

2.  $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 5 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 0 & 5 \end{pmatrix}$
4. (a) False.  
 (b) True.  
 (c) True.  
 (d) False.
11. (a) True.  
 (b) False.  
 (c) False.
15.  $A^k = X\Lambda^kX^{-1}$  approaches the zero matrix as  $k \rightarrow \infty$  if and only if every  $\lambda$  has absolute values less than  $\underline{1}$ .  $A_1$  has eigenvalues 1 and  $-0.3$ , so does not satisfy  $\lim_{k \rightarrow \infty} A_1^k = 0$ . On the other hand  $A_2$  has eigenvalues 0.9 and 0.3, so  $\lim_{k \rightarrow \infty} A_2^k = 0$ .
16.  $\Lambda = \begin{pmatrix} 1 & 0 \\ 0 & -0.3 \end{pmatrix}$ ,  $X = \begin{pmatrix} 9 & 1 \\ 4 & -1 \end{pmatrix}$ .  $\lim_{k \rightarrow \infty} \Lambda^k = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ .  $\lim_{k \rightarrow \infty} X\Lambda^kX^{-1} = \frac{1}{13} \begin{pmatrix} 9 & 9 \\ 4 & 4 \end{pmatrix}$ . In the columns of this matrix, you see the normalized eigenvector corresponding to  $\lambda = 1$ .
18.  $\begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$ . So  $A^k = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 3^k & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1+3^k & 1-3^k \\ 1-3^k & 1+3^k \end{pmatrix}$
29.  $AB = X\Lambda_1X^{-1}X\Lambda_2X^{-1} = X\Lambda_1\Lambda_2X^{-1} = X\Lambda_2\Lambda_1X^{-1} = X\Lambda_2X^{-1}X\Lambda_1X^{-1} = BA$ .
31.  $A - \lambda_1I = X\Lambda X^{-1} - \lambda_1I = X(\Lambda - \lambda_1I)X^{-1}$ . The matrix in the parentheses has a zero in the (1, 1) position. Likewise, for each  $\lambda_i$ , the corresponding matrix will have a zero in the  $(i, i)$  position. We get

$$(A - \lambda_1I)(A - \lambda_2I) \cdots (A - \lambda_nI) = X(\Lambda - \lambda_1I)(\Lambda - \lambda_2I) \cdots (\Lambda - \lambda_nI)X^{-1}.$$

The product of the matrices in parentheses is zero.

34.  $A = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ . Then  $\chi_A(t) = t^2 - (2 \cos \theta)t + 1$ . By using the quadratic equation and simplifying, we find that the eigenvalues are  $\cos \theta + i \sin \theta = e^{i\theta}$  and  $\cos \theta - i \sin \theta = e^{-i\theta}$ . The row reductions are a bit nasty, but if carried through correctly, give eigenvectors  $\begin{pmatrix} 1 \\ -i \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ i \end{pmatrix}$  respectively. So

$$A = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & -i \\ 1 & i \end{pmatrix}.$$

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This gives

$$\begin{aligned} A^n &= \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{ni\theta} & 0 \\ 0 & e^{-ni\theta} \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & i \\ 1 & -i \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} \cos n\theta + i \sin n\theta & 0 \\ 0 & \cos n\theta - i \sin n\theta \end{pmatrix} \begin{pmatrix} 1 & i \\ 1 & -i \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} \cos n\theta + i \sin n\theta & i \cos n\theta - \sin n\theta \\ \cos n\theta - i \sin n\theta & -i \cos n\theta - \sin n\theta \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} 2 \cos n\theta & -2 \sin n\theta \\ 2 \sin n\theta & 2 \cos n\theta \end{pmatrix} = \begin{pmatrix} \cos n\theta & -\sin n\theta \\ \sin n\theta & \cos n\theta \end{pmatrix} \end{aligned}$$

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3. (a) If all the columns add to 0, then the rows add up to  $\vec{0}$ . So we have a non-zero linear combination of rows that adds up to the zero vector, meaning they are linearly dependent. Hence the determinant of  $A$  is 0, so 0 is an eigenvalue.

(b) The eigenvalues of  $A$  are 0 and  $-5$ , with eigenvectors  $[3, 2]^T$  and  $[1, -1]^T$  resp. So  $\vec{u}(t) = c_1 \begin{pmatrix} 3 \\ 2 \end{pmatrix} + c_2 e^{-5t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ . If  $\vec{u}(0) = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$ , we get  $c_1 = c_2 = 1$ , so  $\vec{u}(\infty) = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$ .

