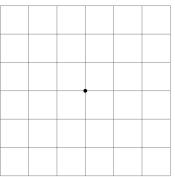
Final Exam Practice Problems

Computational exercises

1. Consider the matrix

$$A = \begin{pmatrix} 1 & -1 & 2 \\ -2 & 2 & -4 \end{pmatrix}.$$

- **a)** Use Gauss–Jordan elimination to put *A* into reduced row echelon form. Circle the free columns.
- **b)** Find bases for the four fundamental subspaces of *A*.
- **c)** The rank of *A* is
- **d)** Draw a picture of the column space C(A) below.



e) Write down a vector **b** in \mathbf{R}^2 such that $A\mathbf{x} = \mathbf{b}$ has no solution. If no such vector exists, explain why not.

f) The null space is a (circle one) $\begin{pmatrix} \text{point} \\ \text{line} \\ \text{plane} \end{pmatrix}$ in (fill in the blank) **R**.

- **g)** Find the general solution of $A\mathbf{x} = \begin{pmatrix} -2 \\ 4 \end{pmatrix}$ in parametric vector form.
- **2.** Consider

$$A = \begin{pmatrix} 1 & 3 & 1 & 2 \\ 2 & 6 & 4 & 8 \\ 0 & 0 & 2 & 4 \end{pmatrix} \qquad \mathbf{b} = \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}.$$

- **a)** Find the general solution of the system of equations $A\mathbf{x} = \mathbf{b}$. Express your answer in parametric vector form.
- b) Compute bases for the four fundamental subspaces of A.
- c) What is $\dim(N(A))$?

3. Consider

$$A = \begin{pmatrix} 1 & 3 & 8 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 1 & 2 & 4 \end{pmatrix} \qquad \mathbf{b} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

- a) Find the reduced row echelon form of the augmented matrix $(A \mid b)$.
- **b)** Find the parametric vector form for the solution set of $A\mathbf{x} = \mathbf{b}$.
- c) What best describes the geometric relationship between the solutions of Ax = 0 and the solutions of Ax = b? (Same A and b as above.)
 - (1) They are both lines through the origin.
 - (2) They are parallel lines.
 - (3) They are both planes through the origin.
 - (4) They are parallel planes.
- **4.** Consider the matrix

$$D = \begin{pmatrix} 1 & 2 & 3 & 2 & 14 & 9 \\ 0 & 0 & 0 & 2 & 10 & 6 \\ 0 & 0 & 0 & 0 & 0 & 3 \end{pmatrix}.$$

Note that this matrix is in row echelon form.

- a) Fill in the blanks:
 - (1) The column space C(D) is a subspace of \mathbf{R}^m , where m = |
 - (2) The null space N(D) is a subspace of \mathbf{R}^n , where n =
- **b)** Write down a vector **b** such that $D\mathbf{x} = \mathbf{b}$ has no solution. If no such vector exists, explain why not.
- c) Compute the reduced row echelon form of *D*.
- d) Find bases of the four fundamental subspaces of *D*.
- **5.** Consider the following consistent system of linear equations.

$$x_1 + 2x_2 + 3x_3 + 4x_4 = -2$$

$$3x_1 + 4x_2 + 5x_3 + 6x_4 = -2$$

$$5x_1 + 6x_2 + 7x_3 + 8x_4 = -2$$

- a) Find the parametric vector form for the general solution.
- b) Find the parametric vector form of the corresponding *homogeneous* equations.
- c) Find a linear dependence relation among the vectors

$$\left\{ \begin{pmatrix} 1\\3\\5 \end{pmatrix}, \begin{pmatrix} 2\\4\\6 \end{pmatrix}, \begin{pmatrix} 3\\5\\7 \end{pmatrix}, \begin{pmatrix} 4\\6\\8 \end{pmatrix} \right\}.$$

6. Consider the following matrix *A*:

$$\begin{pmatrix} 2 & 4 & 7 & -16 \\ 3 & 6 & -1 & -1 \end{pmatrix}$$

- **a)** Find a basis for N(A).
- b) For each of the following vectors v, decide if v is in N(A), and if so, express v as a linear combination of the basis vectors you found above.

$$\begin{pmatrix} 7\\3\\1\\2 \end{pmatrix} \qquad \begin{pmatrix} -5\\2\\-2\\-1 \end{pmatrix} \qquad \begin{pmatrix} -1\\1\\2\\1 \end{pmatrix}$$

7. Consider the system below, where *h* and *k* are real numbers.

$$\begin{aligned} x + 3y &= 2\\ 3x - hy &= k. \end{aligned}$$

- a) Find the values of *h* and *k* which make the system inconsistent.
- **b)** Find the values of *h* and *k* which give the system a unique solution.
- c) Find the values of *h* and *k* which give the system infinitely many solutions.
- **8.** Acme Widgets, Gizmos, and Doodads has two factories. Factory A makes 10 widgets, 3 gizmos, and 2 doodads every hour, and factory B makes 4 widgets, 1 gizmo, and 1 doodad every hour.
 - a) If factory A runs for *a* hours and factory B runs for *b* hours, how many widgets, gizmos, and doodads are produced? Express your answer as a vector equation.
 - **b)** A customer places an order for 16 widgets, 5 gizmos, and 3 doodads. Can Acme fill the order with no widgets, gizmos, or doodads left over? If so, how many hours do the factories run? If not, why not?
- 9. Consider the vectors

$$\mathbf{v}_1 = \begin{pmatrix} 1\\1\\-2 \end{pmatrix} \qquad \mathbf{v}_2 = \begin{pmatrix} 1\\2\\0 \end{pmatrix} \qquad \mathbf{v}_3 = \begin{pmatrix} 0\\1\\0 \end{pmatrix}.$$

- a) Is $\{v_1, v_2, v_3\}$ linearly independent? If not, find a linear dependence relation.
- **b)** Give a geometric description of $S{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3}$.
- **c)** Write (2, 6, -2) as a linear combination of $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$.
- **10.** Consider the vectors

$$\mathbf{v}_1 = \begin{pmatrix} 1\\1\\1\\1 \end{pmatrix} \qquad \mathbf{v}_2 = \begin{pmatrix} 1\\-1\\1\\-1 \end{pmatrix} \qquad \mathbf{v}_3 = \begin{pmatrix} 2\\0\\-2\\0 \end{pmatrix} \qquad \mathbf{v}_4 = \begin{pmatrix} 4\\0\\0\\0 \end{pmatrix}$$

and the subspace $W = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$.

- a) Find a linear dependence relation among v₁, v₂, v₃, v₄.
- **b)** What is the dimension of *W*?
- c) Which subsets of $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ form a basis for *W*?
- [*Hint:* it is helpful, but not necessary, to use the fact that $\{v_1, v_2, v_3\}$ is orthogonal.]
- **11.** Consider the vectors

$$\mathbf{v}_1 = \begin{pmatrix} 1\\3\\2 \end{pmatrix} \qquad \mathbf{v}_2 = \begin{pmatrix} -1\\4\\1 \end{pmatrix} \qquad \mathbf{v}_3 = \begin{pmatrix} 1\\h\\5 \end{pmatrix}.$$

- **a)** Find the value of *h* for which $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly *dependent*.
- **b)** For this value of *h*, produce a linear dependence relation among $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$.

12. Find all values of *h* such that
$$\begin{pmatrix} 1 \\ h \\ 5 \end{pmatrix}$$
 is *not* in the span of $\begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} -1 \\ 4 \\ 1 \end{pmatrix}$.

13. Write a vector *b* in \mathbf{R}^3 which is *not* a linear combination of $\begin{pmatrix} 1\\1\\0 \end{pmatrix}$ and $\begin{pmatrix} 0\\0\\-1 \end{pmatrix}$.

14. Consider the matrix

$$B = \begin{pmatrix} 1 & -1 & 0 \\ -1 & 7 & 1 \\ 2 & 4 & 1 \end{pmatrix}.$$

Is B invertible? If so, find its inverse. If not, explain why.

15. Consider the matrix

$$A = \begin{pmatrix} 5 & 4 & 1 \\ -1 & -2 & -1 \\ 0 & -1 & -1 \end{pmatrix}.$$

- **a)** Find the inverse of *A*.
- **b)** Express A^{-1} as a product of elementary matrices.

c) Solve
$$A\mathbf{x} = \mathbf{b}$$
, where $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ is an unknown vector.
(Your answer will be a formula in b_1, b_2, b_3 .)

