

**MATH 218 SECTION 3  
MIDTERM EXAMINATION 3**

<b>Name</b>		<b>Duke UniqueID</b>	
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Please **read all instructions** carefully before beginning.

- Do not open this test booklet until you are directed to do so.
- You have 75 minutes to complete this exam.
- If you finish early, go back and check your work.
- This exam is closed book.
- You may use a calculator to do arithmetic. No other technology is allowed.
- For full credit you must show your work so that your reasoning is clear.
- Do not spend too much time on any one problem. Read them all through first and attack them in an order that allows you to make the most progress.
- Good luck!

**WHO IS THE  
MOST AWESOME  
PERSON TODAY?**



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# Problem 1.

[20 points]

Consider the following matrix and its singular value decomposition  $A = U\Sigma V^T$ :

$$A = \begin{pmatrix} 1/\sqrt{10} & 1/\sqrt{15} & 1/\sqrt{2} & -1/\sqrt{3} \\ -2/\sqrt{10} & 3/\sqrt{15} & 0 & 0 \\ 2/\sqrt{10} & 2/\sqrt{15} & 0 & 1/\sqrt{3} \\ -1/\sqrt{10} & -1/\sqrt{15} & 1/\sqrt{2} & 1/\sqrt{3} \end{pmatrix} \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \\ -1/\sqrt{6} & -2/\sqrt{6} & -1/\sqrt{6} \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} \end{pmatrix}.$$

From this you can read off all of the following properties of  $A$ .

a)  $A$  is a   $\times$   matrix of rank  $r =$  .

b) Find orthonormal bases of the four fundamental subspaces of  $A$ :

$$\begin{matrix} N(A) & C(A^T) & C(A) & N(A^T) \\ \left\{ \begin{matrix} \\ \\ \\ \end{matrix} \right\} & \left\{ \begin{matrix} \\ \\ \\ \end{matrix} \right\} & \left\{ \begin{matrix} \\ \\ \\ \end{matrix} \right\} & \left\{ \begin{matrix} \\ \\ \\ \end{matrix} \right\} \end{matrix}$$

c) Express  $A$  as a linear combination of rank-one matrices  $\mathbf{u}\mathbf{v}^T$  (your answer should consist of vectors with numbers, not letters):

$$A =$$

d) Find a *unit* vector  $\mathbf{x}$  maximizing  $|\mathbf{A}\mathbf{x}|$ :

$$\mathbf{x} = \begin{pmatrix} \\ \\ \\ \end{pmatrix} \quad |\mathbf{A}\mathbf{x}| = \text{}$$

e) Compute the matrix  $P$  for orthogonal projection onto  $C(A)$  (write it as a product, without expanding it out):

$$P =$$

**Solution.**

- a) The size and rank of  $A$  can be read off from  $\Sigma$ :  $A$  is a  $4 \times 3$  matrix of rank 2.  
 b) The columns of  $U$  and  $V$  give orthonormal bases for the four subspaces.

$$N(A): \left\{ \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$C(A^T): \left\{ \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix} \right\}$$

$$C(A): \left\{ \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ -2 \\ 2 \\ -1 \end{pmatrix}, \frac{1}{\sqrt{15}} \begin{pmatrix} 1 \\ 3 \\ 2 \\ -1 \end{pmatrix} \right\}$$

$$N(A^T): \left\{ \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}.$$

- c) This is the vector form of the SVD:

$$A = 3 \cdot \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ -2 \\ 2 \\ -1 \end{pmatrix} \cdot \frac{1}{\sqrt{3}} (1 \quad -1 \quad 1) + 2 \cdot \frac{1}{\sqrt{15}} \begin{pmatrix} 1 \\ 3 \\ 2 \\ -1 \end{pmatrix} \cdot \frac{1}{\sqrt{6}} (-1 \quad -2 \quad -1)$$

- d) The maximum value of  $|A\mathbf{x}|$  is  $\sigma_1$  and is attained at  $\mathbf{v}_1$ :

$$\mathbf{x} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \quad |A\mathbf{x}| = 3$$

