

LU Decomposition cont'd

Fact: If Gaussian elimination on A requires no row swaps, then

$$A = L U$$

for L lower-unitriangular and U in REF.

In this case $U = (E_r \cdots E_1)A$, $U = REF$

E_i = elementary matrix for $R_i \leftarrow cR_j$, $i > j$
(clear down)

E_i is lower-triangular

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ c & 0 & 1 \end{bmatrix} R_3 \leftarrow cR_1$$

$\Rightarrow E_r \cdots E_1$ is lower-triangular

$\Rightarrow L = (E_r \cdots E_1)^{-1}$ is lower-triangular

and $A = LU$

NB: $L = (E_r \cdots E_1)^{-1}$ "records the row operations"
 $\rightarrow$ keeps track of elimination

NB: $A = LU$ is a matrix factorization: it is a way to write a matrix as a product of simpler matrices. We will learn many more of these.

Eg: $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \xrightarrow{R_2 \leftarrow 4R_1} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 7 & 8 & 9 \end{bmatrix} \quad E_1 = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{R_3 \leftarrow 7R_1} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & -6 & -12 \end{bmatrix} \quad E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -7 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{R_3 \leftarrow 2R_2} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{bmatrix} \quad E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$

U

$$L = (E_3 E_2 E_1)^{-1} = E_1^{-1} E_2^{-1} E_3^{-1}$$

To compute $E_1^{-1} E_2^{-1} E_3^{-1} = E_1^{-1} E_2^{-1} E_3^{-1} I_3$,

start with I_3 :

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{R_3 \leftarrow 2R_2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

$E_3^{-1} = \text{undo } E_3$

$$\xrightarrow{R_3 \leftarrow 7R_1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 7 & 2 & 1 \end{bmatrix}$$

$E_2^{-1} = \text{undo } E_2$

$$\xrightarrow{R_2 \leftarrow 4R_1} \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 2 & 1 \end{bmatrix}$$

$E_1^{-1} = \text{undo } E_1$

$$\begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 2 & 1 \end{bmatrix} = L$$

Check: $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{bmatrix}$

Here's a better way to do the bookkeeping.

Algorithm (LU Decomposition; 2 column method):

Input: A matrix where Gaussian elimination requires no row swaps

Output: A factorization $A=LU$ for L lower-unitriangular and U in REF (the output of Gaussian elimination).

Procedure: Do Gaussian elimination, keeping track of the row operations as follows: start with a blank $n \times n$ matrix L .

- for each row replacement $R_i \leftarrow R_i + c R_j$, put $-c$ in the (i,j) entry of L .

Add 1's & 0's to the part of L above the diagonal. Then

$$A = LU.$$

Eg: $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$

↙ 2 columns ↘

L
U

Start with A in U column

$R_2 \leftarrow 4R_1$

$R_3 \leftarrow 7R_1$

$R_3 \leftarrow 2R_2$

(add these)

L =

$$\begin{bmatrix} \text{blank} \\ 4 \\ 4 \\ 7 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 2 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 7 & 8 & 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & -6 & -12 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{bmatrix}$$

U

NB: Finding $A=LU$ is just Gaussian elimination + extra bookkeeping $\rightarrow$ same complexity. $\approx \frac{2}{3}n^3$ flops

How does this help?

Algorithm (solving $Ax=b$ using $A=LU$)

Input: An LU factorization $A=LU$ & vector b

Output: A solution of $Ax=b$

Procedure:

(1) Solve $Ly=b$ using **forward**-substitution

$$\begin{bmatrix} 1 & 0 & 0 \\ \bullet & 1 & 0 \\ \bullet & \bullet & 1 \end{bmatrix} y = b \equiv \begin{aligned} y_1 &= b_1 \\ y_2 + \bullet y_1 &= b_2 \\ y_3 + \bullet y_2 + \bullet y_1 &= b_3 \end{aligned}$$

($\approx n^2$ flops)

(2) Solve $Ux=y$ using backward-substitution

($\approx n^2$ flops)

Then $Ax = LUx = L(Ux) = Ly = b$ ✓

NB: total complexity is $\approx 2n^2$ flops
 $\rightarrow$ **way faster** than $\frac{2}{3}n^3$!

Still have to do elimination once, but then solving $Ax=b$ for new values of b is much faster.

