The Method of Least Squares Setup: you have a matrix equation Ax = b which is (generally) inconsistent. What is the best approximate solution? What do ve mean by "best approximate solution"? Def: X is a least squares solution of Ax=b if Nb-AxII is minimized over all vector X. This means Ax is as close as possible to b. NB:  $C_0I(A) = \{A\hat{x}: \hat{x} \in \mathbb{R}^n\}$ , so  $A\hat{x}$  is just the closest vector to b in V=Col(A). This is the orthogonal projection!  $A\hat{x}=b_{v}$  for V=G(A)How do we compute by and  $\hat{x}?$  $\rightarrow$  IF  $\hat{x}$  is any solv of ATA $\hat{x}$ =ATb, then Ax=by. So X is a least-squares solution!

Procedure (Least Squares):  
To Find the least squares solution(s) of Ax=b:  
(1) Solve the normal equation ATAX=ATB  
(2) Any solution 
$$\hat{x}$$
 is a least-squares solv  
and  $b_v = A\hat{x}$  for  $V = Col(A)$ .

NB: The error is the distance from Ax to b:  
error = ||b-Ax|| = ||b-bu|| = ||bye||  
Recall that ||b-Ax|| = ||bye|| is minimized:  
if bye = (2) then 
$$\sqrt{a^2+b^2+c^2}$$
, or equivalently  
 $a^2+b^2+c^2 \in the minimized quantity.$   
This is why it's called a least squares solution:  
we're minimizing the sum of the squares of  
the entrizes of b-Ax.

Eq: Find the least-squares solution of 
$$Ax=b$$
  
for  $A = \begin{pmatrix} 0 \\ i \\ 2 \end{pmatrix} b = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}$ .

(1) 
$$A^{T}A = \begin{pmatrix} 5 & 3 \\ 3 & 3 \end{pmatrix} A^{T}b = \begin{pmatrix} 6 \\ 6 \end{pmatrix}$$
  
 $\begin{pmatrix} 5 & 3 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} 6 \\ 6 \end{pmatrix} \xrightarrow{rref} \begin{pmatrix} 1 & 0 & 1 & -3 \\ 0 & 1 & 5 \end{pmatrix}$   
(2)  $\hat{X} = \begin{pmatrix} -3 \\ 5 \end{pmatrix} \xrightarrow{rref} \xrightarrow{rref} \begin{pmatrix} 1 & 0 & 1 & -3 \\ 0 & 1 & 5 \end{pmatrix}$   
 $for V = A\hat{X} = \begin{pmatrix} 5 \\ 2 \\ -1 \end{pmatrix}$   
The error  $\overline{15}$   
 $|b_{V} \perp|| = |b - b_{V}|| = || \begin{pmatrix} 6 \\ 6 \end{pmatrix} - \begin{pmatrix} 5 \\ 2 \\ -1 \end{pmatrix}| = || \begin{pmatrix} -2 \\ 1 \end{pmatrix}||$   
 $= \int |^{2} + (-2)^{2} + |^{2} = |6|$ .

Eq: Find the least-squares solutions of Ax=b  
for 
$$A = \begin{pmatrix} 1 & -1 & -1 \\ 1 & -1 & -1 \end{pmatrix}$$
 and  $b = \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}$ .  
(1)  $A^{T}A = \begin{pmatrix} 6 & 0 & 6 \\ 6 & 6 & 18 \end{pmatrix}$   $A^{T}b = \begin{pmatrix} 4 \\ -1 \\ 2 \end{pmatrix}$   
 $\begin{pmatrix} 6 & 0 & 6 \\ 6 & 6 & 18 \end{pmatrix} \stackrel{\text{ref}}{\longrightarrow} \begin{pmatrix} 1 & 0 & 1 & | & 2/3 \\ 0 & 1 & 2 & | & -1/3 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$   
(2)  $\stackrel{\text{PVF}}{\longrightarrow} \hat{X} = \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \end{pmatrix} + X_{3} \begin{pmatrix} -1 \\ -2 \\ 1 \end{pmatrix}$ 

