_3$ , so  $e_3$  is an eigenvector with eigenvalue 2. This eigenvalue has algebraic multiplicity 1, so the 2-eigenspace has dimension 1, and therefore a basis for the 2-eigenspace is  $\{e_3\}$ .

c) We have shown that every eigenvector of  $A$  is a multiple of  $e_3$  or  $\begin{pmatrix} -1/2 \\ 1/4 \\ 1 \end{pmatrix}$ . Hence  $A$  does not have 3 linearly independent eigenvectors, so it is not diagonalizable.

## Problem 4.

Consider the matrix

$$A = \begin{pmatrix} 3\sqrt{3}-1 & -5\sqrt{3} \\ 2\sqrt{3} & -3\sqrt{3}-1 \end{pmatrix}$$

- [2 points] Find both complex eigenvalues of  $A$ .
- [2 points] Find an eigenvector corresponding to each eigenvalue.
- [3 points] Find an invertible matrix  $P$  and a rotation-scale matrix  $C$  such that  $A = PCP^{-1}$ .
- [1 point] By what factor does  $C$  scale?
- [2 points] By what angle does  $C$  rotate?

## Solution.

- a) We compute the characteristic polynomial:

$$\begin{aligned} f(\lambda) &= \det \begin{pmatrix} 3\sqrt{3}-1-\lambda & -5\sqrt{3} \\ 2\sqrt{3} & -3\sqrt{3}-1-\lambda \end{pmatrix} \\ &= (-1-\lambda+3\sqrt{3})(-1-\lambda-3\sqrt{3}) + (2)(5)(3) \\ &= (-1-\lambda)^2 - 9(3) + 10(3) \\ &= \lambda^2 + 2\lambda + 4. \end{aligned}$$

By the quadratic formula,

$$\lambda = \frac{-2 \pm \sqrt{2^2 - 4(4)}}{2} = \frac{-2 \pm 2\sqrt{3}i}{2} = -1 \pm \sqrt{3}i.$$

- b) Let  $\lambda = -1 - \sqrt{3}i$ . Then

$$A - \lambda I = \begin{pmatrix} (i+3)\sqrt{3} & -5\sqrt{3} \\ 2\sqrt{3} & (i-3)\sqrt{3} \end{pmatrix}.$$

Since  $\det(A - \lambda I) = 0$ , the second row is a multiple of the first, so a row echelon form of  $A$  is

$$\begin{pmatrix} i+3 & -5 \\ 0 & 0 \end{pmatrix}.$$

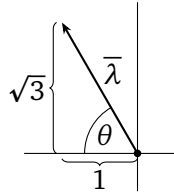
Hence an eigenvector with eigenvalue  $-1 - \sqrt{3}i$  is  $v = \begin{pmatrix} 5 \\ 3+i \end{pmatrix}$ . It follows that an eigenvector with eigenvalue  $-1 + \sqrt{3}i$  is  $\bar{v} = \begin{pmatrix} 5 \\ 3-i \end{pmatrix}$ .

c) Using the eigenvalue  $\lambda = -1 - \sqrt{3}i$  and eigenvector  $v = \begin{pmatrix} 5 \\ 3+i \end{pmatrix}$ , we can take

$$P = (\operatorname{Re} v \quad \operatorname{Im} v) = \begin{pmatrix} 5 & 0 \\ 3 & 1 \end{pmatrix} \quad C = \begin{pmatrix} \operatorname{Re} \lambda & \operatorname{Im} \lambda \\ -\operatorname{Im} \lambda & \operatorname{Re} \lambda \end{pmatrix} = \begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}.$$

d) The scaling factor is  $|\lambda| = \sqrt{(-1)^2 + (-\sqrt{3})^2} = 2$ .

e) We need to find the argument of  $\bar{\lambda} = -1 + \sqrt{3}i$ . We draw a picture:



$$\theta = \frac{\pi}{3} \text{ (trig identity)}$$

$$\text{argument} = \pi - \theta = \frac{2\pi}{3}$$

The matrix  $C$  rotates by  $2\pi/3$ .

## Problem 5.

Let

$$A = \begin{pmatrix} 7 & 1 & 4 & 1 \\ -1 & 0 & 0 & 6 \\ 9 & 0 & 2 & 3 \\ 0 & 0 & 0 & -1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 0 & 1 & 5 & 4 \\ 1 & -1 & -3 & 0 \\ -1 & 0 & 5 & 4 \\ 3 & -3 & -2 & 5 \end{pmatrix}$$

- [3 points] Compute  $\det(A)$ .
- [3 points] Compute  $\det(B)$ .
- [2 points] Compute  $\det(AB)$ .
- [2 points] Compute  $\det(A^2B^{-1}AB^2)$ .

## Solution.

- a) The second column has three zeros, so we expand by cofactors:

$$\det \begin{pmatrix} 7 & 1 & 4 & 1 \\ -1 & 0 & 0 & 6 \\ 9 & 0 & 2 & 3 \\ 0 & 0 & 0 & -1 \end{pmatrix} = -\det \begin{pmatrix} -1 & 0 & 6 \\ 9 & 2 & 3 \\ 0 & 0 & -1 \end{pmatrix}$$

Now we expand the second column by cofactors again:

$$\dots = -2 \det \begin{pmatrix} -1 & 6 \\ 0 & -1 \end{pmatrix} = (-2)(-1)(-1) = -2.$$

- b) This is a complicated matrix without a lot of zeros, so we compute the determinant by row reduction. After one row swap and several row replacements, we reduce to the matrix

$$\begin{pmatrix} 1 & -1 & -3 & 0 \\ 0 & 1 & 5 & 4 \\ 0 & 0 & 7 & 8 \\ 0 & 0 & 0 & -3 \end{pmatrix}.$$

The determinant of this matrix is  $-21$ , so the determinant of the original matrix is  $21$ .

- c)  $\det(AB) = \det(A) \det(B) = (-2)(21) = -42$ .
- d)  $\det(A^2B^{-1}AB^2) = \det(A)^2 \det(B)^{-1} \det(A) \det(B)^2 = \det(A)^3 \det(B) = (-2)^3(21) = -168$ .



[Scratch work]