Eg: Solve $Ax = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ using

$$\begin{bmatrix} 2 & 1 & 0 \\ 4 & 4 & 4 \\ 6 & 1 & 0 \end{bmatrix} = A = LU = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 4 \\ 0 & 0 & 4 \end{pmatrix}$$

$$(1) Ly=b: \begin{array}{rcl} y_1 & = & 1 \\ 2y_1 + y_2 & = & 0 \\ 3y_1 - y_2 + y_3 & = & 1 \end{array} \xrightarrow[\text{subst}]{\text{forward}} y = \begin{pmatrix} 1 \\ -2 \\ -4 \end{pmatrix}$$

$$(1) Ux=y: \begin{array}{rcl} 2x_1 + x_2 & = & 1 \\ 2x_2 + 4x_3 & = & -2 \\ 4x_3 & = & -4 \end{array} \xrightarrow[\text{subst}]{\text{backward}} x = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

Check: $\begin{bmatrix} 2 & 1 & 0 \\ 4 & 4 & 4 \\ 6 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ ✓

Eg: If A is 1000×1000 and we want to solve $Ax=b$ for 1000 values of b :

- $\frac{2}{3}$ gigaflops to compute $A=LU$
- $2 \text{ megaflops} \times 1000 = 2 \text{ gigaflops}$ to solve $Ax=b$ 1000 times.

That's **250x faster** than $\frac{2}{3}$ teraflops from doing elimination 1000 times!

What about inverses?

Wouldn't it be better to compute A^{-1} and solve $A^{-1}x=b$ 1000 times?

No, for 2 reasons:

(1) Computing A^{-1} takes $\approx \frac{4}{3}n^3$ flops = twice as long as the elimination step!

(2) Computing A^{-1} is not numerically stable (less accurate due to rounding errors).

[Inalg.js example below: try it yourself!]

You can copy/paste the code.]

```

// This is the matrix [2 1 1 ... 1]
//                    [1 2 1 ... 1]
//                    [. . . ... .]
//                    [1 1 1 ... 2]
A = Matrix.identity(1000).add(Matrix.constant(1,1000));
// Computes and caches a PA=LU decomposition
A.PLU();
// The vector (1,1,...,1)
b = Vector.constant(1000,1);
// Solve Ax=b 1000 times using the cached PA=LU decomposition
// This takes a few seconds on my browser.
for(i = 0; i < 1000; ++i) A.solve(b)
// Solve Ax=b 1000 times *without* PA=LU decomposition.
// This crashes my browser.
for(i = 0; i < 1000; ++i) { A.invalidate(); A.solve(b) }

```

Maximal Partial Pivoting

Eg: $\begin{cases} x_2 = 1 \\ x_1 + x_2 = 2 \end{cases}$ has one solution: $x_1 = x_2 = 1$

Let's tweak it a little bit:

$$\begin{cases} 10^{-17}x_1 + x_2 = 1 \\ x_1 + x_2 = 2 \end{cases} \rightarrow \text{presumably has one solution } (x_1, x_2) \approx (1, 1).$$

$$\left[\begin{array}{cc|c} 10^{-17} & 1 & 1 \\ 1 & 1 & 2 \end{array} \right] \xrightarrow{R_2 \leftarrow 10^{17}R_1} \left[\begin{array}{cc|c} 10^{-17} & 1 & 1 \\ 0 & 1-10^{17} & 2-10^{17} \end{array} \right]$$

$10^{-17}x_1 + x_2 = 1$

$(1-10^{17})x_2 = 2-10^{17}$

$$\Rightarrow x_2 = \frac{2-10^{17}}{1-10^{17}} = \frac{1+(1-10^{17})}{1-10^{17}} = 1 + \frac{1}{1-10^{17}} \approx 1$$

$$x_1 = 10^{17}(1-x_2) = \frac{10^{17}}{10^{17}-1} \approx 1$$

Let's try this on a computer. [inalg.js]

What went wrong?

→ Javascript uses IEEE 754 64-digit floating point numbers. That means it has ≈ 16 digits of precision.

The computer thinks $1-10^{17} = -10^{17} = 2-10^{17}$

$$\begin{bmatrix} 10^{-17} & 1 & | & 1 \\ 1 & 1 & | & 2 \end{bmatrix} \xrightarrow{R_2 \leftarrow 10^{17} R_1} \begin{bmatrix} 10^{-17} & 1 & | & 1 \\ 0 & -10^{17} & | & -10^{17} \end{bmatrix}$$

$$\begin{aligned} 10^{-17}x_1 + x_2 &= 1 \\ x_2 &= 1 \end{aligned}$$

$$\leadsto x_1 = 10^{17}(0) = 0$$

$(0, 1) \neq (1, 1)$: not numerically stable.

What went wrong?

Dividing by 10^{-17} produced a huge number 10^{17}
 $\leadsto$ all errors just exploded!

On a computer, you never want to divide by tiny numbers!