- e) The orthogonal projection onto  $C(A)$  is  $AA^+ = (U\Sigma V^T)(V\Sigma^+U^T) = U\Sigma\Sigma^+U^T$ , which is

$$P = \begin{pmatrix} 1/\sqrt{10} & 1/\sqrt{15} & 1/\sqrt{2} & -1/\sqrt{3} \\ -2/\sqrt{10} & 3/\sqrt{15} & 0 & 0 \\ 2/\sqrt{10} & 2/\sqrt{15} & 0 & 1/\sqrt{3} \\ -1/\sqrt{10} & -1/\sqrt{15} & 1/\sqrt{2} & 1/\sqrt{3} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

$$\begin{pmatrix} 1/\sqrt{10} & 1/\sqrt{15} & 1/\sqrt{2} & -1/\sqrt{3} \\ -2/\sqrt{10} & 3/\sqrt{15} & 0 & 0 \\ 2/\sqrt{10} & 2/\sqrt{15} & 0 & 1/\sqrt{3} \\ -1/\sqrt{10} & -1/\sqrt{15} & 1/\sqrt{2} & 1/\sqrt{3} \end{pmatrix}^T.$$

## Problem 2.

[20 points]

Consider the symmetric matrix

$$S = \begin{pmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{pmatrix}.$$

a) Find an orthogonal matrix  $Q$  and a diagonal matrix  $\Lambda$  such that  $S = Q\Lambda Q^T$ :

$$Q = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix} \quad \Lambda = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$$

b) Circle one:  $S$  is

positive-definite    positive-semidefinite    neither of these

c) Write down the singular value decomposition of  $S$ :

$$S = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix} \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix} \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$$

### Solution.

- a) First we compute the eigenvalues of  $S$ . We find the characteristic polynomial by expanding cofactors along the first column:

$$\begin{aligned} p(\lambda) &= \det \begin{pmatrix} 1-\lambda & 0 & 2 \\ 0 & -1-\lambda & -2 \\ 2 & -2 & -\lambda \end{pmatrix} \\ &= (1-\lambda) \det \begin{pmatrix} -1-\lambda & -2 \\ -2 & -\lambda \end{pmatrix} + 2 \det \begin{pmatrix} 0 & 2 \\ -1-\lambda & -2 \end{pmatrix} \\ &= (1-\lambda)[(-1-\lambda)(-\lambda) - 4] + 2[-2(-1-\lambda)] \\ &= (1-\lambda)(\lambda^2 + \lambda - 4) - 4(-1-\lambda) \\ &= \lambda^2 + \lambda - 4 - \lambda^3 - \lambda^2 + 4\lambda + 4 + 4\lambda \\ &= -\lambda^3 + 9\lambda = -\lambda(\lambda - 3)(\lambda + 3). \end{aligned}$$

The eigenvalues are 0 and  $\pm 3$ ; we compute eigenvectors:

$$\lambda = 3: S - 3I = \begin{pmatrix} -2 & 0 & 2 \\ 0 & -4 & 2 \\ 2 & -2 & -3 \end{pmatrix} \xrightarrow{\text{RREF}} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \mathbf{v}_1 = \frac{1}{3} \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix}$$

$$\lambda = -3: S + 3I = \begin{pmatrix} 4 & 0 & 2 \\ 0 & 2 & 2 \\ 2 & -2 & 3 \end{pmatrix} \xrightarrow{\text{RREF}} \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \mathbf{v}_2 = \frac{1}{3} \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}$$

$$\lambda = 0: S - 0I = \begin{pmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{pmatrix} \xrightarrow{\text{RREF}} \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \mathbf{v}_3 = \frac{1}{3} \begin{pmatrix} -2 \\ -2 \\ 1 \end{pmatrix}$$

Hence  $S = Q\Lambda Q^T$  for

$$Q = \frac{1}{3} \begin{pmatrix} 2 & -1 & -2 \\ -1 & 2 & -2 \\ 2 & 2 & 1 \end{pmatrix} \quad \Lambda = \begin{pmatrix} 3 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

- b)  $S$  has a negative eigenvalue, so it is neither positive-definite nor positive-semidefinite.  
c) The singular values of  $S$  are the absolute values of the nonzero eigenvalues:  $\sigma_1 = \sigma_2 = 3$ . We have

$$\begin{aligned} 3\mathbf{v}_1 &= S\mathbf{v}_1 = \sigma_1\mathbf{u}_1 \implies \mathbf{u}_1 = \mathbf{v}_1 \\ -3\mathbf{v}_2 &= S\mathbf{v}_2 = \sigma_2\mathbf{u}_2 \implies \mathbf{u}_2 = -\mathbf{v}_2. \end{aligned}$$