8. The eigenvalues are 5 and 2, with eigenvectors  $[2, 1]^T$  and  $[1, 2]^T$  resp. The starting values give  $c_1 = c_2 = 10$ . So we get  $r(t) = 20e^{5t} + 10e^{2t}$  and  $w(t) = 10e^{5t} + 20e^{2t}$ . After a long time, we get a rabbit:wolf ratio of  $\lim_{t \rightarrow \infty} \frac{20e^{5t} + 10e^{2t}}{10e^{5t} + 20e^{2t}} = \lim_{t \rightarrow \infty} \frac{20 + 10e^{-3t}}{10 + 20e^{-3t}} = 2$ .

9. (a)  $c_1 = c_2 = 2$ .

(b)

$$\begin{aligned} \vec{u}(t) &= 2(\cos t + i \sin t) \begin{pmatrix} 1 \\ i \end{pmatrix} + 2(\cos t - i \sin t) \begin{pmatrix} 1 \\ -i \end{pmatrix} \\ &= \begin{pmatrix} 2 \cos t + 2i \sin t \\ 2i \cos t - 2 \sin t \end{pmatrix} + \begin{pmatrix} 2 \cos t - 2i \sin t \\ -2i \cos t - 2 \sin t \end{pmatrix} \\ &= 4 \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} \end{aligned}$$

14(b)  $Q = e^{At} = I + At + \frac{A^2}{2!} + \frac{A^3}{3!} + \dots$  So

$$\begin{aligned} e^{-At} &= I - At + \frac{(-A)^2}{2!} + \frac{(-A)^3}{3!} + \dots \\ &= I + A^T t + \frac{(A^T)^2}{2!} + \frac{(A^T)^3}{3!} + \dots \\ &= I + A^T t + \frac{(A^2)^T}{2!} + \frac{(A^3)^T}{3!} + \dots \\ &= \left( I + At + \frac{A^2}{2!} + \frac{A^3}{3!} + \dots \right)^T \\ &= Q^T \end{aligned}$$

So  $Q^T Q = e^{-At} e^{At} = I$ .

19.  $e^{Bt} = I + Bt = \begin{pmatrix} 1 & -4t \\ 0 & 1 \end{pmatrix}$ . So  $\frac{d}{dt} e^{Bt} = \begin{pmatrix} 0 & -4 \\ 0 & 0 \end{pmatrix}$ . Also  $Be^{Bt} = \begin{pmatrix} 0 & -4 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & -4t \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & -4 \\ 0 & 0 \end{pmatrix}$ .

21.  $A = \begin{pmatrix} 1 & 4 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & -4 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 4 \\ 0 & 1 \end{pmatrix}$ .  $e^{At} = \begin{pmatrix} 1 & -4 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} e & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 4 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} e & 4e - 4 \\ 0 & 1 \end{pmatrix}$ .

22. If  $A^2 = A$ , then  $A^n = A$  for all integer  $n$ . So

$$\begin{aligned} e^{At} &= I + At + \frac{A}{2!}t + \frac{A}{3!}t + \dots \\ &= I + A\left(t + \frac{t^2}{2!} + \frac{t^3}{3!} + \dots\right) \\ &= I + A(e^t - 1) \end{aligned}$$

If  $A = \begin{pmatrix} 1 & 4 \\ 0 & 0 \end{pmatrix}$ , this gives  $e^{At} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} e^t - 1 & 4e^t - 4 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} e & 4e - 4 \\ 0 & 1 \end{pmatrix}$ .

26. (a) The inverse of  $e^{At}$  is  $e^{-At}$ .

(b) If  $A\vec{x} = \lambda\vec{x}$  then  $e^{At}\vec{x} = e^{\lambda t}\vec{x}$ .

31. (a) If  $A\vec{x} = \lambda\vec{x}$ , then  $(\cos A)\vec{x} = \vec{x} - \frac{1}{2!}\lambda^2\vec{x} + \frac{1}{4!}\lambda^4\vec{x} + \dots = (\cos \lambda)\vec{x}$ . So  $\cos \lambda$  is an eigenvalue of  $\cos A$ .

(b) The eigenvalue corresponding to  $[1, 1]^T$  is  $2\pi$ . The eigenvalue corresponding to  $[1, -1]^T$  is 0. So  $\cos A$  has a double eigenvalue of 1 with the same eigenvectors. This gives that  $\cos A = I$ .

(c)  $\vec{u}(0) = \begin{pmatrix} 4 \\ 2 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ . Multiply those eigenvectors by  $\cos(2\pi t)$  and  $\cos(0t) = 1$ .

Add up the solution  $\vec{u}(t) = 3 \cos(2\pi t)\vec{x}_1 + \vec{x}_2 = \begin{pmatrix} 3 \cos(2\pi t) + 1 \\ 3 \cos(2\pi t) - 1 \end{pmatrix}$ .