In this case there are infinitely many  
least-squares solutions!  
$$b_v = Ax$$
 for any  $\hat{x}$ . Take  $\hat{x} = \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \end{pmatrix}$   
 $u_s b_r = \begin{pmatrix} 1 & -1 & -1 \\ 2 & -1 & -1 \end{pmatrix} \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$   
 $b_{v1} = b - b_v = O$   
So the error is zero - the equation  
 $Ax = b$  was consistent after all!  
(Compare UGL2 pp. 4-5)

Observation 1: Ax=b has a unique least-squares soli A has full column rank! This is exactly when ATAX=ATb has a unique solution (ATA is invertible). Otherwise, there are infinitely many leastsquares solvs. This means 11b-AR11 is minimized for any such  $\hat{x}$ :  $b_v = A\hat{x}$  for any solution  $\hat{x}$ . (There can't be zero least-squares solutions!  $A^TA\hat{x} = A^Tb$  is always consistent.)

Observation 2: If Ax=b is consistent, then (least squares) = (ordinary) solutions) = (solutions).

Indeed, a least-squares soln is just a soln of 
$$A\hat{x} = br$$
 ( $V = G(A)$ ), and  $b = br \Longrightarrow b \in G(A) \iff Ax = b$  is consistent.

Least-squares is often weful for fitting data to a model.

Eg (linear regression): Find the best-fit line z=Cx+D thru the data points (0,6), (1,0), (2,0).

If (0,6) lies on 
$$y=Cx+D$$
  
then substituting  $x=0, y=6$   
would give  $G=C\cdot O+D$ . So  
we want to solve:  
(0,6):  $G=C\cdot O+D$  in the CLD  
(1,0):  $O=C\cdot I+D$  unknowns  
(2,0):  $O=C\cdot 2+D$   
ie Ax=b for  $A=\begin{pmatrix} 2\\ 2\\ 1 \end{pmatrix} x=\begin{pmatrix} 2\\ 1 \end{pmatrix} b=\begin{pmatrix} 6\\ 3\\ 7 \end{pmatrix}$   
NB: the data points are not collinear ~  
no exact solution! (maybe measurement error).  
We found a least squares solution before:  
 $\hat{x}=\begin{pmatrix} -3\\ 5 \end{pmatrix}$  ~ best-fit line  $y=-3x+5$   
Important Question:  
 $D=Ax=D$  for  $A=\begin{pmatrix} 1\\ 2\\ 2\\ 1 \end{pmatrix} x=\begin{pmatrix} 1\\ 2\\ 3 \end{pmatrix}$ 

So 
$$b_{y1}=b-A\hat{x}=\begin{pmatrix} -2\\ -2\\ \end{pmatrix}$$
  
 $=\begin{pmatrix} vertical distances\\ from y=-3x+5\\ the data points \end{pmatrix}$   
 $y=-3x+5$  to  
 $y=-3x+5$  to  
 $y=-3x+5$  to  
 $y=-3x+5$   
 $y=-3x+5$ 

Eq (best-fit parabola):  
Find the best-fit parabola 
$$y = Bx^{2}+Cx+D$$
  
thru the data points  $(-1,1/2), (1,-1), (2,-1/2), (3,2)$   
Substitute the data points for  
 $x \ dy \ y = x \ cant to solve$   
 $(-1,1): \ 1 = B(-1)^{2} + C(-1) + D$   
 $(1,-1): \ -1 = B(1)^{2} + C(1) + D$   
 $(2,-1/2): \ -1 = B(2)^{2} + C(2) + D$   
 $(3,2): \ 2 = B(3)^{2} + C(3) + D$   
 $\rightarrow Ax = b$  for  $A = \begin{pmatrix} 1 & -i & i \\ -1 & i & i \\ -1 & 2 & i \\ -1 & 3 & i \end{pmatrix} x = \begin{pmatrix} \beta \\ C \\ 0 \end{pmatrix} b = \begin{pmatrix} 1/2 \\ -1/2 \\ -1/2 \\ 2 \end{pmatrix}$ 

Let's find the least-squares solution.

$$A^{T}A = \begin{pmatrix} q q & 35 & 15 \\ 37 & 15 & 5 \\ 15 & 5 & 4 \end{pmatrix} \quad A^{T}b = \begin{pmatrix} 31/2 \\ 7/2 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} q q & 35 & 15 \\ 37 & 15 & 5 \\ 15 & 5 & 4 \\ 1 \end{pmatrix} \stackrel{71/2}{\longrightarrow} \stackrel{RPEF}{\longrightarrow} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \\ \end{pmatrix} \stackrel{73}{\longrightarrow} \stackrel{73}{\longrightarrow} \stackrel{73}{\longrightarrow} \stackrel{73}{\longrightarrow} \stackrel{74}{\longrightarrow} \stackrel{74}{\longrightarrow}$$

So by = b-Ax = vertical distances from the to the data points, like before.

