Review
Lost time: we did the outer product from SVD
A: mxn of mank r
A= ount + + orunt
· 0,2zor >0 are the singular values
· Svis-, vos 13 can orthonomal set in R"
· called the right singular vectors
· forms a basis for Row (A)
o orthonormal eigenvectors of ATA:
$A^TA_{V_i} = \sigma_i^2 V_i$
· Sus-Jus 13 an orthonormal set in Rm
· called the left singular vectors
o forms a base for Cold) o orthonormal eigenvectors of AAT:
a orthonormal eigenvectors of AA':
$AA^Tui = oi^2ui$
The singular vectors are related by
$Av_i = a_i u_i$ $A^T u_i = a_i v_i$
SVD of AT is
AT= aviut ++ orval

NB: If A is a wide matrix (m<n) then ATA: nxn AAT: mxm = smaller So it's easier to compute eigenvalues & eigenvectors of IT A is well, compute the SVD of AT. Fa: A= (-10 10 -10 10) $A^{T}A = \begin{pmatrix} 200 & -50 & 200 & -50 \\ -57 & 125 & -50 & 125 \\ 200 & -50 & 200 & -50 \\ -50 & 125 & -50 & 125 \end{pmatrix}$ Wikes! Let's compute the SVD of AT instead. $AAT = \begin{pmatrix} 400 & -100 \\ -100 & 250 \end{pmatrix} \qquad \rho(\lambda) = (\lambda - 450)(\lambda - 200)$ $\lambda_{i} = 450 \implies 0_{i} = 5450 = 1552 \quad u_{i} = \frac{1}{55} \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad v_{i} = \frac{1}{550} \begin{pmatrix} -2 \\ -2 \end{pmatrix}$ $\lambda_{2} = 2\omega \implies \sigma_{x} = \sqrt{2\omega} = 10\sqrt{2}$ $\lambda_{2} = \sqrt{2}\left(\frac{1}{2}\right)$ $V_{2} = \sqrt{2}\left(\frac{1}{2}\right)$ $\Rightarrow A^{T} = 15\sqrt{2} \text{ v.u.}^{T} + 10\sqrt{2} \text{ v.v.}^{T}$ $\Rightarrow A = 15\sqrt{2} \text{ u.v.}^{T} + 10\sqrt{2} \text{ u.v.}^{T}$ I ui are rightsingular rectors of At ~ lett singular vector

SVD: Matrix Form
Let A be an mxn mortise of rank r.
Then A = UZYT where: Isquare with
Let A be an mxn motion of rank r. Then A = UZYT where: square with continuous continuous continuous continuous matrix - U = (u,um) is an mxn orthogonal matrix
· V = (vivn) is an non orthogonal matrix
$ Z = \begin{pmatrix} 6 & 0 \\ 0 & 0 \end{pmatrix} $ is an $m \times n$ diagonal matrix
0,26,2-20,20 are the singular values

Where did uni,..., un and vin,..., vn come from?? They're orthonormal bases for the other two fundamental subspaces!

Col(A): Sus-nus
Row(A): {v,,-,v,}

Nul(AT): Sums - um} Nul(A): Svets - vn } Procedure to Compute A= UZIVT: (1) Compute the singular values and singular rectors Jun-30-> [un-304-] 60---, 6as before (2) Find orthonormal bases Eurey-was for Nul(AT) {un, ~vm} for Nul (A) using Gram-Schmidt. (3) W= (4,-4, -10m) V= (4,-4, -10m) $\sum_{i=0}^{n} = \begin{pmatrix} G_{i} & G_{i} & G_{i} \\ G_{i} & G_{i} \\ G_{i} & G_{i} \end{pmatrix}$ (same size as A)

Proof: Use the outer product version of matrix mult: $U\Sigma^{7}V^{7} = \left(u_{1} \dots u_{m}\right) \begin{pmatrix} \sigma_{1} & \sigma_{2} \\ -\sigma_{1} & \sigma_{3} \end{pmatrix}$ $= \left(u_{1} \dots u_{m}\right) \begin{pmatrix} -\sigma_{1} & \sigma_{1} \\ -\sigma_{2} & \sigma_{3} \end{pmatrix}$

= aunit + ... + anunt + 0 + --- +0

Es.
$$A = \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix}$$

(1) $A = 15J_2 \text{ u.v.}^T + 10J_2 \text{ u.v.}^T$
 $U_1 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_2 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_2 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_2 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_3 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_4 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$

PNF

Span

(3) So $A = UZVT$ for

 $U = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_2 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_3 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_4 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_5 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_6 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_7 = \frac{1}{J_2}\begin{pmatrix} -1 \\ -1 \end{pmatrix}$
 $V_8 = \frac{1}{J_2}\begin{pmatrix} -1 \\$

$$A^{T}A = V \begin{pmatrix} G_{1}^{2} & G_{0}^{2} \\ O & G_{0} \end{pmatrix} V^{T} \quad AA^{T} = U \begin{pmatrix} G_{1}^{2} & G_{0}^{2} \\ O & G_{0} \end{pmatrix} U^{T}$$

It also contains orthonormal bases for all four subspaces: o.n. basis o.n. basis

if
$$Av_i = G_i u_i \int_{A} A^T u_i = G_i v_i$$
 $Av_i = 0 \int_{A} \int_{A} A^T u_i = 0$ is

$$A_{v_i} = 0 \int \int A^T u_i = 0$$

The Preudo-Inverse

This is a matrix At that is the "best possible" substitute for AT when A is not invertible.