We can take  $\mathbf{u}_3 = \mathbf{v}_3$  as our orthonormal basis of  $N(S) = N(S^T)$ , so

$$S = \frac{1}{3} \begin{pmatrix} 2 & 1 & -2 \\ -1 & -2 & -2 \\ 2 & -2 & 1 \end{pmatrix} \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 0 \end{pmatrix} \frac{1}{3} \begin{pmatrix} 2 & -1 & 2 \\ -1 & 2 & 2 \\ -2 & -2 & 1 \end{pmatrix}$$

### Problem 3.

[20 points]

Consider the matrix

$$A = \begin{pmatrix} 2 & -1 \\ \frac{3}{2} & -\frac{1}{2} \end{pmatrix}.$$

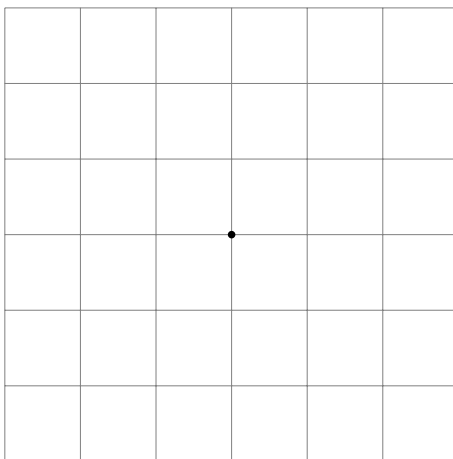
- a) Find an invertible matrix  $X$  and a diagonal matrix  $\Lambda$  such that  $A = X\Lambda X^{-1}$ .

$$X = \begin{pmatrix} & \\ & \end{pmatrix} \quad \Lambda = \begin{pmatrix} & \\ & \end{pmatrix}$$

- b) Compute  $A^n \mathbf{v}_0$  for  $\mathbf{v}_0 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ . What happens when  $n \rightarrow \infty$ ?

$$A^n \mathbf{v}_0 = \begin{pmatrix} & \\ & \end{pmatrix} \quad A^n \mathbf{v}_0 \xrightarrow{n \rightarrow \infty} \begin{pmatrix} & \\ & \end{pmatrix}$$

- c) In the diagram, *draw and label* the eigenspaces of  $A$ , and draw the vectors  $\mathbf{v}_0, A\mathbf{v}_0, A^2\mathbf{v}_0, A^3\mathbf{v}_0, \dots$  as points. (The grid lines are one unit apart, and the dot is the origin.)  
[Hint: you do not have to compute  $A^n \mathbf{v}_0$  numerically to do this.]



- d) Solve the system of ordinary differential equations

$$\begin{aligned} \frac{d}{dt}u_1 &= 2u_1 - u_2 & u_1(0) &= 1 & \rightsquigarrow & u_1(t) = \\ \frac{d}{dt}u_2 &= \frac{3}{2}u_1 - \frac{1}{2}u_2 & u_2(0) &= 2 & & u_2(t) = \end{aligned}$$

## Solution.

a) The characteristic polynomial of  $A$  is

$$p(\lambda) = \lambda^2 - \text{Tr}(A)\lambda + \det(A) = \lambda^2 - \frac{3}{2}\lambda + \frac{1}{2} = (\lambda - 1)\left(\lambda - \frac{1}{2}\right).$$

The eigenvalues are  $\lambda_1 = 1$  and  $\lambda_2 = \frac{1}{2}$ . We compute eigenvectors:

$$A - 1I = \begin{pmatrix} 1 & -1 \\ - & - \end{pmatrix} \rightsquigarrow \mathbf{q}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$A - \frac{1}{2}I = \begin{pmatrix} \frac{3}{2} & -1 \\ - & - \end{pmatrix} \rightsquigarrow \mathbf{q}_2 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

