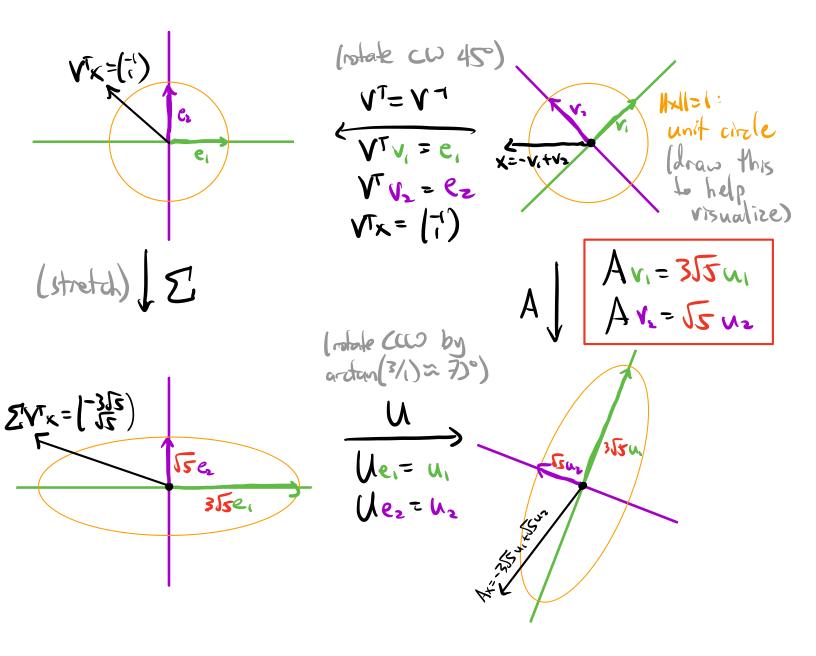
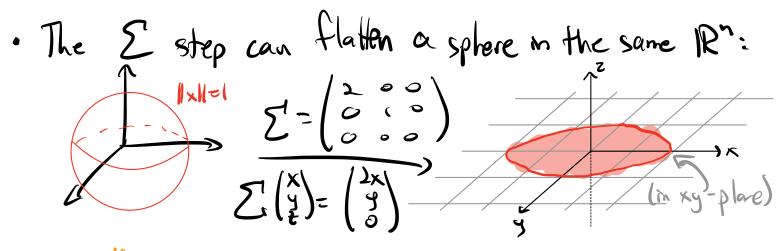


 $5VD: A = \begin{pmatrix} 3 & 0 \\ 4 & 5 \end{pmatrix} = U\Sigma V^T$ for $\mathcal{U} = \frac{1}{\sqrt{3}} \begin{pmatrix} u & u \\ 1 & \frac{1}{\sqrt{3}} \end{pmatrix} \quad \mathcal{V} = \frac{1}{\sqrt{3}} \begin{pmatrix} u & v \\ 1 & \frac{1}{\sqrt{3}} \end{pmatrix} \quad \mathcal{Z} = \begin{pmatrix} u & v \\ \frac{3\sqrt{3}}{\sqrt{3}} \end{pmatrix}$ To evaluate $Ax = U\Sigma V^T x^2$ (1) multiply by VT (2) multiply by Zi (3) multiply by U But U and VT are orthogonal, so these just rotate Alip. Ax= (1) rotate/ Plip (2) stretch (3) rotate/ Plip

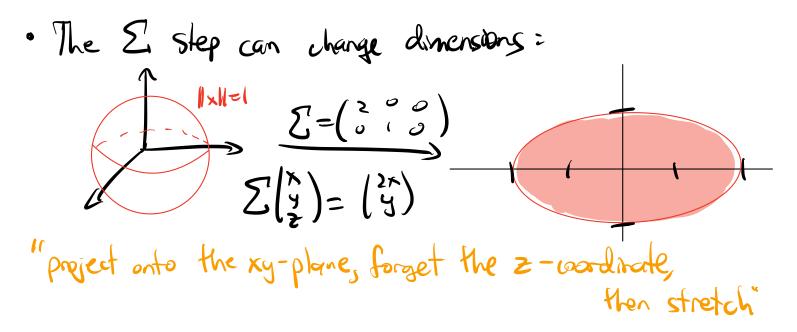


Notes / careats:

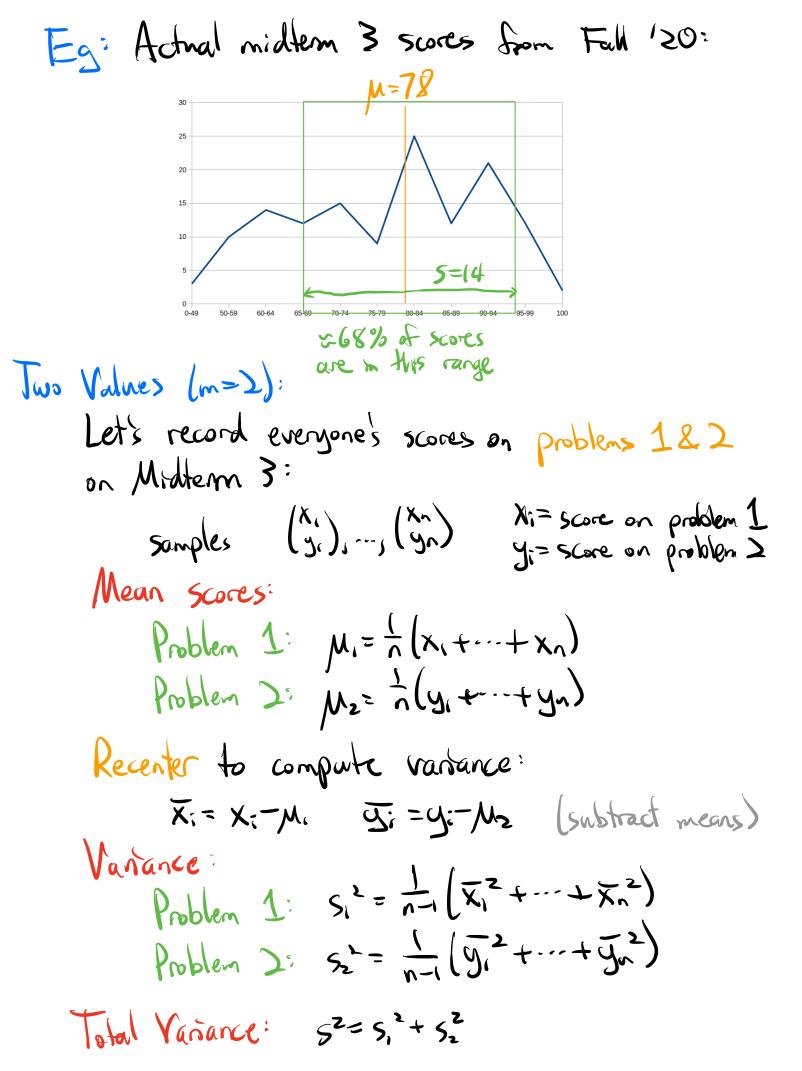
- Diagonalization: start & end in Swi, we? basis
 SVD: start with Svi, ue? & end with Eugue? basis
 Different bases!
- The VT& U steps preserve lengths & angles (rotations / Flips) ~> easier to visualize.