- · Works for non-square matrices: if A is Mxn then At is nxm
- . Atb is the shortest least-squares solution of Ax=b.

First let's do diagonal matrices.

Def: If Σ is an mxn diagonal matrix with nonzero diagonal entries or, or, its pseud-inverse Σ^{t} is the nxm diagonal matrix with nonzero diagonal entries or, or.

NB: It I is invertible (hence square) then I'= I':

$$\begin{pmatrix} 3 & 0 & 0 & -1 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \sqrt{3} & 0 & 0 \\ 0 & \sqrt{2} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Now let's do general matrices.

$$A^{\dagger} = \frac{1}{\sigma_{1}} v_{1} u_{1}^{T} + \cdots + \frac{1}{\sigma_{r}} v_{r} u_{r}^{T}$$

$$A^{\dagger} = V \Sigma^{\dagger} U^{T}$$

This has the same singular rectors (switch right & left) and reciprocal singular values.

$$\int_{0}^{2} \int_{0}^{2} \left(\frac{1}{2}\right) V_{1} = \int_{0}^{2} \left(\frac{1}{2}\right) V_{2} = \int_{0}^{2} \left(\frac{1}{2}\right) V_{3} = \int_{0}^{2} \left(\frac{1}{2}\right) V_{4} = \int_{0}^{2} \left(\frac{1}{2}\right) V_{5} = \int_{0}^{2} \left(\frac{1}{2}\right) V_$$

$$= \frac{1215}{7} \cdot \frac{210}{7} \left(\frac{5}{5}\right) \cdot \frac{22}{7} \left(5 - 1\right) + \frac{1015}{7} \cdot \frac{20}{7} \left(\frac{5}{5}\right) \cdot \frac{22}{7} \left(15\right)$$

$$=\frac{1}{150}\begin{pmatrix} -4 & 2 \\ 2 & -1 \\ -4 & 2 \\ 2 & -1 \end{pmatrix} + \frac{1}{100}\begin{pmatrix} 1 & 2 \\ 2 & 4 \\ 2 & 2 \end{pmatrix} = \frac{1}{300}\begin{pmatrix} -5 & 10 \\ 10 & 10 \\ 10 & 10 \end{pmatrix}$$

$$Col(A) = Rou(A^{+}) = Rou(A^{T})$$

$$UU(A^{T}) = Nul(A^{+}) = Nul(A^{T})$$

$$Rou(A) = Col(A^{+}) = Col(A^{T})$$

$$Nul(A) = Uul(A^{+T}) = Nul(A^{+T})$$

NB. It A 3 invertible then
$$r=m=n$$
 and Σ' is invertible, so $\Sigma' = \Sigma''$ and $AA^{+} = (U\Sigma'V^{+})(V\Sigma^{+}U^{-})$

$$= U\Sigma(V^{-}V)\Sigma^{-}V^{-} = U\Sigma\Sigma^{-1}U^{-} = UU^{-}=I_{n}$$

A is invertible \(\infty A^- = A^t

So what are AtA and AAt if A is not invertible?

Prop: AtA = projection onto Row(A)

AAt = projection onto (a)(A)

Proof $AA^{\dagger} = (U\Sigma^{\dagger}V^{\dagger})(V\Sigma^{\dagger}U^{\dagger}) = U\Sigma(V^{\dagger}V)\Sigma^{\dagger}U^{\dagger}$ $= U\Sigma^{\dagger}U^{\dagger} = U\begin{pmatrix} \sigma_{1} & \sigma_{2} \\ \sigma_{3} & \sigma_{3} \end{pmatrix}\begin{pmatrix} \sigma_{1}^{\dagger} & \sigma_{3} \\ \sigma_{3} & \sigma_{3} \end{pmatrix} U^{\dagger}$ $= \begin{pmatrix} u_{1} & \dots & u_{m} \\ u_{m} & \dots & u_{m} \end{pmatrix}\begin{pmatrix} -u_{m}^{\dagger} - u_{m}^{\dagger} \\ -u_{m}^{\dagger} - u_{m}^{\dagger} \end{pmatrix} = \begin{pmatrix} u_{1} & \dots & u_{m} \\ -u_{m}^{\dagger} - u_{m}^{\dagger} \end{pmatrix}$ $= u_{1}u_{1}^{\dagger} + \dots + u_{m}u_{m}^{\dagger}$

This is the outer product formula for Po V=GI(A) because Sun-iung is an orthonormal basis for GI(A) AtA: similar.

