

From last time:

Thm (SVD, outer product form):

Let A be an $m \times n$ matrix of rank r . Then

$$A = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_r u_r v_r^T$$

where

- $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$
- $\{u_1, \dots, u_r\}$ is an orthonormal set in $\mathbb{R}^m$
- $\{v_1, \dots, v_r\}$ is an orthonormal set in $\mathbb{R}^n$.

To compute:

- $\lambda_1 \geq \dots \geq \lambda_r > 0$ are the nonzero eigenvalues of $A^T A$
- $\{v_1, \dots, v_r\}$ are orthonormal eigenvectors, $A^T A v_i = \lambda_i v_i$
- $\sigma_i = \sqrt{\lambda_i}$, $u_i = \frac{1}{\sigma_i} A v_i$

SVD of A^T :

$$A^T = \sigma_1 v_1 u_1^T + \sigma_2 v_2 u_2^T + \dots + \sigma_r v_r u_r^T$$

NB: If A is a wide matrix ($m < n$) then

$A^T A$: $n \times n$ $A A^T$: $m \times m$ is smaller

So it's easier to compute eigenvalues & eigenvectors of $A A^T$!

If A is wide, compute the SVD of A^T .

Eg: $A = \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix}$

$$A^T A = \begin{pmatrix} 200 & -50 & 200 & -50 \\ -50 & 125 & -50 & 125 \\ 200 & -50 & 200 & -50 \\ -50 & 125 & -50 & 125 \end{pmatrix} \quad \text{yikes!}$$

Let's compute the SVD of A^T instead.

$$A A^T = \begin{pmatrix} 400 & -100 \\ -100 & 250 \end{pmatrix} \quad \rho(\lambda) = (\lambda - 450)(\lambda - 200)$$

$$\lambda_1 = 450 \Rightarrow \sigma_1 = \sqrt{450} = 15\sqrt{2} \quad u_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad v_1 = \frac{1}{\sigma_1} A^T u_1 = \frac{1}{\sqrt{10}} \begin{pmatrix} -2 \\ 1 \\ -2 \\ 1 \end{pmatrix}$$

$$\lambda_2 = 200 \Rightarrow \sigma_2 = \sqrt{200} = 10\sqrt{2} \quad u_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad v_2 = \frac{1}{\sigma_2} A^T u_2 = \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ 2 \\ 1 \\ 2 \end{pmatrix}$$

$$\Rightarrow A^T = 15\sqrt{2} v_1 u_1^T + 10\sqrt{2} v_2 u_2^T$$

$$\Rightarrow A = 15\sqrt{2} u_1 v_1^T + 10\sqrt{2} u_2 v_2^T$$

↘ u_i are right-singular vectors of $A^T \rightsquigarrow$ left-singular vectors of A

SVD: Matrix Form

Let

$$A = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_r u_r v_r^T$$

be the SVD of A in outer product form.

Facts:

- (1) $\{u_1, \dots, u_r\}$ is an orthonormal basis for $\text{Col}(A)$
- (2) $\{v_1, \dots, v_r\}$ is an orthonormal basis for $\text{Row}(A)$

Proof: • $u_i = A \cdot \frac{1}{\sigma_i} v_i \Rightarrow u_i \in \text{Col}(A)$

• $\{u_1, \dots, u_r\}$ is orthonormal $\Rightarrow$ linearly independent

• $\dim(\text{Col}(A)) = \text{rank} = r$

• Basis theorem $\Rightarrow \{u_1, \dots, u_r\}$ is a basis for $\text{Col}(A)$.

Fact (2) follows by replacing A by A^T .



Let $\{u_{r+1}, \dots, u_m\}$ be an orthonormal basis for $\text{Nul}(A^T)$

$\hookrightarrow \{u_1, \dots, u_r, u_{r+1}, \dots, u_m\}$ is an orthonormal basis of $\mathbb{R}^m$

$\hookrightarrow$ it's also an orthonormal eigenbasis for AA^T

$(\text{Nul}(A^T) = \text{Nul}(AA^T) = 0\text{-eigenspace of } AA^T)$

Let $\{v_{r+1}, \dots, v_n\}$ be an orthonormal basis for $\text{Nul}(A)$

$\hookrightarrow \{v_1, \dots, v_r, v_{r+1}, \dots, v_n\}$ is an orthonormal basis of $\mathbb{R}^n$

$\hookrightarrow$ it's also an orthonormal eigenbasis for $A^T A$

$(\text{Nul}(A) = \text{Nul}(A^T A) = 0\text{-eigenspace of } A^T A)$

Thm (SVD, Matrix Form):