Hence  $A = X\Lambda X^{-1}$  for

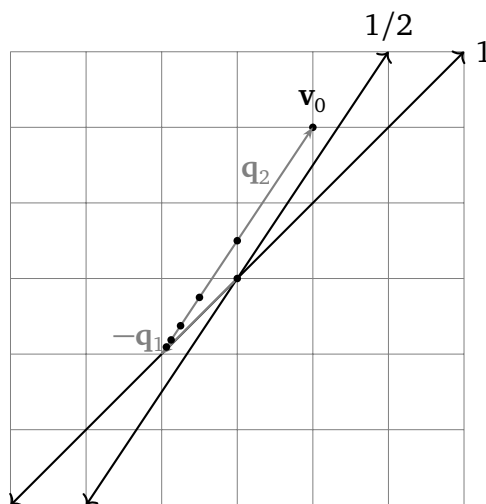
$$X = \begin{pmatrix} 1 & 2 \\ 1 & 3 \end{pmatrix} \quad \Lambda = \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{pmatrix}.$$

b) We eyeball  $\mathbf{v}_0 = -\mathbf{q}_1 + \mathbf{q}_2$ , so

$$A^n \mathbf{v}_0 = -\mathbf{q}_1 + \frac{1}{2^n} \mathbf{q}_2.$$

This approaches  $-\mathbf{q}_1 = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$  as  $n \rightarrow \infty$ .

c) The eigenspaces are spanned by  $\mathbf{q}_1$  and  $\mathbf{q}_2$ .



d) We need to solve  $\mathbf{u}' = A\mathbf{u}$  for  $\mathbf{u}(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \mathbf{v}_0$  and  $A$  as above. We have  $\mathbf{u}(0) = -\mathbf{q}_1 + \mathbf{q}_2$ , so the solution is

$$\mathbf{u}(t) = -e^t \mathbf{q}_1 + e^{t/2} \mathbf{q}_2 \quad \Rightarrow \quad \begin{aligned} u_1 &= -e^t + 2e^{t/2} \\ u_2 &= -e^t + 3e^{t/2} \end{aligned}$$



## Problem 4.

[16 points]

All of the following statements are false. Provide a counterexample to each. You need not justify your answers.

- a) The singular values of a diagonalizable, invertible, square matrix are the absolute values of the eigenvalues. [Hint: try a  $2 \times 2$  matrix of the form  $\begin{pmatrix} a & b \\ 0 & d \end{pmatrix}$ .]
- b) If a matrix has determinant zero, then two of the columns are multiples of each other, or one of the columns is zero.
- c) If  $S$  is symmetric, then either  $S$  or  $-S$  is positive-semidefinite.
- d) If  $\lambda$  is an eigenvalue of  $AA^T$ , then  $\lambda$  is an eigenvalue of  $A^T A$ .

**Solution.**

- a) The matrix  $A = \begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix}$  has eigenvalues 1 and 2, so it is invertible and diagonalizable. However,

$$A^T A = \begin{pmatrix} 1 & 0 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 5 \end{pmatrix}$$

has characteristic polynomial  $p(\lambda) = \lambda^2 - \text{Tr}(A)\lambda + \det(A) = \lambda^2 - 6\lambda + 4$ ; we have  $p(1^2) = -1$  and  $p(2^2) = -4$ , so neither 1 nor 2 is a singular value of  $A$ .

- b) One column can be the sum of the other two; for instance,

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 5 \\ 3 & 4 & 7 \end{pmatrix}.$$

- c) Any symmetric matrix  $S$  with both positive and negative eigenvalues works:

$$S = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

- d) This can only be true for  $\lambda = 0$  (see 5(a)). Zero is an eigenvalue of  $A^T A$  (resp.  $AA^T$ ) if and only if  $A$  has linearly independent columns (resp. rows), so we need to find a matrix with linearly independent columns and linearly dependent rows. For instance:

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}.$$

## Problem 5.

[16 points]

Prove the following statements. (None should take more than a couple of lines.)

- a) If  $\lambda$  is an eigenvalue of  $A^T A$  and  $\lambda > 0$ , then  $\lambda$  is also an eigenvalue of  $AA^T$ .
- b) If  $A$  is a  $3 \times 3$  matrix that has eigenvalues 1 and  $-1$ , both of algebraic multiplicity one, then  $A$  is diagonalizable (over the real numbers).
- c) The row space of  $A$  equals the row space of  $A^T A$ .
- d) If  $A$  has linearly independent columns then  $A^+ A$  is the identity matrix.

