

Homework #3

due Tuesday, September 8, at 11:59pm

1. Express each system of linear equations as a vector equation. For example,

$$\begin{array}{r} x_1 + 2x_2 = 3 \\ -x_1 - x_2 = 4 \end{array} \rightsquigarrow x_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} + x_2 \begin{pmatrix} 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}.$$

a)
$$\begin{array}{r} 3x_1 + 2x_2 + 4x_3 = 9 \\ -x_1 + 4x_3 = 2 \end{array}$$

b)
$$\begin{pmatrix} 3 & -5 \\ 2 & 4 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$$

c)
$$\left(\begin{array}{cccc|c} 1 & 0 & 1 & 1 & 2 \\ 0 & 3 & -1 & -2 & 4 \\ 1 & -3 & -4 & -3 & 2 \\ 6 & 5 & -1 & -8 & 1 \end{array} \right)$$

2. For each matrix A and vector b , find the parametric form of the general solution of $Ax = b$. For instance,

$$\begin{pmatrix} 1 & -1 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \rightsquigarrow x_1 = x_2 + 1.$$

Also answer the following questions: Which variables are free? How many solutions does the system have?

a)
$$A = \begin{pmatrix} 2 & 1 & 1 & 4 \\ 4 & 2 & 1 & 7 \end{pmatrix} \quad b = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

b)
$$A = \begin{pmatrix} 2 & 2 & -1 \\ -4 & -5 & 5 \\ 6 & 1 & 12 \end{pmatrix} \quad b = \begin{pmatrix} 3 \\ 2 \\ 49 \end{pmatrix}$$

c)
$$A = \begin{pmatrix} 2 & 2 & -1 \\ -4 & -5 & 5 \\ 6 & 1 & 12 \end{pmatrix} \quad b = \begin{pmatrix} 3 \\ 2 \\ 48 \end{pmatrix}$$

d)
$$A = \begin{pmatrix} 1 & 2 & 3 & -1 & 1 \\ -2 & -4 & -5 & 4 & 1 \\ 1 & 2 & 2 & -3 & -1 \\ -3 & -6 & -7 & 7 & 6 \end{pmatrix} \quad b = \begin{pmatrix} 2 \\ 4 \\ -6 \\ 10 \end{pmatrix}$$

e)
$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} \quad b = \begin{pmatrix} 2 \\ 5 \\ 4 \end{pmatrix}$$

3. For each matrix A and vector b in Problem 2, find the parametric *vector* form of the general solution of $Ax = b$, and express the solution set in the form

$$\text{Span}\{???\} + p$$

for some vector p . For instance,

$$\begin{pmatrix} 1 & -1 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\rightsquigarrow \text{soln set} \quad \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} + \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

4. For each matrix A in Problem 2, determine if the homogeneous equation $Ax = 0$ has a nontrivial solution. If it does, write the solution set of $Ax = 0$ as a span.
5. Find values of a and b such that the following system has **a)** zero **b)** one **c)** infinitely many solutions.

$$\begin{aligned} 2x + ay &= 4 \\ x - y &= b \end{aligned}$$

6. The equation $x + 2y = z$ determines a plane in \mathbf{R}^3 . (This is an *implicit equation* for the plane).
- What is the coefficient matrix A for this system?
 - Which are the free variables?
 - Write the parametric form of the solutions of $x + 2y = z$. This expresses the points on the plane in terms of two *parameters*.
 - Do the same for the plane defined by $2y = z$. What is different?
7. Give examples of matrices A in reduced row echelon form for which the number of solutions of $Ax = b$ is:
- 0 or 1, depending on b
 - ∞ for every b
 - 0 or ∞ , depending on b
 - 1 for every b .

Is there a square matrix satisfying **b)**? Why or why not?

8. a) Is $\begin{pmatrix} 3 \\ 2 \\ 49 \end{pmatrix}$ in $\text{Span} \left\{ \begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} \right\}$?