16. Compute the matrix *A* satisfying

$$A\begin{pmatrix} 0\\1\\2 \end{pmatrix} = \begin{pmatrix} 1\\0\\0 \end{pmatrix} \qquad A\begin{pmatrix} 1\\0\\0 \end{pmatrix} = \begin{pmatrix} 0\\1\\0 \end{pmatrix} \qquad A\begin{pmatrix} 0\\1\\3 \end{pmatrix} = \begin{pmatrix} 0\\0\\1 \end{pmatrix}.$$

17. Let

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 5 & 6 & 7 & 8 \\ 6 & 8 & 10 & 12 \\ -9 & -10 & -11 & -12 \end{pmatrix}.$$

- a) What three row operations are needed to transform A into B?
- **b)** What are the elementary matrices E_1, E_2, E_3 for these three operations?
- **c)** Write an equation for *B* in terms of *A* and E_1, E_2, E_3 .
- **d)** Write an equation for A in terms of B and E_1, E_2, E_3 .
- **18.** Consider the matrix

$$A = \begin{pmatrix} 2 & 3 & 1 \\ -4 & -5 & -3 \\ -2 & -6 & 0 \end{pmatrix}.$$

a) Find a lower-triangular matrix *L* with ones on the diagonal and an upper-triangular matrix *U* such that A = LU.

b) Solve the equation
$$A\mathbf{x} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$$
 using the *LU* decomposition you found in (a).

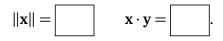
19. Consider the matrix

$$A = \begin{pmatrix} 1 & 2 & 5 & 0 \\ 1 & 2 & 4 & 2 \\ 0 & -1 & 0 & 8 \\ -1 & -3 & -1 & -1 \end{pmatrix}.$$

- a) Find a permutation matrix *P*, a lower-triangular matrix *L* with ones on the diagonal, and an upper-triangular matrix *U* such that PA = LU.
- **b)** Use part (a) to solve Ax = b, for b = (12, 1, -30, 6).
- **20.** Find the general solution of the equation $A\mathbf{x} = \mathbf{b}$ using the PA = LU factorization given below. Do not compute *A*.

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \quad L = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -2 & -1 & 1 \end{pmatrix} \quad U = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 2 \end{pmatrix} \quad \mathbf{b} = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}.$$

21. Let \mathbf{v}, \mathbf{w} be orthogonal vectors with $\|\mathbf{v}\| = 5$ and $\|\mathbf{w}\| = \sqrt{2}$. Let $\mathbf{x} = -\mathbf{v} + 3\mathbf{w}$ and $\mathbf{y} = 3\mathbf{v} - \mathbf{w}$. Compute:



- **22.** Let $W = S\{(2, 1, -6, 18)\}$. Compute an orthogonal basis of W^{\perp} .
- **23.** Let *W* be the set of all vectors of the form (x, y, x + y). Compute an orthonormal basis of W^{\perp} .

24. Find an orthonormal basis of Span
$$\left\{ \begin{pmatrix} 1\\-1\\0\\-2 \end{pmatrix}, \begin{pmatrix} 1\\1\\4\\3 \end{pmatrix}, \begin{pmatrix} 3\\-1\\4\\-1 \end{pmatrix}, \begin{pmatrix} 4\\-8\\-2\\0 \end{pmatrix} \right\}.$$

25. Consider the subspace $V = \left\{ \text{all solutions of } \begin{array}{c} x_1 + x_2 + 7x_3 + 5x_4 = 0 \\ -2x_1 - 2x_2 + 4x_3 + 8x_4 = 0 \end{array} \right\}.$

- **a)** Find an orthonormal basis of *V*.
- **b)** Find an orthonormal basis of V^{\perp} .
- **c)** Compute the matrix *P* for projection onto *V*.
- **d)** Compute the matrix P_{\perp} for projection onto V^{\perp} .
- e) Compute the projection **p** of $\mathbf{v} = (1, 0, 0, 1)$ onto V^{\perp} .
- **26.** Consider the subspace $V = \{ \text{all solutions of } 2x + 3y + 4z = 0 \}.$ **a)** Find a basis for *V*.
 - **b)** Find a basis for V^{\perp} .
- **27.** Let *W* be the span of (1, 1, 1, 1) in \mathbb{R}^4 . Find a matrix whose null space is W^{\perp} .

28. If
$$W = S\left\{ \begin{pmatrix} 1\\2\\1 \end{pmatrix}, \begin{pmatrix} 2\\1\\2 \end{pmatrix} \right\}$$
 then dim $(W^{\perp}) =$ _____.

29. Find two linearly independent vectors that are orthogonal to $\begin{pmatrix} 2\\0\\-1 \end{pmatrix}$.

- **30.** Find a nonzero vector orthogonal to $\begin{pmatrix} 1\\0\\1 \end{pmatrix}$ and $\begin{pmatrix} -2\\1\\4 \end{pmatrix}$.
- **31.** Let *A* be a 4×5 matrix whose null space is spanned by $\mathbf{a} = (1, 2, 1, 3, 1)$.

- a) Find the projection matrix onto the null space of A.
- **b)** Find the projection matrix onto the row space of *A*.
- **32.** Let *W* be the span of the vectors

$$\mathbf{u}_1 = \begin{pmatrix} 1\\1\\0 \end{pmatrix} \qquad \mathbf{u}_2 = \begin{pmatrix} 1\\0\\2 \end{pmatrix}.$$

- **a)** Find the orthogonal projection of $\mathbf{y} = (2, -1, 3)$ onto *W*.
- **b)** How far is **y** from *W*?
- **33.** Let *L* be the line y = x in \mathbb{R}^2 .
 - **a)** Compute the matrices *P* and P_{\perp} for orthogonal projection onto *L* and L^{\perp} , respectively.
 - **b)** Find a basis for C(P) without using elimination.
 - **c)** Find a basis for $C(PP_{\perp})$ without using elimination.
- 34. Consider

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{pmatrix} \qquad \mathbf{z} = \begin{pmatrix} 1 \\ 3 \\ 8 \\ 2 \end{pmatrix}.$$

Compute the distance from \mathbf{z} to C(A).

35. Find the least-squares solution of

$$\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & -1 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 1 \\ 3 \\ 4 \\ 0 \end{pmatrix}.$$

36. Consider the QR decomposition

$$A = QR = \frac{1}{2} \begin{pmatrix} 1 & -\sqrt{2} \\ -1 & 0 \\ -1 & 0 \\ 1 & \sqrt{2} \end{pmatrix} \begin{pmatrix} 6 & 2 \\ 0 & 2\sqrt{2} \end{pmatrix}.$$

Determine the least-squares solution of $A\mathbf{x} = (0, 2, 0, 0)$.

37. Consider the matrix

$$A = \begin{pmatrix} 3 & -3 \\ 3 & 1 \\ 3 & 5 \\ 3 & 1 \end{pmatrix}.$$

- a) Use Gram–Schmidt to find the QR decomposition of A.
- **b)** Find the least squares solution $\hat{\mathbf{x}}$ of $A\mathbf{x} = (2, 4, 6, 8)$, using your QR decomposition above or otherwise.
- **c)** Find the projection **p** of **v** onto C(A).
- **38.** Consider the matrix

$$A = \begin{pmatrix} 1 & -2 & 2 \\ 1 & -1 & 2 \\ 1 & 1 & 3 \\ 1 & 2 & 4 \end{pmatrix}$$

- **a)** Find the QR decomposition of *A*.
- **b)** Find the least squares solution $\hat{\mathbf{x}}$ of $A\mathbf{x} = (1, 2, 3, 5)$, using your QR decomposition above.
- **39.** Consider the matrix

$$A = \begin{pmatrix} 2 & 5 & 0 \\ 0 & 1 & 4 \\ 1 & 0 & 5 \end{pmatrix}.$$

- **a)** Find an orthonormal basis for C(A).
- **b)** Find a *QR* factorization of *A*.
- **c)** Find a different orthonormal basis for *C*(*A*). (Reordering and scaling your basis in (a) does not count.)
- **40.** Consider the matrix

$$A = \begin{pmatrix} 1 & 1 \\ 2 & -1 \\ -2 & 4 \end{pmatrix}.$$

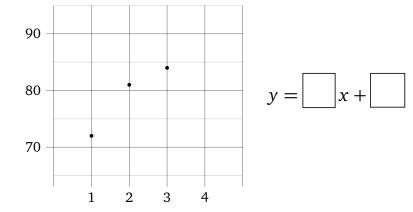
a) Find the QR factorization of *A*.

b) Find the least-squares solution of the system $A\mathbf{x} = \begin{pmatrix} 1 \\ 2 \\ 7 \end{pmatrix}$ using the QR factorization you found in (a).