**Solution.**

a) Say  $A^T A \mathbf{v} = \lambda \mathbf{v}$ . Set  $\mathbf{u} = A \mathbf{v}$ ; this is not zero because  $A^T \mathbf{u} = A^T A \mathbf{v} = \lambda \mathbf{v} \neq 0$ . Then

$$AA^T \mathbf{u} = AA^T A \mathbf{v} = A(A^T A \mathbf{v}) = A(\lambda \mathbf{v}) = \lambda A \mathbf{v} = \lambda \mathbf{u},$$

so  $\mathbf{u}$  is an eigenvector of  $AA^T$  with eigenvalue  $\lambda$ .

b) The characteristic polynomial  $p(\lambda)$  has roots at  $\pm 1$ . Since  $p(\lambda)$  has degree 3, it has a third root  $\lambda$ ; since complex roots of  $p$  come in conjugate pairs,  $\lambda$  must be real. Since  $\pm 1$  have algebraic multiplicity one,  $\lambda \neq \pm 1$ , so  $A$  has three distinct eigenvalues, hence is diagonalizable.

c) The null space of  $A^T A$  is equal to  $N(A)$ . The row space of  $A^T A$  is the orthogonal complement of  $N(A^T A) = N(A)$ , as is the row space of  $A^T A$ .

d) Since  $A$  has linearly independent columns, its null space is zero, so its row space is all of  $\mathbf{R}^n$ . But  $A^+ A$  is the projection onto the row space of  $A$ , and the projection onto all of  $\mathbf{R}^n$  is the identity.

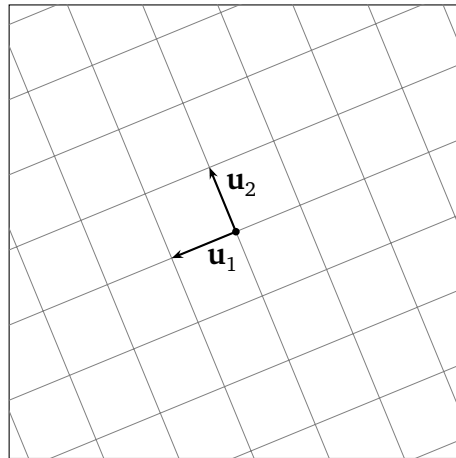
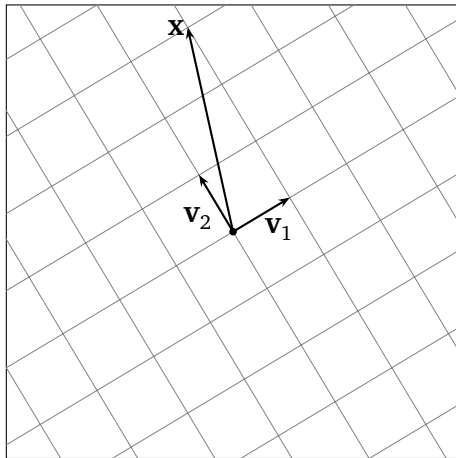
## Problem 6.

[8 points]

A certain  $2 \times 2$  matrix  $A$  has the singular value decomposition

$$A = \begin{pmatrix} | & | \\ \mathbf{u}_1 & \mathbf{u}_2 \\ | & | \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} | & | \\ \mathbf{v}_1 & \mathbf{v}_2 \\ | & | \end{pmatrix}^T,$$

where  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{v}_1, \mathbf{v}_2$  are drawn in the diagrams below. Given  $\mathbf{x}$  in the diagram on the left, draw  $A\mathbf{x}$  on the diagram on the right.



**Solution.**

We have  $\mathbf{x} = \mathbf{v}_1 + 3\mathbf{v}_2$ . The way the SVD works, we have  $A\mathbf{v}_1 = 2\mathbf{u}_1$  and  $A\mathbf{v}_2 = 0$ , so

$$A\mathbf{x} = A\mathbf{v}_1 + 3A\mathbf{v}_2 = 2\mathbf{u}_1.$$

