

Cofactor Expansion

This is a handy **recursive** formula for $\det(A)$.

Def: Let A be an $n \times n$ matrix.

- The (i,j) **minor** A_{ij} is obtained by deleting the i^{th} row & j^{th} column of A . $(n-1) \times (n-1)$ matrix
- The (i,j) **cofactor** C_{ij} is
$$C_{ij} = (-1)^{i+j} \det(A_{ij}).$$
- The **cofactor matrix** is the matrix C whose (i,j) entry is C_{ij} .

Eg: $A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 3 \end{pmatrix}$ $A_{21} = \begin{pmatrix} 1 & 0 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & 3 \end{pmatrix}$
 $C_{21} = (-1)^{2+1} \det \begin{pmatrix} 1 & 0 \\ 1 & 3 \end{pmatrix} = -3$

NB: $(-1)^{i+j}$ follows this pattern:

$$\begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$$

Thm (Cofactor Expansion):

Let $A = (a_{ij})$ be an $n \times n$ matrix, C_{ij} = cofactors

(1) **Cofactor expansion along the i^{th} row:**

$$\det(A) = a_{i1}C_{i1} + a_{i2}C_{i2} + \dots + a_{in}C_{in}$$

(1) **Cofactor expansion along the j^{th} column:**

$$\det(A) = a_{1j}C_{1j} + a_{2j}C_{2j} + \dots + a_{nj}C_{nj}$$

Eg: $A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 3 \end{pmatrix}$

Expand along the 3rd row:

$$\det(A) = 0 \cdot \det \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} - 1 \det \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} + 3 \det \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$$

$$= 0 - 1(1) + 3(2-1) = -1 + 3 = 2 \quad \checkmark$$

Expand along 1st column:

$$\det(A) = 1 \cdot \det \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} - 1 \det \begin{pmatrix} 1 & 0 \\ 1 & 3 \end{pmatrix} + 0 \det \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$$

$$= 1(6-1) - 1(3) + 0 = 5 - 3 = 2 \quad \checkmark$$

Remarks:

- (1) This is a recursive formula: $C_{ij} = \det((n-1) \times (n-1))$
- (2) You can calculate $C_{ij} = (-1)^{i+j} \det(A_{ij})$ using any method you like — you'll always get the same number.
- (3) Expanding along any row/column gives you the determinant — same number!
- (4) This is handy when A has unknown entries or if there's a row or column with lots of zeros. (Otherwise ridiculously inefficient: $O(n! \cdot n)$)

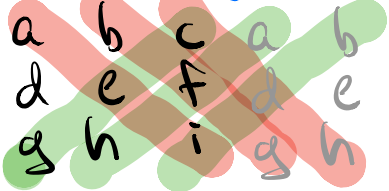
Eg: $\det \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} = a \det \begin{pmatrix} e & f \\ h & i \end{pmatrix} - b \det \begin{pmatrix} d & f \\ g & i \end{pmatrix} + c \det \begin{pmatrix} d & e \\ g & h \end{pmatrix}$

$$= a(ei - fh) - b(di - fg) + c(dh - ge)$$

$$= aei + bfg + cdh - afh - bdi - ceg$$

How to remember this?

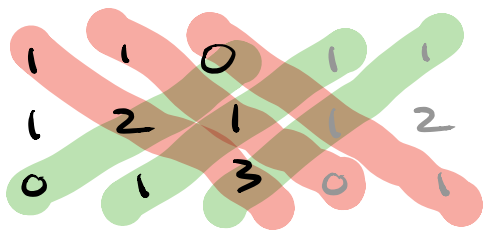
Sarrus' Scheme:



To compute $\det(3 \times 3 \text{ matrix})$:

$$\det = aei + bfg + cdh - ceg - afh - bdi$$

Eg:



$$\begin{aligned} \det &= 1 \cdot 2 \cdot 3 + 1 \cdot 1 \cdot 0 + 0 \cdot 1 \cdot 1 \\ &\quad - 0 \cdot 2 \cdot 0 - 1 \cdot 1 \cdot 1 - 3 \cdot 1 \cdot 1 \\ &= 6 + 1 - 3 = 2 \quad \checkmark \end{aligned}$$

Warning: This only works for 3×3 matrices!

Eg:

$$\det \begin{pmatrix} 2 & 5 & -3 & -2 \\ -2 & -3 & 2 & -5 \\ 1 & 3 & -2 & 0 \\ -1 & 6 & 4 & 0 \end{pmatrix}$$

column with
lots of zeros

$$\begin{aligned} &= -(-2) \det \begin{pmatrix} -2 & -3 & 2 \\ 1 & 3 & -2 \\ -1 & 6 & 4 \end{pmatrix} - 5 \det \begin{pmatrix} 2 & 5 & -3 \\ 1 & 3 & -2 \\ -1 & 6 & 4 \end{pmatrix} \\ &\quad - 0 \cdot \det \begin{pmatrix} \text{don't} \\ \text{care} \end{pmatrix} + 0 \det \begin{pmatrix} \text{don't} \\ \text{care} \end{pmatrix} \end{aligned}$$

$$= 2(-24) - 5(11) = -48 - 55 = -103$$

only computed
two 3×3 dets

Methods for Computing Determinants

(1) **Special formulas** (2×2 , 3×3)

→ best for small matrices, except 3×3 with lots of 0's

(2) **Cofactor expansion**

→ best if you have unknown entries, or a row/column with lots of zeros.