- **c)** Compute the matrix *P* for the projection onto *C*(*A*) using the QR factorization you found in (a).
- **41.** Your roomate Karxon is currently taking Math 105L. Karxon scored 72% on the first exam, 81% on the second exam, and 84% on the third exam. Not having taken linear algebra yet, Karxon does not know what kind of score to expect on the final exam. Luckily, you can help out.
 - a) The general equation of a line in \mathbb{R}^2 is y = Cx + D. Write down the system of linear equations in *C* and *D* that would be satisfied by a line passing through

the points (1, 72), (2, 81), and (3, 84), and then write down the corresponding matrix equation.

b) Solve the corresponding least squares problem for *C* and *D*, and use this to *write down* and *draw* the the best fit line below. [Use a calculator]



c) What score does this line predict for the fourth (final) exam?

- **42.** In this problem, you will find the best-fit line through the points (0, 6), (1, 0), and (2, 0).
 - a) The general equation of a line in \mathbf{R}^2 is y = C + Dx. Write down the system of linear equations in *C* and *D* that would be satisfied by a line passing through all three points, then write down the corresponding matrix equation.
 - **b)** Solve the least squares problem in (a) for *C* and *D*. Give the equation for the best fit line, and graph it along with the three points.
- **43.** Compute determinants of the following matrices:

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \end{pmatrix} \begin{pmatrix} 5 & 0 & 0 \\ -3 & 0 & 0 \\ 8 & 5 & -1 \end{pmatrix} \begin{pmatrix} 2 & 1 & 1 & 1 & 0 \\ 0 & 2 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 5 \\ 0 & 0 & 0 & 7 & 1 \end{pmatrix} \begin{pmatrix} 1 & -2 & 3 \\ 2 & 0 & -6 \\ 1 & 0 & -3 \end{pmatrix}$$

44. Let *A* be the 3×3 matrix satisfying

$$A\begin{pmatrix}1\\0\\0\end{pmatrix} = \begin{pmatrix}0\\1\\0\end{pmatrix} \qquad A\begin{pmatrix}0\\1\\0\end{pmatrix} = \begin{pmatrix}0\\0\\1\end{pmatrix} \qquad A\begin{pmatrix}0\\0\\1\end{pmatrix} = \begin{pmatrix}1\\0\\0\end{pmatrix}.$$

Compute det(*A*).

45. Compute the determinant of the matrix

$$\begin{pmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 2 & 7 & 6 & -3 \\ -3 & -10 & -7 & 2 \end{pmatrix}^2$$

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46. Given that

$$\det \begin{pmatrix} a & b & c \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} = 5,$$

compute the determinants of the following matrices:

$$\begin{pmatrix} 4 & 5 & 6 \\ a & b & c \\ 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 4 & 6 & 5 \\ a & c & b \\ 1 & 3 & 2 \end{pmatrix} \begin{pmatrix} 2a & 2b & 2c \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \begin{pmatrix} a & b & c \\ 5 & 7 & 9 \\ 1 & 2 & 3 \end{pmatrix}.$$

47. Find the volume of the parallelepiped defined by the columns of this matrix:

$$\begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ -1 & 0 & -1 \end{pmatrix}.$$

48. For which value(s) of k, if any, do these vectors not form a basis of \mathbf{R}^4 ?

$$\begin{pmatrix} 1\\0\\0\\-6 \end{pmatrix}, \quad \begin{pmatrix} 0\\1\\0\\-1 \end{pmatrix}, \quad \begin{pmatrix} 0\\0\\1\\-8 \end{pmatrix}, \quad \begin{pmatrix} 1\\2\\3\\k \end{pmatrix}$$

49. Find all values of *k* so that the following set of vectors is linearly dependent.

$$\left\{ \begin{pmatrix} -1\\3\\-1 \end{pmatrix}, \begin{pmatrix} 1\\1\\-1 \end{pmatrix}, \begin{pmatrix} 1\\k\\-7 \end{pmatrix} \right\}$$

50. Let *A*, *B*, *C* be 4×4 matrices with det(*A*) = 2, det(*B*) = -3, det(*C*) = 5. Find the determinants of these matrices:

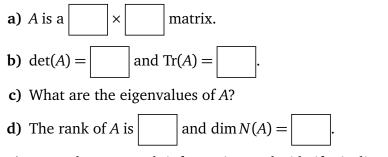
$$AB \qquad AC^{-1}B \qquad B^T C^2 \qquad A^3 B^{-1} C^T \qquad 4C.$$

51. For which value(s) of *a* is $\lambda = 1$ an eigenvector of this matrix?

$$A = \begin{pmatrix} 3 & -1 & 0 & a \\ a & 2 & 0 & 4 \\ 2 & 0 & 1 & -2 \\ 13 & a & -2 & -7 \end{pmatrix}$$

52. Let *A* be a matrix with characteristic polynomial

$$p(\lambda) = (3 - \lambda)(1 - \lambda)^2(4 + \lambda)^3.$$



e) Do we have enough information to decide if A is diagonalizable?

53. Consider these 3×3 matrices:

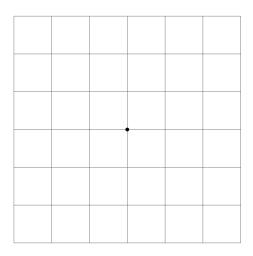
$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -1 & -1 & 1 \\ 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -1 & -1 & -1 \\ 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 4 & 2 & -4 \\ 0 & 2 & 0 \\ 2 & 2 & -2 \end{pmatrix}.$$

For each matrix,

- a) Compute all eigenvalues with algebraic multiplicity.
- b) Compute the geometric multiplicity of each eigenvalue.
- c) If the matrix is diagonalizable, express it in the form $X\Lambda X^{-1}$ for Λ diagonal. Otherwise, explain why the matrix is not diagonalizable.
- **54.** Consider the matrix

$$A = \begin{pmatrix} 2 & -1 \\ \frac{3}{2} & -\frac{1}{2} \end{pmatrix}.$$

- **a)** Find an invertible matrix *X* and a diagonal matrix Λ such that $A = X \Lambda X^{-1}$.
- **b)** Compute $A^n \mathbf{v}_0$ for $\mathbf{v}_0 = \binom{1}{2}$. What happens when $n \to \infty$?
- c) In the diagram, *draw and label* the eigenspaces of *A*, and draw the vectors v₀, Av₀, A²v₀, A³v₀, ... as points. (The grid lines are one unit apart, and the dot is the origin.) [Hint: you do not have to compute Aⁿv₀ numerically to do this.]



d) Solve the system of ordinary differential equations

$$\frac{d}{dt}u_1 = 2u_1 - u_2 \qquad u_1(0) = 1 \qquad u_1(t) = 1 \\ \frac{d}{dt}u_2 = \frac{3}{2}u_1 - \frac{1}{2}u_2 \qquad u_2(0) = 2 \qquad u_2(t) = 1$$

55. Consider the sequence of numbers 0, 1, 5, 31, 185, ... given by the recursive formula

$$a_0 = 0$$

 $a_1 = 1$
 $a_n = 5a_{n-1} + 6a_{n-2}$ $(n \ge 2).$

a) Find a matrix *A* such that

$$A\binom{a_{n-2}}{a_{n-1}} = \binom{a_{n-1}}{a_n}$$

for all $n \ge 2$.

- **b)** Find an invertible matrix *X* and a diagonal matrix Λ such that $A = X \Lambda X^{-1}$.
- c) Give a formula for A^n . Your answer should be a single matrix whose entries depend only on n.
- **d)** Give a non-recursive formula for a_n .