Solution: Use the larger pivot (in absolute value)

$$\begin{bmatrix} 10^{-17} & 1 & | & 1 \\ 1 & 1 & | & 2 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 1 & | & 2 \\ 10^{-17} & 1 & | & 1 \end{bmatrix}$$

$$\xrightarrow{R_2 \leftarrow 10^{-17} R_1} \begin{bmatrix} 1 & 1 & | & 2 \\ 0 & 1 & | & 1 \end{bmatrix}$$

$$x_1 + x_2 = 2$$

$$x_2 = 1$$

$$\leadsto x_1 = 1$$

[linear sys]

computer:

$$1 - 10^{-17} \approx 1$$

$$1 - 2 \cdot 10^{17} \approx 1$$

```

// Create the matrix [10^(-17) 1 1]
//           [           1 1 2]
A = mat([1e-17,1,1],[1,1,2]);
// R2 -= 1/10^(-17) R1
A.rowReplace(1,0,-A[1][0]/A[0][0]);
// What did this do to A?
console.log(A.toString());
// Output: [0.0000           1.0000           1.0000]
//           [0.0000 -10000000000000000.0000 -10000000000000000.0000]
// Solve for x2; you get x2 = 1
x2 = A[1][2]/A[1][1];
// solve for x1 using back-substitution
x1 = (A[0][2] - A[0][1]*x2) / A[0][0];
// you get x1 = 0!
// Evaluate this:
1 - 1e-17 // = 1

// Let's try again using maximal partial pivoting
// Create the matrix [10^(-17) 1 1]
//           [           1 1 2]
A = mat([1e-17,1,1],[1,1,2]);
// R1 <-> R2
A.rowSwap(0,1);
// R2 -= 10^(-17)/1 R1
A.rowReplace(1,0,-A[1][0]/A[0][0]);
// Solve for x2; you get x2 = 1
x2 = A[1][2]/A[1][1];
// solve for x1 using back-substitution
x1 = (A[0][2] - A[0][1]*x2) / A[0][0];
// you get x1 = 1

```

Gaussian Elimination using Maximal Partial Pivoting:

In step (a), row swap so that the **largest** number in the column (in absolute value) is the pivot.

This is much more **numerically stable**.
→ avoids dividing by tiny numbers.

$PA=LU$ Decompositions

Recall: LU only works when you don't need to **row swap** when eliminating.

But elimination works much better with row swaps!
Need to tweak LU.

Idea: Do all the row swaps you need **first**, then do elimination without row swaps.

(How do you know in advance which row swaps to do? You don't - need to do more bookkeeping)

Def: A **permutation matrix** is a product of elementary matrices for row swaps.

PA=LU Decomposition: Any matrix A has a factorization

$$PA = LU$$

Do a bunch of row swaps on A...

... then do an LU decomp

where:

P: permutation matrix

L: lower-unitriangular matrix

U: REF matrix

Eg:

$$\begin{aligned}
 A &= \begin{bmatrix} 1 & 1 & 1 \\ -10 & -20 & -30 \\ 5 & 15 & 10 \end{bmatrix} \xrightarrow{\substack{\text{maximal} \\ \text{partial} \\ \text{pivoting}}} R_1 \leftrightarrow R_2 \begin{bmatrix} -10 & -20 & -30 \\ 1 & 1 & 1 \\ 5 & 15 & 10 \end{bmatrix} P_1 \\
 &\xrightarrow{\substack{R_2 + \frac{1}{10}R_1 \\ R_3 + \frac{1}{2}R_1}} \begin{bmatrix} -10 & -20 & -30 \\ 0 & -1 & -2 \\ 0 & 5 & -5 \end{bmatrix} E_1, E_2 \\
 &\xrightarrow{\substack{\text{maximal} \\ \text{partial} \\ \text{pivoting}}} R_2 \leftrightarrow R_3 \begin{bmatrix} -10 & -20 & -30 \\ 0 & 5 & -5 \\ 0 & -1 & -2 \end{bmatrix} P_2 \\
 &\xrightarrow{R_3 + \frac{1}{5}R_2} \begin{bmatrix} -10 & -20 & -30 \\ 0 & 5 & -5 \\ 0 & 0 & -3 \end{bmatrix} E_3 \\
 &\quad \underbrace{\hspace{10em}}_U
 \end{aligned}$$

$$\begin{aligned}
 &\text{with } P_2 \text{ were here...} \\
 U &= E_3 P_2 E_2 E_1 P_1 A \\
 &\quad \underbrace{\hspace{4em}}_{\text{not lower-unitriangular!}}
 \end{aligned}$$

Trick: $P_2 E_2 E_1 = \underbrace{(P_2 E_2 E_1 P_2)}_{\text{is lower-uniform!}} P_2$ $P_2 P_2 = I_3$

$$P_2 E_2 E_1 P_2 = P_2 E_2 E_1 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\begin{array}{l} R_2 \leftrightarrow R_1 \\ R_3 \leftrightarrow R_1 \end{array} P_2 \begin{bmatrix} 1 & 0 & 0 \\ 1/10 & 0 & 1 \\ 1/2 & 1 & 0 \end{bmatrix}$$

$$\begin{array}{l} R_1 \leftrightarrow R_2 \end{array} \begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 1/10 & 0 & 1 \end{bmatrix} \quad \text{lower-uniform!}$$

Then $U = E_3 (P_2 E_2 E_1 P_2) P_1 A$

$$\Rightarrow PA = LU$$

for $P = P_2 P_1$ $L = (E_3 P_2 E_2 E_1 P_2)^{-1}$

Here is an efficient way of doing the bookkeeping.