Let A be an $m \times n$ matrix of rank r . Then

$$A = U \Sigma^T V^T \quad \text{where:}$$

• $U = \begin{pmatrix} | & & | \\ u_1 & \dots & u_m \\ | & & | \end{pmatrix}$ is an $m \times m$ orthogonal matrix

• $V = \begin{pmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{pmatrix}$ is an $n \times n$ orthogonal matrix

• $\Sigma = \begin{pmatrix} \sigma_1 & \dots & 0 \\ & \ddots & \\ 0 & \sigma_r & 0 \dots 0 \end{pmatrix}$ is an $m \times n$ diagonal matrix.

$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$ are the singular values

Procedure to Compute $A = U\Sigma V^T$:

(1) Compute the singular values and singular vectors
 $\{v_1, \dots, v_r\}$ $\{u_1, \dots, u_r\}$ $\sigma_1, \dots, \sigma_r$

as before

(2) Find orthonormal bases

$\{u_{r+1}, \dots, u_m\}$ for $\text{Nul}(A^T)$

$\{v_{r+1}, \dots, v_n\}$ for $\text{Nul}(A)$

$$(3) \quad U = \begin{pmatrix} | & \dots & | & | & \dots & | \\ u_1 & \dots & u_r & u_{r+1} & \dots & u_m \\ | & \dots & | & | & \dots & | \end{pmatrix} \quad V = \begin{pmatrix} | & \dots & | & | & \dots & | \\ v_1 & \dots & v_r & v_{r+1} & \dots & v_n \\ | & \dots & | & | & \dots & | \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} \sigma_1 & \dots & \sigma_r & 0 & \dots & 0 \\ & \ddots & & & \ddots & \\ 0 & \dots & 0 & \sigma_{r+1} & \dots & 0 \end{pmatrix} \quad (\text{same size as } A)$$

Proof: Use the outer product version of matrix mult:

$$U\Sigma V^T = \begin{pmatrix} | & \dots & | \\ u_1 & \dots & u_m \\ | & \dots & | \end{pmatrix} \begin{pmatrix} \sigma_1 & \dots & \sigma_r & 0 & \dots & 0 \\ & \ddots & & & \ddots & \\ 0 & \dots & 0 & \sigma_{r+1} & \dots & 0 \end{pmatrix} \begin{pmatrix} -v_1- \\ \vdots \\ -v_n- \end{pmatrix}$$

$$= \begin{pmatrix} | & \dots & | \\ u_1 & \dots & u_m \\ | & \dots & | \end{pmatrix} \begin{pmatrix} -\sigma_1 u_1- \\ \vdots \\ -\sigma_r u_r- \\ \vdots \\ -0- \end{pmatrix}$$

$$= \sigma_1 u_1 v_1^T + \dots + \sigma_r u_r v_r^T + 0 + \dots + 0$$



Eg: $A = \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix}$

(1) $A = 15\sqrt{2} u_1 v_1^T + 10\sqrt{2} u_2 v_2^T$ for

$$u_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad v_1 = \frac{1}{\sqrt{10}} \begin{pmatrix} -2 \\ 1 \\ -2 \\ 1 \end{pmatrix}$$

$$u_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad v_2 = \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ 2 \\ 1 \\ 2 \end{pmatrix}$$

(2) $\text{Nul}(A^T) = \{0\}$ because $r=m$

$$\text{Nul}(A): \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} \xrightarrow{\text{ref}} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{\text{PVE}} \text{Span} \left\{ \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

[already
orthogonal -
usually need
Gram-Schmidt]

$$\xrightarrow{\text{normalize}} v_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \quad v_4 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}$$

(3) So $A = U \Sigma V^T$ for

$$U = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 15\sqrt{2} & 0 & 0 & 0 \\ 0 & 10\sqrt{2} & 0 & 0 \end{pmatrix}$$

$$V = \begin{pmatrix} -2/\sqrt{10} & 1/\sqrt{10} & -1/\sqrt{2} & 0 \\ 1/\sqrt{10} & 2/\sqrt{10} & 0 & -1/\sqrt{2} \\ -2/\sqrt{10} & 1/\sqrt{10} & 1/\sqrt{2} & 0 \\ 1/\sqrt{10} & 2/\sqrt{10} & 0 & 1/\sqrt{2} \end{pmatrix}$$