56. Solve the system of ordinary differential equations

$$u'_1 = 3u_1 + 24u_2$$
 $u_1(0) = 7$
 $u'_2 = -2u_1 - 11u_2$ $u_2(0) = -2.$

What happens to $u_1(t)$ and $u_2(t)$ as $t \to \infty$?

57. Solve the system of ordinary differential equations

$$u'_1 = u_2 \qquad u_1(0) = 1$$

 $u'_2 = -u_1 \qquad u_2(0) = 1.$

Your answer should not contain any complex numbers.

58. Consider the matrix

$$A = \begin{pmatrix} -2\sqrt{3} - 1 & 5\\ -1 & -2\sqrt{3} + 1 \end{pmatrix}$$

- a) Find both complex eigenvalues of *A*.
- b) Find an eigenvector corresponding to each eigenvalue.
- c) Express *A* as a product $X\Lambda X^{-1}$, where *X* is invertible and Λ is diagonal. These matrices will have complex entries.
- d) Solve the system of ordinary differential quations

$$\mathbf{u}' = A\mathbf{u} \qquad \mathbf{u}(0) = \begin{pmatrix} 0 \\ 4 \end{pmatrix}.$$

Your answer should not contain any complex numbers.

- e) What happens to $u_1(t)$ and $u_2(t)$ as $t \to \infty$?
- **59.** Consider the symmetric matrix

$$A = \begin{pmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{pmatrix}$$

Find an orthogonal matrix *Q* and a diagonal matrix Λ such that $A = Q\Lambda Q^T$.

60. Consider the matrix

$$A = \begin{pmatrix} 23 & 36 \\ 36 & 2 \end{pmatrix}.$$

- **a)** Find the eigenvalues of this matrix.
- **b)** Find an orthogonal matrix Q and a diagonal matrix Λ such that $A = Q\Lambda Q^T$.
- c) Consider the following system of differential equations with initial values:

$$\frac{dx}{dt} = 23x + 36y \qquad x(0) = 7$$

$$\frac{dy}{dt} = 36x + 2y \qquad y(0) = -1.$$

Find the solutions x(t) and y(t).

- **d)** Find a formula for A^n in terms of n.
- **61.** Consider the matrix

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

- **a)** Compute the eigenvalues of *A*. What are their algebraic and geometric multiplicities?
- **b)** Find an invertible matrix *X* and a diagonal matrix Λ such that $A = X \Lambda X^{-1}$.
- **c)** Compute A^{114} and A^{115} .

62. Consider the symmetric matrix

$$S = \begin{pmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{pmatrix}.$$

- **a)** Find an orthogonal matrix Q and a diagonal matrix Λ such that $S = Q\Lambda Q^T$.
- **b)** Circle one: S is

positive-definite positive-semidefinite neither of these

- c) Write down the singular value decomposition of *S*.
- **d)** Find a different orthogonal matrix $Q' \neq Q$ and a different diagonal matrix $\Lambda' \neq \Lambda$ such that $S = Q' \Lambda' Q'^T$.
- **63.** Consider the quadratic form

$$q(x, y, z) = 9x^{2} + 10y^{2} + 8z^{2} + 4xy - 4xz.$$

- a) Construct a symmetric matrix *S* such that $q(\mathbf{x}) = \mathbf{x}^T S \mathbf{x}$.
- b) Find x maximizing ||x|| subject to the constraint q(x) = 1.
 [Hint: one of the eigenvalues of S is 12.]
- **64.** Compute the singular value decompositions of these matrices:

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & -3 & 0 \\ -7 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 0 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} -1 & 1 & 0 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 2 & 1 \end{pmatrix}$$

65. Consider the following matrix and its singular value decomposition $A = U\Sigma V^{T}$:

$$A = \begin{pmatrix} 1/\sqrt{10} & 1/\sqrt{15} & 1/\sqrt{2} & -1/\sqrt{3} \\ -2/\sqrt{10} & 3/\sqrt{15} & 0 & 0 \\ 2/\sqrt{10} & 2/\sqrt{15} & 0 & 1/\sqrt{3} \\ -1/\sqrt{10} & -1/\sqrt{15} & 1/\sqrt{2} & 1/\sqrt{3} \end{pmatrix} \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \\ -1/\sqrt{6} & -2/\sqrt{6} & -1/\sqrt{6} \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} \end{pmatrix}.$$

From this you can read off all of the following properties of A.

- a) A is a matrix of rank r =
- **b)** Find orthonormal bases of the four fundamental subspaces of *A*.
- c) Express *A* as a linear combination of rank-one matrices $\mathbf{u}\mathbf{v}^{T}$ (your answer should consist of vectors with numbers, not letters).
- **d**) Find a *unit* vector \mathbf{x} maximizing $||A\mathbf{x}||$.
- e) Compute the matrix *P* for orthogonal projection onto *C*(*A*) (write it as a product, without expanding it out).

66. A certain matrix *A* has singular value decomposition $A = U\Sigma V^T$, where

$$U = \begin{pmatrix} | & | & | & | \\ \mathbf{u}_1 & \mathbf{u}_2 & \mathbf{u}_3 & \mathbf{u}_4 \\ | & | & | & | \end{pmatrix} \qquad \Sigma = \begin{pmatrix} 4 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \qquad V = \begin{pmatrix} | & | & | & | & | & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 & \mathbf{v}_4 & \mathbf{v}_5 \\ | & | & | & | & | \end{pmatrix}.$$

- **a)** What is the rank of *A*?
- **b)** What is the maximum value of $||A\mathbf{x}||$ subject to $||\mathbf{x}|| = 1$?
- c) Find orthonormal bases of the four fundamental subspaces of *A*.
- **d)** What is the singular value decomposition of A^T ?
- **67.** Consider the matrix

$$A = \begin{pmatrix} 1 & 1 \\ 3 & 3 \end{pmatrix}.$$

This question is about the singular value decomposition $A = U\Sigma V^T$. Let $U = \begin{pmatrix} \mathbf{u}_1 & \mathbf{u}_2 \end{pmatrix}$ and $V = \begin{pmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{pmatrix}$.

- **a)** Find \mathbf{v}_1 without computing $A^T A$ or $A A^T$. [Hint: in which space does \mathbf{v}_1 live?]
- **b)** Using your answer to (a), compute σ_1 and \mathbf{u}_1 .
- **c)** Write down the singular value decomposition $A = U\Sigma V^T$ of *A*.
- **d)** Compute the pseudo-inverse A^+ .
- e) Find the shortest least-squares solution of $A\mathbf{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

Conceptual exercises

68. Which of these matrices are in reduced row echelon form?

$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 & -3 & | 1 \\ 0 & 0 & 1 & -1 & | 5 \\ 0 & 0 & 0 & 0 & | 0 \end{pmatrix}$$

69. Decide if the following sets of vectors span a point, line, plane, or all of \mathbb{R}^3 . [Hint: you should be able to eyeball these.]

$$\left\{ \begin{pmatrix} 1\\-2\\5 \end{pmatrix}, \begin{pmatrix} 4\\-8\\20 \end{pmatrix} \right\} \qquad \left\{ \begin{pmatrix} 1\\-2\\5 \end{pmatrix}, \begin{pmatrix} 4\\2\\0 \end{pmatrix}, \begin{pmatrix} 1\\1/2\\0 \end{pmatrix}, \begin{pmatrix} 0\\0\\0 \end{pmatrix} \right\}$$

- **70.** Let *A* be a 2 × 2 matrix such that N(A) is the line y = x. Let **b** be a *nonzero* vector in \mathbb{R}^2 . Which of the following are definitely *not* the solution set of $A\mathbf{x} = \mathbf{b}$? (Circle all that apply.)
 - (1) The line y = x.
 - (2) The y-axis.
 - (3) The line y = x + 1
 - (4) The set {0}.
 - (5) The empty set.
- **71.** Which of the following properties of a matrix *A* are preserved under row operations? (In other words, which remain unchanged after doing any row operation?)
 - (1) The rank
 - (2) The solutions of $A\mathbf{x} = \mathbf{b}$
 - (3) The dimension of the null space
 - (4) The column space
 - (5) The null space
 - (6) The row space
 - (7) The left null space
 - (8) The eigenvalues
 - (9) The eigenvectors
 - (10) The singular values
 - (11) The determinant
 - (12) The reduced row echelon form
- **72.** Let *A* be an $m \times n$ matrix. Which of the following are equivalent to the statement "the columns of *A* are linearly independent?"
 - (1) *A* has full column rank
 - (2) $A\mathbf{x} = \mathbf{b}$ has a unique solution for every \mathbf{b} in \mathbf{R}^m
 - (3) $A\mathbf{x} = \mathbf{b}$ has a unique least-squares solution for every \mathbf{b} in \mathbf{R}^m
 - (4) $A\mathbf{x} = \mathbf{0}$ has a unique solution
 - (5) A has n pivots
 - (6) $N(A) = \{\mathbf{0}\}$