This same method works to find a best-fit function of the form y=AftBgtCht. where figh,... are really any functions! Just plug the x-values of your data points into figh -> I mear equations Jor A, B, C, .-

Eg (best-fit trogonometric function): see \$6.5 in ILA for an example. This real-life example of Gauss was in the first lecture:

Eg: An asteroid has been observed at condinates: (0,2), (2,1), (1,-1), (-1,-2), (-3,1), (-1,1)Question: What is the most likely orbit? Will the asteroid Crash into the Earth? Will the esteroid Crash into the Eart Fact: The orbit is an II.

ellipse.

Equation for an ellipse:  $X^2 + By^2 + Cxy + Dx + Ey + F = 0$ 

For our points to lie on the ellipse, substitude  
the coordinates into 
$$(x_{1,y})$$
 we these should hdd:  
 $\begin{pmatrix} 0 \\ 2 \end{pmatrix}$ :  $O + 4B + O + O + 2E + F = O$   
 $(2,1)$ :  $4 + B + 2C + 2D + E + F = O$   
 $(1,-1)$ :  $1 + B - C + D - E + F = O$   
 $(1,-1)$ :  $1 + B - C + D - 2E + F = O$   
 $(-1,-2)$ :  $1 + 4B + 2C - D - 2E + F = O$   
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 $(-1,-2)$ :  $1 + B - C - D + E + F = O$   
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 $(-1,-1)$ :  $1 + B - C - D + E + F = O$   
 $(-1,-1)$ :

$$Ax - b = \begin{pmatrix} 4 & 0 & 0 & 1 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & 1 & -3 & 1 \\ 1 & -1 & -1 & 1 & 1 \end{pmatrix} x - \begin{pmatrix} -4 \\ -1 \\ -1 \\ -4 \\ -1 \\ -4 \\ -1 \end{pmatrix}$$

$$= \begin{pmatrix} 0^{2} + \frac{405}{216}(z)^{2} - \frac{89}{133}(9(z) + \frac{201}{133}(0) - \frac{123}{216}(z) - \frac{687}{133}) \\ y^{2} + \frac{405}{216}(1)^{4} - \frac{89}{133}(9(1) + \frac{201}{133}(z)) - \frac{123}{216}(z) - \frac{687}{133}) \\ 1^{2} + \frac{405}{216}(z)^{4} - \frac{89}{133}(1)(z) + \frac{201}{133}(1) - \frac{123}{216}(z) - \frac{687}{133}) \\ (-1)^{2} + \frac{405}{216}(z)^{2} - \frac{89}{133}(z)(z) + \frac{201}{133}(z) - \frac{123}{216}(z) - \frac{687}{133}) \\ (-1)^{2} + \frac{405}{216}(z)^{2} - \frac{89}{133}(z)(z) + \frac{201}{133}(z) - \frac{123}{216}(z) - \frac{687}{133}) \\ (-1)^{2} + \frac{405}{216}(z)^{2} - \frac{89}{133}(z)(z) + \frac{201}{133}(z) - \frac{123}{216}(z) - \frac{687}{133}) \\ (-1)^{2} + \frac{405}{216}(z)^{2} - \frac{89}{133}(z)(z) + \frac{201}{133}(z) - \frac{123}{216}(z) - \frac{687}{133}) \\ (-1)^{2} + \frac{405}{216}(z)^{2} - \frac{89}{133}(z)(z) + \frac{201}{133}(z) - \frac{123}{216}(z) - \frac{687}{133}) \\ This was what you get by substituting the x- and y-values of the date points into the LHS of x- and y-values of the date points into the LHS of x- and y-values from zero. [deno] Upshot: You're minimizing IIb - Axil; it's up to you to interpret that queutity.$$