

## Math 218D Problem Session

Week 3

### 1. Making some examples

a)  $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$

b)  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$

c)  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

d)  $A = \begin{pmatrix} 1 & 0 \\ 2 & 0 \\ 3 & 0 \end{pmatrix}$  has 1 pivot.  $A = \begin{pmatrix} 1 & 1 \\ 2 & 0 \\ 3 & 0 \end{pmatrix}$  has 2 pivots.

e)  $A = \begin{pmatrix} 1 & 1 \\ 2 & 0 \\ 3 & -1 \end{pmatrix}$ .  $b = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$  would work, as would any vector  $b$  such that

$$b_1 - 2b_2 + b_3 \neq 0.$$

f)  $A = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}$

g) There is no  $2 \times 3$  matrix with full column rank. Any  $2 \times 3$  matrix with full row rank (2 pivots) is always consistent, so we can't find one such that  $Ax = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  is inconsistent.

## 2. Parametric forms

a) The RREF is  $\left( \begin{array}{ccc|c} 1 & 0 & 1/3 & 1/3 \\ 0 & 1 & 2/3 & -1/3 \\ 0 & 0 & 0 & 0 \end{array} \right)$

b) The parametric form of the solution is:

$$\begin{aligned}x_1 &= -\frac{1}{3}x_3 + \frac{1}{3} \\x_2 &= -\frac{2}{3}x_3 - \frac{1}{3} \\x_3 &= x_3\end{aligned}$$

Setting  $x_3 = 0$  gives one solution:  $(x_1, x_2, x_3) = (1/3, -1/3, 0)$ . Setting  $x_3 = 1$  gives another solution  $(x_1, x_2, x_3) = (0, -1, 1)$ .

c) The parametric vector form is:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = x_3 \cdot \begin{pmatrix} -1/3 \\ -2/3 \\ 1 \end{pmatrix} + \begin{pmatrix} 1/3 \\ -1/3 \\ 0 \end{pmatrix}.$$

d) The line passes through the point  $(1/3, -1/3, 0)$ , and goes in the direction of the vector  $(-1/3, -2/3, 1)$ .

e) This system of equations has no solutions.

f) The parametric vector form of this system is

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = x_3 \cdot \begin{pmatrix} -1/3 \\ -2/3 \\ 1 \end{pmatrix}.$$

The solution to the homogeneous equation is a line, parallel to the line from part d), passing through the origin.

g) A vector  $b = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$  makes  $Ax = b$  consistent precisely when  $-b_1 + b_2 - b_3 = 0$ .

h) The span of these vectors is the same as the set of vectors making  $Ax = b$  consistent. By g), this is the same as the vectors which satisfying a single linear equation. The set of vectors satisfying a single linear equation is a plane.

### 3. The geometry of spans

a) No, it is not possible. You can confirm this by computing the RREF of  $\left(\begin{array}{cc|c} 1 & 1 & 1 \\ -1 & -1 & 1 \\ 5 & 1 & 0 \end{array}\right)$ .

Alternately, you could observe that the first two components of  $\begin{pmatrix} 1 \\ -1 \\ 5 \end{pmatrix}$  and

$\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$  add up to 0, while the first two components of  $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$  do not.

b) It is all of  $\mathbf{R}^3$ , since  $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$  is not contained in the plane  $\text{Span}\left\{\begin{pmatrix} 1 \\ -1 \\ 5 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}\right\}$  (using 3a)).

c) By computing the REF of  $\left(\begin{array}{cc|c} 1 & 1 & b_1 \\ -1 & -1 & b_2 \\ 5 & 1 & b_3 \end{array}\right)$ , we confirm that the vectors  $b = (b_1, b_2, b_3)$  which make

$$\begin{pmatrix} 1 & 1 \\ -1 & -1 \\ 5 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

consistent are precisely those where  $b_1 + b_2 = 0$ . This means that the plane parametrized by

$$x_1 \begin{pmatrix} 1 \\ -1 \\ 5 \end{pmatrix} + x_2 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

has equation

$$x + y = 0.$$

d) Yes, you can find scalars  $x_1, x_2$  so that

$$x_1 \begin{pmatrix} 1 \\ -1 \\ 5 \end{pmatrix} + x_2 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ -4 \\ 0 \end{pmatrix},$$

since  $(4, -4, 0)$  solves the equation  $x + y = 0$  found in 3c).

e) The vectors  $\begin{pmatrix} 1 \\ -1 \\ 5 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$  are not parallel, so they span a plane. The third vector  $\begin{pmatrix} 4 \\ -4 \\ 0 \end{pmatrix}$  is contained in that plane by 3d), so adding it to the list of vectors does not enlarge the span.