(7) $m \ge n$

- (8) $A^T A$ is invertible
- (9) AA^T is invertible
- (10) A^+A is the identity matrix
- (11) The row space of *A* is \mathbf{R}^n
- **73.** Let *A* be an $m \times n$ matrix. Which of the following are equivalent to the statement "*A* has full row rank?"
 - (1) The rows of *A* are linearly independent
 - (2) The left null space of A is $\{0\}$
 - (3) $A\mathbf{x} = \mathbf{b}$ has a unique solution for every \mathbf{b} in \mathbf{R}^m
 - (4) $A\mathbf{x} = \mathbf{b}$ has a solution for every \mathbf{b} in \mathbf{R}^m
 - (5) A has m pivots
 - $(6) C(A) = \mathbf{R}^m$
 - (7) $n \ge m$
 - (8) $A^T A$ is invertible
 - (9) AA^T is invertible
 - (10) AA^+ is the identity matrix
 - (11) The row space of *A* is \mathbf{R}^n
- **74.** Consider the subspace

$$V = S\left\{ \begin{pmatrix} 1\\1 \end{pmatrix}, \begin{pmatrix} 1\\-1 \end{pmatrix} \right\}.$$

Find two other vectors that span *V*. (You may not include scalar multiples of the vectors $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ or $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$.)

- **75.** Write three different nonzero vectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ in \mathbf{R}^3 such that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly *de*pendent, but \mathbf{v}_3 is *not* in $S\{\mathbf{v}_1, \mathbf{v}_2\}$. Clearly indicate which is \mathbf{v}_3 .
- **76.** If *A* is a 20 × 60 matrix, then rank(*A*) + dim N(A) =
- **77.** If *A* is a 5×6 matrix of rank 2, then *N*(*A*) is a _____-dimensional subspace of **R**______
- **78.** Which of the following are subspaces of \mathbf{R}^4 and **why**?

a) Span
$$\left\{ \begin{pmatrix} 1\\0\\3\\2 \end{pmatrix}, \begin{pmatrix} -2\\7\\9\\13 \end{pmatrix}, \begin{pmatrix} 144\\0\\0\\1 \end{pmatrix} \right\}$$

b) $N \begin{pmatrix} 2 & -1 & 3\\0 & 0 & 4\\6 & -4 & 2\\-9 & 3 & 4 \end{pmatrix}$

c)
$$C \begin{pmatrix} 2 & -1 & 3 \\ 0 & 0 & 4 \\ 6 & -4 & 2 \\ -9 & 3 & 4 \end{pmatrix}$$

d) $V = \begin{cases} \text{all vectors } \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \text{ in } \mathbf{R}^4 \text{ such that } xy = zw \end{cases}$

79. Consider the subspace *V* of \mathbf{R}^4 consisting of all vectors (x, y, z, w) such that w = 0.

a) Explain why
$$\begin{cases} \begin{pmatrix} 1\\0\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\0\\1\\0 \end{pmatrix} \end{cases}$$
 is a basis for V.
b) Explain why
$$\begin{cases} \begin{pmatrix} 1\\2\\3\\0 \end{pmatrix}, \begin{pmatrix} 3\\2\\1\\0 \end{pmatrix}, \begin{pmatrix} 1\\-1\\1\\0 \end{pmatrix} \end{cases}$$
 is a basis for V.

- **80.** Which of the following are subspaces of \mathbf{R}^n ?
 - (1) The null space of an $m \times n$ matrix
 - (2) An eigenspace of an $n \times n$ matrix (for a particular eigenvalue)
 - (3) The column space of an $m \times n$ matrix
 - (4) The span of n-1 vectors in \mathbb{R}^n
 - (5) The row space of an $m \times n$ matrix
 - (6) W^{\perp} where W is a subspace of \mathbf{R}^n
- **81.** Let *A* be an invertible $n \times n$ matrix. Which of the following can you conclude?
 - (1) The columns of *A* span \mathbf{R}^n
 - (2) det(A) \neq 0
 - (3) A is diagonalizable
 - (4) The rank of *A* equals *n*
 - (5) $N(A) = \{0\}$
 - (6) $A\mathbf{x} = \mathbf{b}$ has a unique solution for every \mathbf{b} in \mathbf{R}^n
 - (7) The eigenvalues of *A* are positive
 - (8) There exists a matrix *B* such that $AB = I_n$
- **82.** Let *A* be an $n \times n$ matrix that is *not* invertible. Which of the following can you conclude?
 - (1) A has two identical columns
 - (2) det(A) = 0
 - (3) *A* has a row of zeros
 - (4) The rank of A equals zero
 - (5) There are two different vectors \mathbf{x}, \mathbf{y} in \mathbf{R}^n such that $A\mathbf{x} = A\mathbf{y}$

- (6) Zero is an eigenvalue of *A*
- (7) *A* is not diagonalizable
- (8) The rank of *A* is less than n
- (9) A has linearly dependent rows
- **83.** Give an example of a 3×2 matrix *A* and a vector **b** in \mathbf{R}^3 such that $A\mathbf{x} = \mathbf{b}$ has more than one least-squares solution.
- **84.** Let *A* be an $n \times n$ matrix. Which of the following are equivalent to the statement "*A* is diagonalizable over the real numbers?"
 - (1) A is similar to a diagonal matrix.
 - (2) A has at least one eigenvector for each eigenvalue.
 - (3) For each real eigenvalue λ of *A*, the dimension of the λ -eigenspace is equal to the algebraic multiplicity of λ .
 - (4) *A* has *n* linearly independent eigenvectors.
 - (5) *A* is invertible.
- **85.** Let *A* be a square matrix. Complete the following definitions, paying attention to the quantifiers (there exists / for all):
 - **a)** An eigenvector of *A* is...
 - **b)** An eigenvalue of *A* is...
- **86.** Let *A* be an $n \times n$ matrix with eigenvalues 2 and 3. Compute the eigenvalues of these matrices:

$$A^{-1} \qquad A - 7I_n \qquad 2A.$$

- **87.** Let *V* be a subspace of \mathbb{R}^n ; assume that $V \neq \{0\}$ and $V \neq \mathbb{R}^n$. Let *P* be the matrix for the projection onto *V*.
 - **a)** Show that the eigenvalues of *P* are 0 and 1.
 - **b)** Which of the four fundamental subspaces is equal to the 0-eigenspace? Which of the four fundamental subspaces is equal to the 1-eigenspace?
 - c) Why is *P* diagonalizable? What diagonal matrix is it similar to?
- **88.** Without computing any eigenvalues, decide which of the following matrices are positive definite.

$$\begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} \quad \begin{pmatrix} -1 & 2 \\ 2 & 4 \end{pmatrix} \quad \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} \quad \begin{pmatrix} 1 & 3 & 2 \\ 3 & -1 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

89. Let *A* be a 3 × 3 matrix with singular values 1 and 2. Compute the following quantities:

a) The rank of *A*.

- **b)** The determinant of *A*.
- **c)** The determinant of $A^T A$.
- **d)** The eigenvalues of $A^T A$.
- **90.** Indicate which of the following phrases and expressions are not defined.
 - (1) The dimension of the matrix *A* is equal to 5.
 - (2) The subspace *V* has dimensions 4×4 .
 - (3) The matrix *A* is linearly independent.
 - (4) The subspace *V* has basis $\begin{pmatrix} 1 & 2 & 3 \\ 1 & -2 & 1 \\ 0 & 0 & 3 \end{pmatrix}$.
 - (5) The quantity $\mathbf{u} \cdot \mathbf{u} \cdot \mathbf{u}$, for \mathbf{u} in \mathbf{R}^n .
 - (6) A^{\perp} for A an $m \times n$ matrix.