NB: $A = U \Sigma^T V^T$ contains full orthogonal diagonalizations of $A^T A$ and of $A A^T$:

$$A^T A = V \begin{pmatrix} \sigma_1^2 & & & 0 \\ & \ddots & & \\ & & \sigma_r^2 & \\ 0 & & & 0 \end{pmatrix} V^T \quad A A^T = U \begin{pmatrix} \sigma_1^2 & & & 0 \\ & \ddots & & \\ & & \sigma_r^2 & \\ 0 & & & 0 \end{pmatrix} U^T$$

It also contains orthonormal bases for all four subspaces:

$$U = \left(\begin{array}{c|c} \text{o.n. basis for Col}(A) & \text{o.n. basis for Nul}(A^T) \\ \hline u_1 & u_{r+1} \\ \vdots & \vdots \\ u_r & u_m \end{array} \right)$$

$$i \leq r \quad \boxed{A v_i = \sigma_i u_i \quad \updownarrow \quad A^T u_i = \sigma_i v_i} \quad \boxed{A v_i = 0 \quad \updownarrow \quad A^T u_i = 0} \quad i > r$$

$$V = \left(\begin{array}{c|c} \text{o.n. basis for Row}(A) & \text{o.n. basis for Nul}(A) \\ \hline v_1 & v_{r+1} \\ \vdots & \vdots \\ v_r & v_n \end{array} \right)$$

The Pseudo-Inverse

This is a matrix A^+ that is the "best possible" substitute for A^{-1} when A is not invertible.

- Works for non-square matrices:
if A is $m \times n$ then A^+ is $n \times m$
- A^+b is the shortest least-squares solution of $Ax=b$.

First let's do diagonal matrices.

Def: If Σ is an $m \times n$ diagonal matrix with nonzero diagonal entries $\sigma_1, \dots, \sigma_r$, its pseudo-inverse Σ^+ is the $n \times m$ diagonal matrix with diagonal entries $\sigma_1^{-1}, \dots, \sigma_r^{-1}$.

$$\Sigma = \begin{pmatrix} 3 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}_{4 \times 5} \rightsquigarrow \Sigma^+ = \begin{pmatrix} 1/3 & 0 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}_{5 \times 4}$$

NB: If Σ is invertible (hence square) then $\Sigma^+ = \Sigma^{-1}$.

$$\begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1/3 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Now let's do general matrices.

Def: Let A be an $m \times n$ matrix with SVD

$$A = \sigma_1 u_1 v_1^T + \dots + \sigma_r u_r v_r^T \quad A = U \Sigma^T V^T$$

The **pseudo-inverse** of A is the $n \times m$ matrix

$$A^\dagger = \frac{1}{\sigma_1} v_1 u_1^T + \dots + \frac{1}{\sigma_r} v_r u_r^T \quad A^\dagger = V \Sigma^\dagger U^T$$

This has the **same singular vectors** (switch right & left) and **reciprocal singular values**.

Eg: $A = \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} = 15\sqrt{2} u_1 v_1^T + 10\sqrt{2} u_2 v_2^T$

$$\text{for } u_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad v_1 = \frac{1}{\sqrt{10}} \begin{pmatrix} -2 \\ 1 \\ -2 \\ 1 \end{pmatrix}$$

$$u_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad v_2 = \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ 2 \\ 1 \\ 2 \end{pmatrix}$$

$$\hookrightarrow A^\dagger = \frac{1}{15\sqrt{2}} v_1 u_1^T + \frac{1}{10\sqrt{2}} v_2 u_2^T$$

$$= \frac{1}{15\sqrt{2}} \cdot \frac{1}{\sqrt{10}} \begin{pmatrix} -2 \\ 1 \\ -2 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{5}} (2 \ -1) + \frac{1}{10\sqrt{2}} \cdot \frac{1}{\sqrt{10}} \begin{pmatrix} 1 \\ 2 \\ 1 \\ 2 \end{pmatrix} \cdot \frac{1}{\sqrt{5}} (1 \ 2)$$

$$= \frac{1}{150} \begin{pmatrix} -4 & 2 \\ 2 & -1 \\ -4 & 2 \\ 2 & -1 \end{pmatrix} + \frac{1}{100} \begin{pmatrix} 1 & 2 \\ 2 & 4 \\ 1 & 2 \\ 2 & 4 \end{pmatrix} = \frac{1}{300} \begin{pmatrix} -5 & 10 \\ 10 & 10 \\ -5 & 10 \\ 10 & 10 \end{pmatrix}$$