If so, express $\begin{pmatrix} 3 \\ 2 \\ 49 \end{pmatrix}$ as a linear combination of $\begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix}$.

[Hint: compare Problem 2.]

b) Find a vector that is *not* in the span of the columns of $\begin{pmatrix} 2 & 2 & -1 \\ -4 & -5 & 5 \\ 6 & 1 & 12 \end{pmatrix}$.

9. Describe and compare (geometrically) the solution sets of the following systems:

$$\begin{cases} 2x_1 + x_2 + x_3 = 1 \\ 4x_1 + 2x_2 + x_3 = 1 \end{cases} \quad \begin{cases} 2x_1 + x_2 + x_3 = 2 \\ 4x_1 + 2x_2 + x_3 = 0. \end{cases}$$

10. Decide if each statement is true or false, and explain why.

- A square matrix has no free variables.
- An invertible matrix has no free variables.
- An $m \times n$ matrix has at most m pivots.
- A wide matrix (more columns than rows) must have a free variable.
- If A is a tall matrix (more rows than columns), then $Ax = b$ has at most one solution.

11. Let A be a 4×5 matrix with four pivots. Suppose that

$$(\text{column } 1) + 2(\text{column } 3) - (\text{column } 4) = 0.$$

- Find a nonzero solution of $Ax = 0$.
- Which is the free variable?

[Hint: the solutions of $Ax = 0$ are unchanged by Gauss–Jordan elimination.]

12. When is the following system consistent?

$$\begin{aligned} 2x_1 + 2x_2 - x_3 &= b_1 \\ -4x_1 - 5x_2 + 5x_3 &= b_2 \\ 6x_1 + x_2 + 12x_3 &= b_3 \end{aligned}$$

Your answer should be a single linear equation in b_1, b_2, b_3 . Explain the relationship between this equation and

$$\text{Span} \left\{ \begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} \right\}.$$

13. Find a 2×3 matrix A in RREF and a vector b such that the solution set of $Ax = b$ consists of all vectors of the form

$$\begin{pmatrix} 1+t \\ 2-t \\ t \end{pmatrix} \quad t \in \mathbf{R}.$$

14. Suppose that A is a 3×3 matrix and b is a vector such that $Ax = b$ is a line in \mathbf{R}^3 . How many pivots does A have?

15. Suppose that A is a 2×3 matrix such that

$$A \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad \text{and} \quad A \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}.$$

a) Find two different solutions of $Ax = 0$.

b) Find two more solutions of $Ax = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$.

16. Suppose that $Ax = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ has infinitely many solutions. Is it possible for $Ax = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$ to have exactly one solution? How about zero solutions?

17. Suppose that $Ax = b$ is consistent. Explain why $Ax = b$ has a unique solution precisely when $Ax = 0$ has only the trivial solution.

18. List five different vectors in $\text{Span}\{x, y\}$, where

$$x = \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} \quad y = \begin{pmatrix} -2 \\ 3 \\ -1 \end{pmatrix}.$$

19. Give geometric descriptions of the following spans.

a) $\text{Span} \left\{ \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} \right\}$ b) $\text{Span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix} \right\}$ c) $\text{Span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ -6 \end{pmatrix} \right\}$

d) $\text{Span} \left\{ \begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} \right\}$ e) $\text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \right\}$

[Hint: for d), compare Problem 12.]

20. Decide if each statement is true or false, and explain why.

a) A vector b is a linear combination of the columns of A if and only if $Ax = b$ has a solution.

b) If $Ax = b$ has no solutions, then A does not have a pivot in every row.

c) The zero vector is contained in every span.

d) The matrix equation $Ax = 0$ can be consistent or inconsistent, depending on what A is.

e) If the zero vector is a solution of a system of equations, then the system is homogeneous.

f) If $Ax = b$ has a unique solution, then A has a pivot in every column.

g) If $Ax = b$ is consistent, then the solution set of $Ax = b$ is obtained by translating the solution set of $Ax = 0$.

h) It is possible for $Ax = b$ to have exactly 13 solutions.