Vector form: for its we have same singular vectors reciprocal singular values

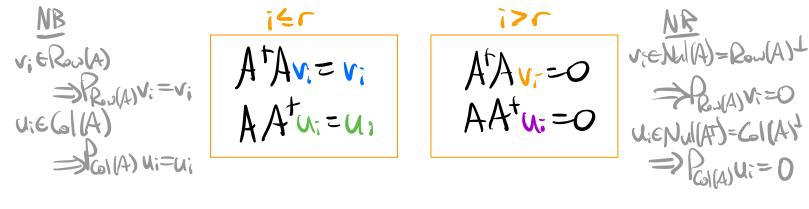
At Av. = At (o.u.) = o. At u. = o. - o. v. = v.

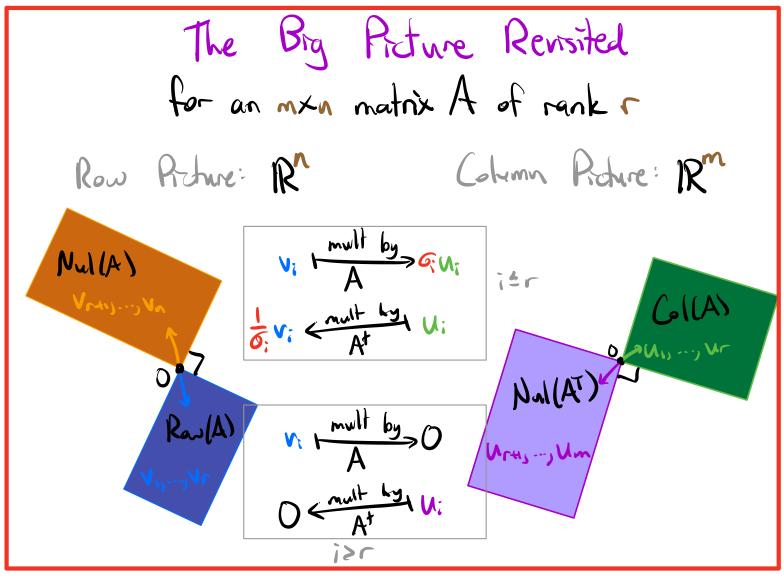
 $AA^{\dagger}u_i = A\left(\frac{1}{\sigma_i}v_i\right) = \frac{1}{\sigma_i}Av_i = \frac{1}{\sigma_i}\cdot\sigma_iu_i = u_i$

But for it we have

 $A^{\dagger}A_{i} = A^{\dagger} \cdot 0 = 0 \qquad (v_{i} \in Nul(A))$

 $AA^{\dagger}u_{\tau} = A \cdot 0 = 0 \qquad (u_{i} \in Nul(A^{\dagger}) = Nul(A^{\dagger}))$





Recall: A projection matrix Pr is the identity matrix $\Leftrightarrow V$ is all of \mathbb{R}^n

Consequence:

• AtA=In
$$\Longrightarrow$$
 A has full column rank
$$(Row(A) = Nul(A)^{\perp} = 503^{\perp} = \mathbb{R}^{n})$$

NB: This shows that:

· A has full row rank (See HW6#11 for the "E" implications.)

$$A = \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} \qquad A^{+} = \frac{1}{300} \begin{pmatrix} -5 & 10 \\ -5 & 10 \\ 10 & 10 \end{pmatrix}$$

$$A^{\dagger}A = \frac{1}{300} \begin{pmatrix} -5 & 10 \\ 10 & 10 \\ 10 & 10 \end{pmatrix} \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} = \begin{pmatrix} 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \end{pmatrix}$$

$$AA^{+} = \frac{1}{300} \begin{pmatrix} -10 & 10 & -10 & 10 \\ 10 & 5 & 10 & 5 \end{pmatrix} \begin{pmatrix} -5 & 10 \\ -5 & 10 \\ 10 & 10 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Now we can compute exactly what Atb is: Prop. For any bolk, &=Atb is the shortest least-squares solution of Ax=b. Proof: First note Ax=AA+b= projection of b onto CI(A) => $\hat{x} = A^{\dagger}b$ solves $A\hat{x} = b_{G(A)}$ => x a least-squares solution of Ax=b. Note &= = viutb+ --+ + vrutb = = (n'.p) 1 + --+ or (n.p) 12 2 (V) (Y) E Span { V , ..., Vr } = Row (A). Any other solution &' has the form x'=x+y for SeNN(V) (The least-squares solutions are the solutions of AR= bca(A).) Note yERan(A) => x·y=0. K112= 12+y12 = (x+y). (x+y) = x.x+2xy + y-y

=> & is the shortest

 $A^{+} = \left(\frac{1}{3}, \frac{1}{3},$

The shortest least-squares solution of Ax=b=(3) $Bx=A+b=\frac{1}{4}(1)(3)=(1)$ All other least-squares solutions Aither by Nul(A) = Span S(-1)3.

shortest vector or anen line