

# Linear Independence

HW #3.12:

$\text{Span}\left\{\begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix}\right\}$  is the plane  $-13b_1 - 5b_2 + b_3 = 0$

But, if you solve  $Ax=0$  in  $\mathbb{R}^3$ , 3 parameters  $\Rightarrow$  null space is "space" (3-dimensional). What's the difference? They're coplanar!

$$\begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} = \frac{5}{2} \begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix} - 3 \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}$$

So want a notion of "some vector is a linear combo of the others." Which one?

$$\begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix} = \frac{2}{5} \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} + \frac{6}{5} \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix} = -\frac{1}{3} \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} + \frac{5}{6} \begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix}$$

**Def:** A set of vectors  $\{v_1, \dots, v_n\}$  is linearly dependent (LD) if the homogeneous vector equation

$$x_1 v_1 + x_2 v_2 + \dots + x_n v_n = 0$$

has a nontrivial solution. Such a solution is a linear dependence relation.

**Eg:**  $5 \begin{pmatrix} 2 \\ -4 \\ 6 \end{pmatrix} - 6 \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix} - \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} = 0$

is a linear dependence relation.

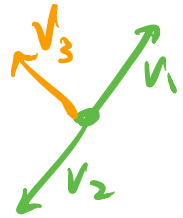
Given a linear dependence relation  $x_1 v_1 + x_2 v_2 + x_3 v_3 = 0$

nontrivial  $\Rightarrow$  some  $x_i \neq 0$ . Suppose  $x_1 \neq 0$ . Then  
 $v_1 = \frac{1}{x_1}(x_2 v_2 + x_3 v_3) \Rightarrow v_1 \in \text{Span}\{v_2, v_3\}$

**LD:** some vector is in the span of the others.

**NB:** this doesn't say every vector  
 $\ni$  in the span of the others!

$$v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad v_2 = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \quad v_3 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$



Linear dependence relation:  $v_1 + v_2 + 0v_3 = 0$   
 $\leadsto v_1 = -v_2 \in \text{Span}\{v_2, v_3\}$

**Def:** A set of vectors  $\{v_1, \dots, v_n\}$  is linearly independent (LI)  
if it's not linearly dependent, i.e.,

$$x_1 v_1 + x_2 v_2 + \dots + x_n v_n = 0$$

has only the trivial solution.

**LI:** no vector is in the span of the others.

A set of vectors is LI  
if its span is as big as  
you expect it to be.

i.e.  
1 vector  $\rightsquigarrow$  line  
2 vectors  $\rightsquigarrow$  plane  
3 vectors  $\rightsquigarrow$  space etc.

Eg: Are

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}, \begin{pmatrix} 7 \\ 8 \\ 10 \end{pmatrix} \quad \text{LI?}$$

Need to solve  $x_1 \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + x_2 \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} + x_3 \begin{pmatrix} 7 \\ 8 \\ 10 \end{pmatrix} = 0$

$$\rightsquigarrow \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 10 \end{pmatrix} x = 0 \quad \xrightarrow{\text{REF}} \begin{pmatrix} 1 & 4 & 7 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

No free vars  $\Rightarrow$  no nontrivial solns  $\Rightarrow$  LI.

**NB:** If  $Ax=0$  has a nontrivial solution  $(x_1, \dots, x_n)$

$\Rightarrow x_1 v_1 + \dots + x_n v_n = 0$  is a linear dependence relation.

$$A = \begin{pmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{pmatrix}$$

**Matrix interpretation:**

A has **LI columns**

$\Leftrightarrow Ax=0$  has only the trivial soln

$\Leftrightarrow \text{Nul}(A) = \{0\}$

$\Leftrightarrow A$  has **full column rank**.

**Language:** LI/LD are adjectives that describe a **set of vectors**.

**Bad:** "A is LI" "  $v_1$  is LD on  $v_2$  &  $v_3$ "

**Good:** "A has LI columns" " $\{v_1, v_2, v_3\}$  is LD"

Eg:  $\bullet \{v\}$  is LI  $\Leftrightarrow v \neq 0$

$\bullet$  Any set containing  $0$  is LD: if  $v_i = 0 \Rightarrow$

$$1v_1 + 0v_2 + \dots + 0v_n = 0 \quad \text{LDR}$$

- $\{v_1, v_2\}$  is LD  $\Leftrightarrow v_1 \in \text{Span}\{v_2\}$  or  $v_2 \in \text{Span}\{v_1\}$   
 $\Leftrightarrow v_1, v_2$  collinear  
 $\Leftrightarrow \text{Span}\{v_1, v_2\}$  is a **line** (or  $\{0\}$ )
- Similarly,  $\{v_1, v_2, v_3\}$  LD  $\Leftrightarrow$  **coplanar**

## Basis

**Like:** writing a subspace  $V$  as  $\text{Span}\{v_1, v_2, v_3\}$ :  
any vector in  $V$  is  $v = x_1v_1 + x_2v_2 + x_3v_3$

**Don't like:** This expression can be non-unique!  
 $0 = x_1v_1 + x_2v_2 + x_3v_3$  can have nontrivial solns.

This happens if you used too many vectors  
(eg. 3 vectors to span a plane).

**Def:** A **basis** for a subspace  $V$  is a set of vectors  $\{v_1, \dots, v_d\}$  in  $V$  satisfying:

(1)  $V = \text{Span}\{v_1, \dots, v_d\}$

(2)  $\{v_1, \dots, v_d\}$  is LI

"spans & is LI"

**Spans:** every vector in  $V$  can be written  
 $v = x_1v_1 + \dots + x_dv_d$

**LI:** this expression is **unique**: only one choice of  $(x_1, \dots, x_d)$

**Why?**  $A = \begin{pmatrix} | & & | \\ v_1 & \dots & v_d \\ | & & | \end{pmatrix}$  then  $A \begin{pmatrix} x_1 \\ \vdots \\ x_d \end{pmatrix} = v$

has **one** solution. (**Zero** solns:  $v \notin V$ )

Basis  $\{v_1, \dots, v_d\}$

makes  $V \in \mathbb{R}^d$  "look like"

$$\begin{pmatrix} x_1 \\ \vdots \\ x_d \end{pmatrix}$$

$$\iff x_1 v_1 + \dots + x_d v_d$$

Def: The **unit coordinate vectors** are the columns of  $I_n$ :

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots,$$

$$e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$$

Eg:  $\{e_1, \dots, e_n\}$  is a basis for  $\mathbb{R}^n$

Spans:  $\begin{pmatrix} a \\ b \\ c \end{pmatrix} = a \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  ✓

LI:  $I_n$  has full column rank ✓

Bases of  $\mathbb{R}^n$ : Suppose the columns of  $A$  form a basis of  $\mathbb{R}^n$ . Let  $r = \text{rank}$ .

(1) span:  $\text{Col}(A) = \mathbb{R}^n \iff$  full row rank  $r = m$

(2) LI:  $\text{Nul}(A) = \{0\} \iff$  full col rank  $r = n$

So  $r = m = n$  so  $A$  is invertible.

Basis for  $\mathbb{R}^n$



columns of an invertible matrix

## Notes:

- $\mathbb{R}^n$  has many bases:  
eg.  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$ ,  $\left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 4 \end{pmatrix} \right\}$ , ...
- Every basis of  $\mathbb{R}^n$  has  $n$  vectors.

True for any subspace.  $\rightsquigarrow$  dimension