91. True/false problems:

- (1) If $A\mathbf{x} = \mathbf{b}$ has at least one solution for every **b**, then *A* has full row rank.
- (2) If the columns of A span \mathbf{R}^m , then $A\mathbf{x} = \mathbf{b}$ is consistent for every vector \mathbf{b} in \mathbf{R}^m .
- (3) If $A\mathbf{x} = \mathbf{b}$ is consistent, then $A\mathbf{x} = 5\mathbf{b}$ is consistent.
- (4) If **x** is a solution of A**x** = **b**, then every vector in S{**x**} is also a solution of A**x** = **b**.
- (5) The solution set of $A\mathbf{x} = \mathbf{b}$ is a subspace.
- (6) The solution set of $A\mathbf{x} = \mathbf{0}$ is a subspace.

(7) The columns of
$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$
 are linearly independent.

(8) The matrix equation $\begin{pmatrix} 1 & -1 & 2 \\ 0 & 4 & 3 \end{pmatrix}$ **x** = **b** is consistent for every **b** in **R**².

- (9) If $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is a basis for \mathbf{R}^5 , then n = 5.
- (10) Any four linearly independent vectors in \mathbf{R}^4 form a basis of \mathbf{R}^4 .
- (11) There exists a 3×5 matrix of rank 4.
- (12) There exists a 3×5 matrix whose null space has dimension 4.
- (13) Every elementary matrix is invertible.
- (14) If *V* is the set of all vectors (x, y, z) in \mathbb{R}^3 such that x = 2y, then the orthogonal complement of *V* is a line.
- (15) If *A* is a 3×4 matrix, then $C(A)^{\perp}$ is a subspace of \mathbb{R}^4 .
- (16) If *A* has the QR factorization A = QR, then the columns of *R* span C(A).
- (17) If *A* has the QR factorization A = QR, then the columns of *Q* span *C*(*A*).
- (18) A least-squares solution $\hat{\mathbf{x}}$ of $A\mathbf{x} = \mathbf{b}$ minimizes the quantity $||A\hat{\mathbf{x}} \mathbf{b}||^2$.
- (19) If **x** is in a subspace V, then the projection of **x** onto V is equal to zero.
- (20) If **x** is not in a subspace *V*, then the projection of **x** onto V^{\perp} is nonzero.
- (21) If *V* is a two-dimensional subspace of \mathbf{R}^4 , then dim $(V^{\perp}) = 2$.
- (22) Every subspace of \mathbf{R}^n has an orthonormal basis.
- (23) If *A* is an $n \times n$ matrix and *c* is a scalar, then det(*cA*) = *c* det(*A*).

- (24) If *A* is a matrix with characteristic polynomial $p(\lambda) = -\lambda^3 + \lambda^2 + \lambda$, then *A* is invertible.
- (25) If A is a square matrix, then the nonzero vectors in N(A) are eigenvalues of A.
- (26) The eigenvalues of a triangular square matrix are the numbers on the main diagonal.
- (27) If λ is a complex eigenvalue of a real matrix *A*, then so is $\overline{\lambda}$.
- (28) A triangular matrix *A* with real entries can have a complex (non-real) eigenvalue.
- (29) If *A* is an $n \times n$ matrix and det(*A*) = 2, then 2 is an eigenvalue of *A*.
- (30) The $n \times n$ zero matrix is diagonalizable.
- (31) If A is a 3×3 matrix and 1, 2, 3 are eigenvalues of A, then A is diagonalizable.
- (32) A diagonalizable $n \times n$ matrix admits *n* linearly independent eigenvectors.
- (33) If *S* is a symmetric matrix with eigenvalue λ , then the algebraic multiplicity of λ equals the geometric multiplicity.
- (34) The maximum value of $||A\mathbf{x}|| / ||\mathbf{x}||$, for $\mathbf{x} \neq 0$, is the largest eigenvalue of *A*.
- 92. In the following, if the statement is true, prove it; if not, give a counterexample.
 - (1) A system of linear equations $A\mathbf{x} = \mathbf{b}$ cannot have exactly two solutions.
 - (2) If a linear system has more equations than unknowns, then the system cannot have a unique solution.
 - (3) If a linear system has more unknowns than equations, then the system cannot have a unique solution.
 - (4) If *A* has more columns than rows, then the columns of *A* must be linearly dependent.
 - (5) If *A* has more rows than columns, then the columns of *A* must be linearly independent.
 - (6) If *A* has more rows than columns, then $A\mathbf{x} = \mathbf{b}$ is inconsistent for some \mathbf{b} in \mathbf{R}^{m} .
 - (7) The zero vector is in the span of the columns of A.
 - (8) $A\mathbf{x} = \mathbf{b}$ is consistent if and only if **b** is in the span of the columns of *A*.
 - (9) If $A\mathbf{x} = \mathbf{b}$ has a unique solution for some \mathbf{b} in \mathbf{R}^m , then $A\mathbf{x} = \mathbf{0}$ has a unique solution.
 - (10) If *A* is an $m \times n$ matrix with linearly dependent columns, then the columns of *A* do not span \mathbb{R}^m .
 - (11) If *A* and *B* are matrices and *AB* is defined, then the column space of *AB* is contained in the column space of *A*.
 - (12) Any two vectors in \mathbf{R}^3 span a plane.
 - (13) If $A\mathbf{x} = \mathbf{0}$ has only one solution, then $A\mathbf{x} = \mathbf{b}$ has a unique solution for every \mathbf{b} in \mathbf{R}^m .
 - (14) There is no 3×3 matrix *A* such that C(A) = N(A).
 - (15) Any set of vectors containing **0** is linearly dependent.
 - (16) If *A* is a 3 × 3 matrix of rank 2, then $A^2 \neq 0$.
 - (17) For any matrix *A*, we have $N(A) = N(A^T A)$.
 - (18) If $\{v_1, v_2\}$ is linearly independent and $\{v_2v_3\}$ is linearly independent, then $\{v_1, v_2, v_3\}$ is linearly independent.

- (19) A singular matrix A must have a zero entry.
- (20) An invertible matrix is a product of elementary matrices.
- (21) An invertible matrix has a factorization A = LU, for U upper-triangular and L lower-triangular.
- (22) If A, B, C are nonzero matrices such that AB = AC, then B = C.
- (23) If A, B, C are invertible matrices such that AB = AC, then B = C.
- (24) If *A* and *B* are nonzero matrices and *AB* is defined, then the column space of *AB* is equal to the column space of *A*.
- (25) If *A* and *B* are $n \times n$ matrices and *A* is singular, then the columns of *AB* are linearly dependent.
- (26) If *A* is an invertible $n \times n$ matrix, then the columns of A^{-1} span \mathbb{R}^n .
- (27) If *A* is an $m \times n$ matrix, then dim C(A) + dim N(A) = n.
- (28) If *V* and *W* are subspaces of \mathbb{R}^n with dim(*V*) + dim(*W*) > *n*, then there is a nonzero vector contained in both *V* and *W*.
- (29) If every vector in a subspace *V* is orthogonal to every vector in another subspace *W*, then $V = W^{\perp}$.
- (30) Every projection matrix P can be written as QQ^T for a matrix Q with orthonormal columns.
- (31) If *P* is the projection matrix onto the the row space of a matrix *A*, then I P projects vectors onto the null space of *A*.
- (32) The row space of A equals the row space of $A^{T}A$.
- (33) Let *W* be a subspace of \mathbf{R}^n . If **y** is in *W* and **y** is in W^{\perp} , then $\mathbf{y} = \mathbf{0}$.
- (34) Let *W* be a subspace of \mathbf{R}^n and let \mathbf{x} be a vector in \mathbf{R}^n . Then \mathbf{x} can be expressed in the form $\mathbf{y} + \mathbf{z}$ for \mathbf{y} in *W* and \mathbf{z} in W^{\perp} .
- (35) If *P* is a projection matrix then $P^2 = P$.
- (36) If *A* and *B* are orthogonal square matrices, then so is A + B.
- (37) If *A* and *B* are orthogonal square matrices, then so is *AB*.
- (38) A matrix with orthonormal columns has full column rank.
- (39) If *Q* is an orthogonal $n \times n$ matrix and **x**, **y** are vectors in \mathbb{R}^n , then $(Q\mathbf{x}) \cdot (Q\mathbf{y}) = \mathbf{x} \cdot \mathbf{y}$ and $||Q\mathbf{x}|| = ||\mathbf{x}||$.
- (40) If $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a linearly independent set of vectors in \mathbf{R}^3 , then $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is orthogonal.
- (41) If $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are nonzero orthogonal vectors in \mathbf{R}^3 , then $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly independent.
- (42) If Q has orthonormal columns, then QQ^T is the matrix for the orthogonal projection onto C(Q).
- (43) If **b** is in C(A), then the least-squares solutions of $A\mathbf{x} = \mathbf{b}$ are simply the solutions of $A\mathbf{x} = \mathbf{b}$.
- (44) If *A* has linearly independent columns, then $A\mathbf{x} = \mathbf{b}$ has a unique least squares solution.
- (45) If *A* is a 3 × 2 matrix with orthonormal columns \mathbf{v}_1 , \mathbf{v}_2 , then the least-squares solution of $A\mathbf{x} = \mathbf{b}$ is $(\mathbf{b} \cdot \mathbf{v}_1, \mathbf{b} \cdot \mathbf{v}_2)$.
- (46) If a matrix has determinant zero, then two of the columns (or rows) are multiples of each other, or one of the columns (or rows) is zero.
- (47) If A^n is invertible for some positive integer *n*, then *A* is invertible.