(3) **Row (& column) operations**

→ best if you have a big matrix with no unknown entries & no row or column with lots of zeros.

(4) **Any combination of the above**

→ eg. do a row op. to create a column with lots of zeros, then expand cofactors, ...

Thm: Let C be the cofactor matrix of A . Then

$$AC^T = \det(A) I_n = C^T A$$

In particular, if $\det(A) \neq 0$, then

$$A^{-1} = \frac{1}{\det(A)} C^T \quad \text{see supplement}$$

→ Ridiculously inefficient computationally.

Eg: $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow A^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$

→ generalizes the formula for 2×2 inverse

Cross Products

This is a trick for vectors in \mathbb{R}^3 . $e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ $e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ $e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

Def: If $v = (a \ b \ c)$, $w = (d \ e \ f)$ then

$$v \times w = \text{"det"} \begin{pmatrix} e_1 & e_2 & e_3 \\ a & b & c \\ d & e & f \end{pmatrix} = (bf - ed)e_1 - (af - cd)e_2 + (ae - bd)e_3$$

is their
cross product.

$$= \begin{pmatrix} bf - ed \\ cd - af \\ ae - bd \end{pmatrix} \in \mathbb{R}^3$$

Eg: $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \text{"det"} \begin{pmatrix} e_1 & e_2 & e_3 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$

Def: For $u, v, w \in \mathbb{R}^3$ their triple product is

$$u \cdot (v \times w) = \text{det} \begin{pmatrix} -u^T & - \\ -v^T & - \\ -w^T & - \end{pmatrix}$$

→ another formula for $\text{det}(3 \times 3)$.

Eg: $u = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ $v = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ $w = \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}$

$$v + w = \text{"det"} \begin{pmatrix} e_1 & e_2 & e_3 \\ 1 & 2 & 1 \\ 0 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 5 \\ -3 \\ 1 \end{pmatrix}$$

$$u \cdot (v + w) = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 5 \\ -3 \\ 1 \end{pmatrix} = 5 - 3 = 2 = \text{det} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 3 \end{pmatrix} \checkmark$$

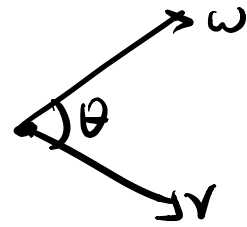
Properties:

(1) $v \times w \perp v, v \times w \perp w$

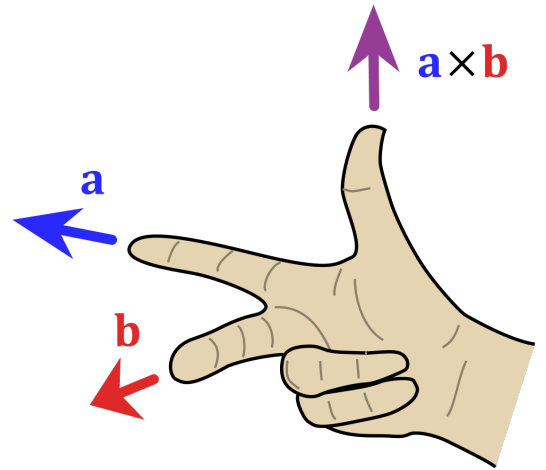
$\rightarrow v \cdot (v \times w) = \det \begin{pmatrix} -v^T & - \\ -v^T & - \\ -w^T & - \end{pmatrix} = 0$

(2) $\|v \times w\| = \|v\| \cdot \|w\| \cdot \sin(\theta)$

\rightarrow compare $\|v \cdot w\| = \|v\| \cdot \|w\| \cos(\theta)$



(3) $v \times w$ points in the direction determined by the **right hand rule**.



(1)-(3) characterize $v \times w$

(4) $v \times w = 0 \iff v, w$ are collinear

$\rightarrow \theta = 0^\circ, 180^\circ \Rightarrow \sin(\theta) = 0$

(5) $w \times v = -v \times w$

$\rightarrow \det \begin{pmatrix} e_1 & e_2 & e_3 \\ - & w^T & - \\ - & v^T & - \end{pmatrix} = -\det \begin{pmatrix} e_1 & e_2 & e_3 \\ - & v^T & - \\ - & w^T & - \end{pmatrix}$