NB: If A is invertible then $r=m=n$ and Σ is invertible, so $\Sigma^\dagger = \Sigma^{-1}$ and

$$AA^\dagger = (U\Sigma V^\dagger)(V\Sigma^\dagger U^\dagger)$$

$$= U\Sigma (\cancel{V^\dagger V})^\dagger \Sigma^{-1} U^\dagger = U\Sigma \Sigma^{-1} U^\dagger = U \cancel{U^\dagger}^\dagger = I_n$$

$$A \text{ is invertible} \iff A^{-1} = A^\dagger$$

In general, for $i \leq r$ we have

same singular vectors
reciprocal singular values

$$A^\dagger A v_i = A^\dagger (\sigma_i u_i) = \sigma_i A^\dagger u_i = \sigma_i \cdot \frac{1}{\sigma_i} v_i = v_i$$

$$A A^\dagger u_i = A \left(\frac{1}{\sigma_i} v_i \right) = \frac{1}{\sigma_i} A v_i = \frac{1}{\sigma_i} \cdot \sigma_i u_i = u_i$$

But for $i > r$ we have

$$A^\dagger A v_i = A^\dagger \cdot 0 = 0$$

$$(v_i \in \text{Nul}(A))$$

$$A A^\dagger u_i = A \cdot 0 = 0$$

$$(u_i \in \text{Nul}(A^\dagger) = \text{Nul}(A^*))$$

$i \leq r$

$$\begin{aligned} A^\dagger A v_i &= v_i \\ A A^\dagger u_i &= u_i \end{aligned}$$

$i > r$

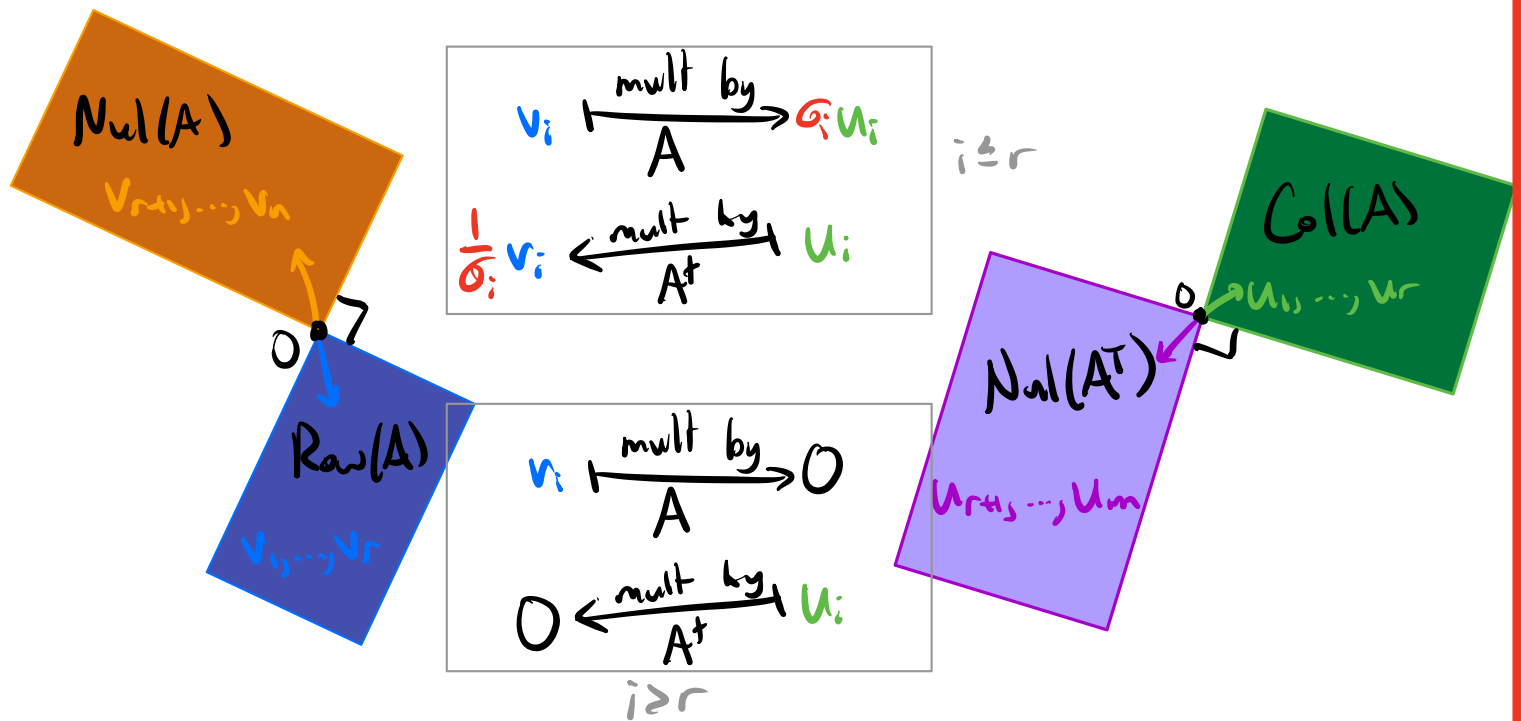
$$\begin{aligned} A^\dagger A v_i &= 0 \\ A A^\dagger u_i &= 0 \end{aligned}$$