- (48) An orthogonal matrix has determinant ± 1 .
- (49) If λ is an eigenvalue of *A*, then the set of all eigenvectors with eigenvalue λ is a subspace.
- (50) A square matrix has the same eigenvalues as its transpose.
- (51) A square matrix has the same characteristic polynomial as its transpose.
- (52) Every square matrix admits at least one (potentially complex) eigenvalue.
- (53) If *A* is an $n \times n$ matrix and A 3I has rank *n*, then 3 is not an eigenvalue of *A*.
- (54) If *A* is an invertible matrix and 2 is an eigenvalue of *A*, then 1/2 is an eigenvalue of A^{-1} .
- (55) If \mathbf{v}_1 and \mathbf{v}_2 are eigenvectors of *A* with eigenvalues λ_1 and λ_2 , respectively, and if $\lambda_1 \neq \lambda_2$, then $\{\mathbf{v}_1, \mathbf{v}_2\}$ is linearly independent.
- (56) If *A* is a square matrix and $\mathbf{v}_1, \mathbf{v}_2$ are eigenvectors of *A*, then $\mathbf{v}_1 + \mathbf{v}_2$ is an eigenvector of *A*.
- (57) Suppose *A* and *B* are $n \times n$ matrices. If 0 is an eigenvalue of *AB*, then 0 is an eigenvalue of *BA*.
- (58) If λ is an eigenvalue of *A* then λ^2 is an eigenvalue of A^2 .
- (59) If λ is an eigenvalue of two $n \times n$ matrices *A* and *B*, then λ^2 is an eigenvalue of *AB*.
- (60) If *A* is square and \mathbf{v}_1 , \mathbf{v}_2 are nonzero vectors satisfying $A\mathbf{v}_1 = 2\mathbf{v}_1$ and $A\mathbf{v}_2 = 3\mathbf{v}_2$, then $\mathbf{v}_1 \perp \mathbf{v}_2$.
- (61) If *A* is a 3×3 matrix that has eigenvalues 1 and -1, both of algebraic multiplicity one, then *A* is diagonalizable (over the real numbers).
- (62) If *A* is a 3×3 matrix that has eigenvalues 1 and -1, with algebraic multiplicities 1 and 2, respectively, then *A* is diagonalizable.
- (63) If A is a 9×9 matrix with three distinct eigenvalues, and the eigenspace corresponding to one of these eigenvalues has dimension 7, then A is diagonalizable.
- (64) If $A = XBX^{-1}$ then A and B have the same characteristic polynomial.
- (65) If $A = XBX^{-1}$ then A and B have the same eigenvectors.
- (66) Every square matrix is diagonalizable if we allow complex eigenvalues and eigenvectors.
- (67) If *A* is an $n \times n$ matrix with *n* linearly independent eigenvectors, then A^T also has *n* linearly independent eigenvectors.
- (68) If A is diagonalizable then so is A^2 .
- (69) If A^2 is diagonalizable then so is A.
- (70) If *A* is invertible and diagonalizable then so is A^{-1} .
- (71) If A is a diagonalizable matrix whose only eigenvalue is 1, then A is the identity.
- (72) A diagonalizable $n \times n$ matrix has *n* distinct eigenvalues.
- (73) If S is symmetric, then either S or -S is positive-semidefinite.
- (74) If λ is an eigenvalue of AA^T , then λ is an eigenvalue of A^TA .
- (75) If λ is a eigenvalue of $A^T A$ and $\lambda > 0$, then λ is also an eigenvalue of AA^T .
- (76) If *S* and *T* are positive definite, then so is S + T.
- (77) If *S* is a symmetric $n \times n$ matrix and **x**, **y** are vectors in \mathbb{R}^n , then $(S\mathbf{x}) \cdot \mathbf{y} = \mathbf{x} \cdot (S\mathbf{y})$.
- (78) If *S* is symmetric and $\mathbf{v}_1, \mathbf{v}_2$ are nonzero vectors satisfying $S\mathbf{v}_1 = 2\mathbf{v}_1$ and $S\mathbf{v}_2 = 3\mathbf{v}_2$, then $\mathbf{v}_1 \perp \mathbf{v}_2$.
- (79) If A is any matrix, then $A^{T}A$ is positive semidefinite.

- (80) A positive definite matrix must have positive numbers on the main diagonal.
- (81) The singular values of a diagonalizable, invertible, square matrix are the absolute values of the eigenvalues. [Hint: try a 2 × 2 matrix of the form $\begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$.]
- (82) If A has linearly independent columns, then A^+A is the identity matrix.
- (83) The largest singular value of an orthogonal matrix is 1.
- (84) The maximum value of $||A\mathbf{x}||$, for $||\mathbf{x}|| = 1$, is the largest singular value of *A*.
- (85) The singular values of a symmetric matrix are the absolute values of the nonzero eigenvalues.
- **93.** Give examples of matrices with the following properties. If no such matrix exists, explain why. All matrices must have real entries.
 - (1) A 4 × 4 matrix A such that C(A) = N(A).
 - (2) A 3×2 matrix with singular values 2 and 1.
 - (3) A matrix having eigenvalue 3 with algebraic multiplicity 2 and geometric multiplicity 1.
 - (4) A matrix having eigenvalue 3 with algebraic and geometric multiplicity 2.
 - (5) A matrix having eigenvalue 3 with algebraic multiplicity 1 and geometric multiplicity 2.
 - (6) A 2×2 matrix that is invertible but not diagonalizable.
 - (7) A 2×2 matrix that is diagonalizable but not invertible.
 - (8) A 2×2 matrix that is diagonalizable and invertible.
 - (9) A 2×2 matrix that is neither diagonalizable nor invertible.
 - (10) A 3×4 matrix A and a 4×3 matrix B such that AB is invertible.
 - (11) A 3 \times 4 matrix *A* and a 4 \times 3 matrix *B* such that *BA* is invertible.
 - (12) A 3×3 symmetric matrix that is positive semidefinite but not positive definite.
 - (13) A 3×3 symmetric matrix that is not diagonalizable.
 - (14) A 3×3 matrix whose entries are all either 1 or -1, with determinant 4.
 - (15) A 4×6 matrix of rank 6.
 - (16) An invertible 2 × 2 matrix A such that $A_{\binom{1}{2}} = A_{\binom{2}{1}}^{\binom{2}{2}}$.
 - (17) A 2 × 2 matrix whose column space is the line 3x + y = 0 and whose null space is the line 5x + y = 0.
 - (18) A 2 × 2 matrix whose column space is the line 3x + y = 0 and whose null space is the line 5x + y = 1.
 - (19) A 2 × 2 matrix whose column space is the line 3x + y = 0 and whose null space is $\{0\}$.
 - (20) A 3×3 matrix with no real eigenvalues.
 - (21) A 2×2 matrix with no real eigenvalues.
 - (22) A 2 \times 2 singular matrix with eigenvalue 2 + 3*i*.
 - (23) A diagonalizable 3×3 matrix with exactly two distinct eigenvalues.
 - (24) A 2×2 matrix with eigenvalues 1 and 2.
 - (25) A 2 × 2 matrix with eigenvectors $\binom{1}{0}$ and $\binom{0}{1}$ having the same eigenvalue.
 - (26) A nonzero 2 × 2 diagonalizable matrix with characteristic polynomial $p(\lambda) = \lambda^2$.
 - (27) A 2 × 2 matrix whose 1-eigenspace is the line x + 2y = 0 and whose 2-eigenspace is the line x + 3y = 0.