Algorithm ($PA=LU$ Decomposition; 3-column method):

Input: Any matrix A

Output: A factorization $PA = LU$ where:

P : permutation matrix

L : lower-unitriangular matrix

U : REF matrix

Procedure: Perform Gaussian elimination using any pivoting strategy (eg. maximal partial pivoting). Keep track of row operations as follows: start with a blank matrix L and an identity matrix P .

- for each row replacement $R_i += c R_j$, put $-c$ in the (i,j) entry of L (as before)
- for each row swap $R_i \leftrightarrow R_j$, swap the corresponding rows of L and P .

Add 1's & 0's to the part of L above the diagonal. Then

$$PA = LU.$$

Eg: $A = \begin{bmatrix} 1 & 1 & 1 \\ -10 & -20 & -30 \\ 5 & 15 & 10 \end{bmatrix}$

3 columns
 $P \quad L \quad U$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

[blank]

$$\begin{bmatrix} 1 & 1 & 1 \\ -10 & -20 & -30 \\ 5 & 15 & 10 \end{bmatrix}$$

Start with A in the U col

$R_1 \leftrightarrow R_2$

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

[blank]

$$\begin{bmatrix} -10 & -20 & -30 \\ 1 & 1 & 1 \\ 5 & 15 & 10 \end{bmatrix}$$

$R_2 + \frac{1}{10}R_1$
 $R_3 + \frac{1}{2}R_1$

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} -1/10 \\ -1/2 \end{bmatrix}$$

$$\begin{bmatrix} -10 & -20 & -30 \\ 0 & -1 & -2 \\ 0 & 5 & -5 \end{bmatrix}$$

$R_2 \leftrightarrow R_3$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1/2 \\ -1/10 \end{bmatrix}$$

$$\begin{bmatrix} -10 & -20 & -30 \\ 0 & 5 & -5 \\ 0 & -1 & -2 \end{bmatrix}$$

$R_3 + \frac{1}{5}R_2$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1/2 \\ -1/10 & -1/5 \end{bmatrix}$$

$$\begin{bmatrix} -10 & -20 & -30 \\ 0 & 5 & -5 \\ 0 & 0 & -3 \end{bmatrix}$$

P

add these 2

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -1/2 & 1 & 0 \\ -1/10 & -1/5 & 1 \end{bmatrix}$$

U

Check:

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ -10 & -20 & -30 \\ 5 & 15 & 10 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1/2 & 1 & 0 \\ -1/10 & -1/5 & 1 \end{bmatrix} \begin{bmatrix} -10 & -20 & -30 \\ 0 & 5 & -5 \\ 0 & 0 & -3 \end{bmatrix}$$

Can we still use this to solve $Ax=b$?

Algorithm (solving $Ax=b$ using $PA=LU$)

Solving $Ax=b$ is the same as $PAx=Pb$, so:

(0) Compute Pb (re-order the entries of b)

(1) Solve $Ly=Pb$ using forward-substitution

(2) Solve $Ux=y$ using backward-substitution

$$\text{Then } PAx = LUx = Ly = Pb$$

$$\Rightarrow Ax=b \quad (\text{multiply both sides by } P^{-1}) \quad \checkmark$$

Eg: Solve $Ax=b$ for

$$A = \begin{bmatrix} 1 & 1 & 1 \\ -10 & -20 & -30 \\ 5 & 15 & 10 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ -10 \\ 10 \end{bmatrix}$$

$$(0) \quad Pb = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ -10 \\ 10 \end{bmatrix} = \begin{bmatrix} -10 \\ 10 \\ 0 \end{bmatrix}$$

$$(1) \quad \begin{bmatrix} 1 & 0 & 0 \\ -1/2 & 1 & 0 \\ -1/10 & -1/5 & 1 \end{bmatrix} y = Pb = \begin{bmatrix} -10 \\ 10 \\ 0 \end{bmatrix} \rightsquigarrow \begin{matrix} y_1 = -10 \\ y_2 = 5 \\ y_3 = 0 \end{matrix}$$

$$(2) \quad \begin{bmatrix} -10 & -20 & -30 \\ 0 & 5 & -5 \\ 0 & 0 & -3 \end{bmatrix} x = \begin{bmatrix} -10 \\ 5 \\ 0 \end{bmatrix} \rightsquigarrow \begin{matrix} x_1 = -1 \\ x_2 = 1 \\ x_3 = 0 \end{matrix} \quad x = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$