The Big Picture Revisited

for an $m \times n$ matrix A of rank r

Row Picture: $\mathbb{R}^n$

Column Picture: $\mathbb{R}^m$



This tells us exactly what $A^T A$ and $A A^T$ are when A is not invertible:

Prop: $A^T A = \text{projection onto } Row(A)$
 $A A^T = \text{projection onto } Col(A)$

Proof: If $P = \text{projection matrix for } Row(A)$ then

$$P v_i = v_i = A^T A v_i \quad \text{for } i \leq r \quad (v_i \in Row(A))$$

$$P v_i = 0 = A^T A v_i \quad \text{for } i > r \quad (v_i \in Nul(A) = Row(A)^\perp)$$

Now take linear combinations. Same for $A A^T$. ✓

Recall: A projection matrix P_V is the identity matrix
 $\Rightarrow V$ is all of $\mathbb{R}^n$

Consequence:

- $A^T A = I_n \Leftrightarrow A$ has full column rank
($\text{Row}(A) = \text{Nul}(A)^\perp = \{0\}^\perp = \mathbb{R}^n$)
- $A A^T = I_m \Leftrightarrow A$ has full row rank
($\text{Col}(A) = \mathbb{R}^m$)

Eg:

$$A = \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} \quad A^T = \frac{1}{300} \begin{pmatrix} -5 & 10 \\ 10 & 10 \\ -5 & 10 \\ 10 & 10 \end{pmatrix}$$

$$A^T A = \frac{1}{300} \begin{pmatrix} -5 & 10 \\ 10 & 10 \\ -5 & 10 \\ 10 & 10 \end{pmatrix} \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} = \begin{pmatrix} 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \end{pmatrix}$$

$$A A^T = \frac{1}{300} \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} \begin{pmatrix} -5 & 10 \\ 10 & 10 \\ -5 & 10 \\ 10 & 10 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$(\text{Col}(A) = \mathbb{R}^2 \Rightarrow \text{projection is } I_2)$$

Prop: For any $b \in \mathbb{R}^m$, $\hat{x} = A^T b$ is the shortest
least-squares solution of $Ax = b$.

Proof: First note $A\hat{x} = AA^+b =$ projection of b onto $\text{Col}(A)$
 $\Rightarrow \hat{x}$ is a least-squares solution.

Note $\hat{x} = \frac{1}{\sigma_1} v_1 u_1^T b + \dots + \frac{1}{\sigma_r} v_r u_r^T b$
 $= \frac{1}{\sigma_1} (u_1 \cdot b) v_1 + \dots + \frac{1}{\sigma_r} (u_r \cdot b) v_r$

$\in \text{Span}\{v_1, \dots, v_r\} = \text{Row}(A). \quad \leadsto \hat{x} \in \text{Row}(A)$

Any other solution $\hat{x}'$ has the form $\hat{x}' = \hat{x} + y$
 for $y \in \text{Nul}(A)$. Note $y \in \text{Row}(A)^\perp \Rightarrow \hat{x} \cdot y = 0$

$$\|\hat{x} + y\|^2 = (\hat{x} + y) \cdot (\hat{x} + y) = \hat{x} \cdot \hat{x} + 2\hat{x} \cdot y + y \cdot y$$

$$\|\hat{x} + y\|^2 = \|\hat{x}\|^2 + \|y\|^2 \geq \|\hat{x}\|^2$$

$\Rightarrow \hat{x}$ is the **shortest**.



Eg: $A = \begin{pmatrix} 1 & 1 \end{pmatrix} = 2 \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \end{pmatrix}$

$$A^+ = \frac{1}{2} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

The shortest least-squares
 solution of $Ax = b = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$

is $\hat{x} = A^+ b = \frac{1}{4} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

All other least-squares solutions
 differ by $\text{Nul}(A) = \text{Span}\{\begin{pmatrix} -1 \\ 1 \end{pmatrix}\}$.