- (28) A 4 × 4 matrix whose columns form an orthonormal basis for \mathbf{R}^4 , other than the identity matrix.
- (29) A symmetric, orthogonal 2×2 matrix, other than the identity matrix.
- (30) A matrix A satisfying

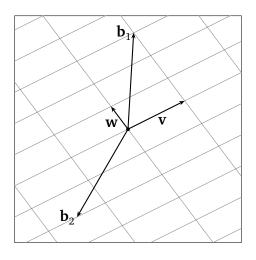
$$\dim(\operatorname{Row}(A)^{\perp}) = 2$$
 and $\dim(C(A)^{\perp}) = 3$.

- (31) A matrix that does not have a singular value decomposition.
- (32) A 3×4 matrix with orthonormal columns.
- (33) A 4×3 matrix with orthonormal columns.
- (34) A symmetric matrix *S* satisfying

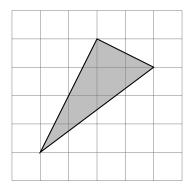
$$S\begin{pmatrix}1\\2\\3\end{pmatrix} = \begin{pmatrix}2\\4\\6\end{pmatrix}$$
 and $S\begin{pmatrix}2\\1\\0\end{pmatrix} = \begin{pmatrix}-2\\-1\\0\end{pmatrix}$.

Pictures

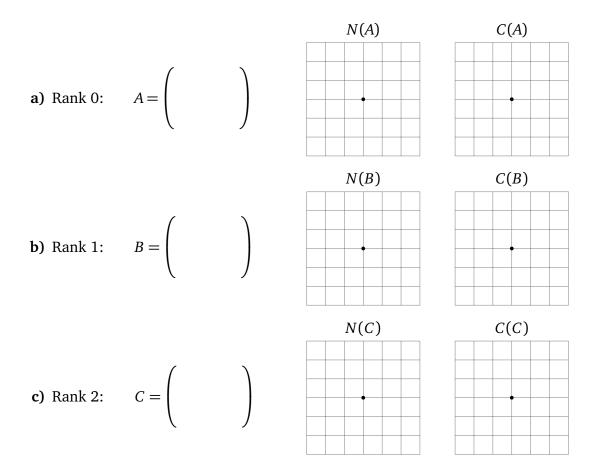
94. A certain 2×2 matrix *A* has columns **v** and **w**, pictured below. Solve the equations $A\mathbf{x}_1 = \mathbf{b}_1$ and $A\mathbf{x}_2 = \mathbf{b}_2$, where \mathbf{b}_1 and \mathbf{b}_2 are the vectors in the picture.



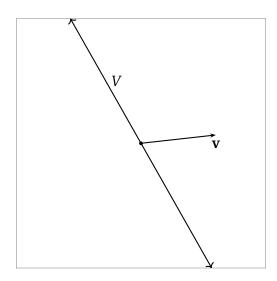
95. Compute the area of the triangle in the picture:



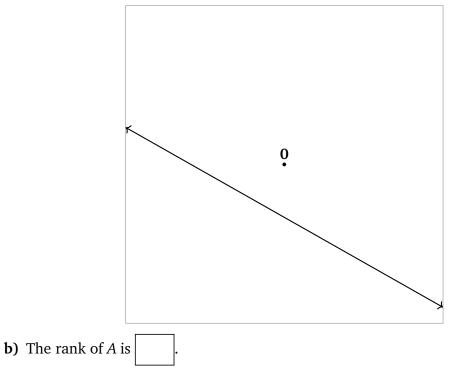
96. Give examples of 2×2 matrices *A*, *B*, *C* with ranks 0, 1, and 2, respectively, and draw pictures of the null space and column space. (Be precise!)



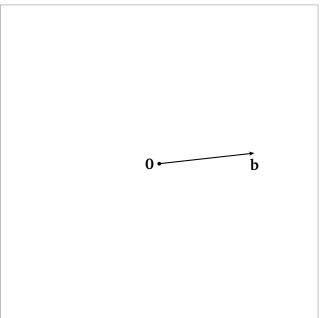
97. A subspace *V* and a vector **v** are drawn below. Draw the projection **p** of **v** onto *V*, and draw the projection \mathbf{p}_{\perp} of **v** onto V^{\perp} . Label your answers!



- **98.** This problem concerns a certain 2×2 matrix *A* and a vector $\mathbf{b} \in \mathbf{R}^2$. You do not know what they are numerically.
 - **a)** The solutions of A**x** = **b** are drawn below. Draw N(A) in the same diagram.



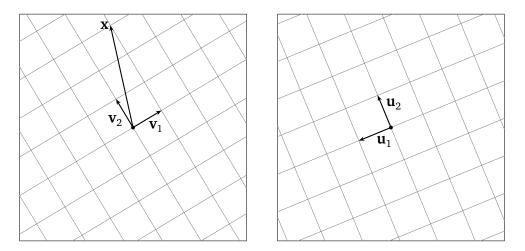
c) Suppose that b is the vector in the picture. Draw the left null space of A in the same picture. [This is the same b as before, so in particular, Ax = b has a solution.]



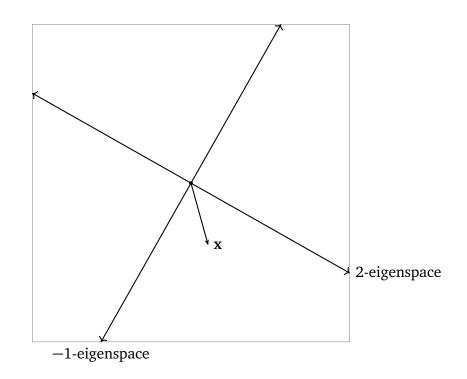
99. A certain 2×2 matrix *A* has the singular value decomposition

$$A = \begin{pmatrix} | & | \\ \mathbf{u}_1 & \mathbf{u}_2 \\ | & | \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} | & | \\ \mathbf{v}_1 & \mathbf{v}_2 \\ | & | \end{pmatrix}^T,$$

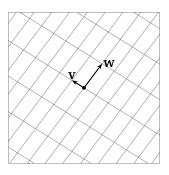
where $\mathbf{u}_1, \mathbf{u}_2, \mathbf{v}_1, \mathbf{v}_2$ are drawn in the diagrams below. Given \mathbf{x} in the diagram on the left, draw $A\mathbf{x}$ on the diagram on the right.



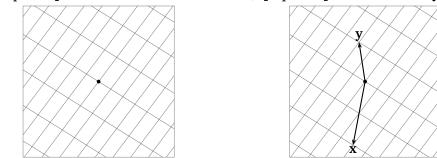
100. A certain 2×2 matrix *A* has eigenvalues 2 and -1, with eigenspaces drawn below. If **x** is the vector in the picture, draw *A***x**.



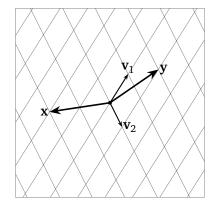
101. A certain 2×2 matrix *A* has eigenectors **v** and **w**, pictured below, with corresponding eigenvalues 3/2 and -1/2.



a) [3 points] Draw Av and Aw below. b) [4 points] Draw Ax and Ay below.



102. Suppose that $A = X \begin{pmatrix} 1/2 & 0 \\ 0 & -1 \end{pmatrix} X^{-1}$, where *X* has columns \mathbf{v}_1 and \mathbf{v}_2 . Given **x** and **y** in the picture below, draw the vectors $A\mathbf{x}$ and $A\mathbf{y}$.



103. Find the 2×2 matrix *A* whose eigenspaces are drawn below. The grid lines are one unit apart.