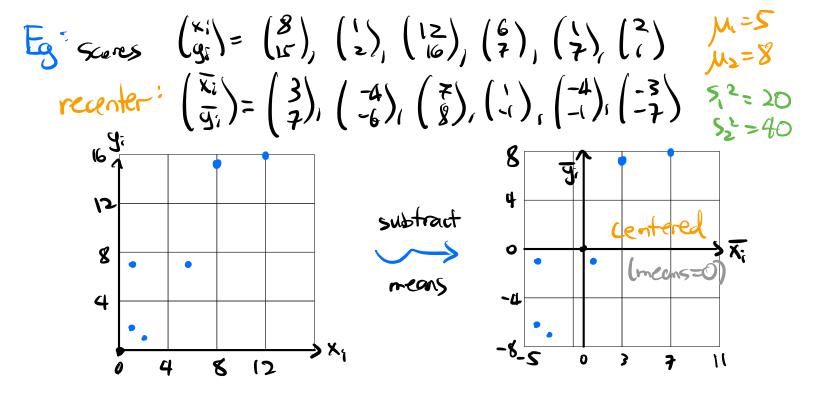


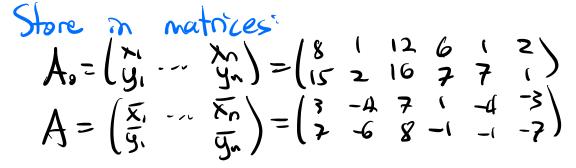
"project onto the xy-plane, then stretch"



Principal Component Analysis (PCA) This is "SVD+QO in stats language". -> it's often how SVD (or "Inear algebra") is used in statistics & data analysis. -> it makes precise statements about fitting data to lines/planes/etc and how good the fit is Idea: If you have a samples of m values each us columns of an mxn data matrix Let's introduce some terminology from statistics. One Value (m=1): Let's record everyone's scores on Middlerm 3= samples X, Xn Mean (average): M= - (X,+...+Xn) Variance: $s^2 = \frac{1}{n-1} \left[(x_1 - \mu)^2 + \dots + (x_n - \mu)^2 \right]$ Standard Derivation: S= Transance This fells you have "spaced out" the samples are: ≈68% of samples are within ±s of the mean. Where do these formulas come from? Take a state class!







evariance Matrix:

$$S = \frac{1}{n-1} AAT = \frac{1}{n-1} \begin{pmatrix} (row 1) \cdot (row 1) & (row 1) \cdot (row 2) \\ (row 2) \cdot (row 2) & (row 2) \end{pmatrix}$$

$$= \frac{1}{n-1} \begin{pmatrix} x_1^2 + \dots + x_n^2 & \overline{x_1y_1} + \dots + \overline{x_ny_n} \\ \overline{x_1y_1} + \dots + \overline{x_ny_n} & \overline{y_1^2} + \dots + \overline{y_n^2} \end{pmatrix}$$
The diagonal entries are the variances:

$$s_1^2 = \frac{1}{n-1} (\overline{x_1^2} + \dots + \overline{x_n^2}) \quad s_2^2 = \frac{1}{n-1} (\overline{y_1^2} + \dots + \overline{y_n^2})$$
The trace is the total variance:

$$Tr(S) = s_1^2 + s_2^2 = s^2$$
The off-diagonal entries are called covariances.
Eq. the (1,2) - entry is
(row 1) (row 2) = \frac{1}{n-1} (\overline{x_1y_1} + \dots + \overline{x_ny_n})
It this is positive then $\overline{x_1} \leq \overline{y_1}$ generally have
the same sign: if you did above average on P1

- then you likely did above average on P2 too, & vice-versa. The values are correlated.
- If this is negative then X: I J; generally have opposite signs: if you did above average on P1 then you likely did below average on P2, & vice-versa. The values are anti-correlated.
- If this is almost zero then the values are not correlated.

In our case:

$$S = \frac{1}{5} AA^{T} = \begin{pmatrix} 25 & 25 \\ 25 & 40 \end{pmatrix} \quad S_{2}^{2} = 40$$

$$(1,2) - covariance = 25 > 0; people who did above
average on PL likely did above average on P2.
The SVD will tell us which directions have the
largest & smallest variance.
$$(column means = 0)$$
Def: Let A be a recentered data matrix

$$A = (d_{1} \cdot d_{n}) \quad where \quad d_{1} = \begin{pmatrix} x_{11} \\ x_{1m} \end{pmatrix} = i^{12} recentered data point
Let $S = \frac{1}{n-1} AA^{T}$ be the covariance matrix.
Let $u \in \mathbb{R}^{m}$ be a unit vector.
The variance in the u-direction is

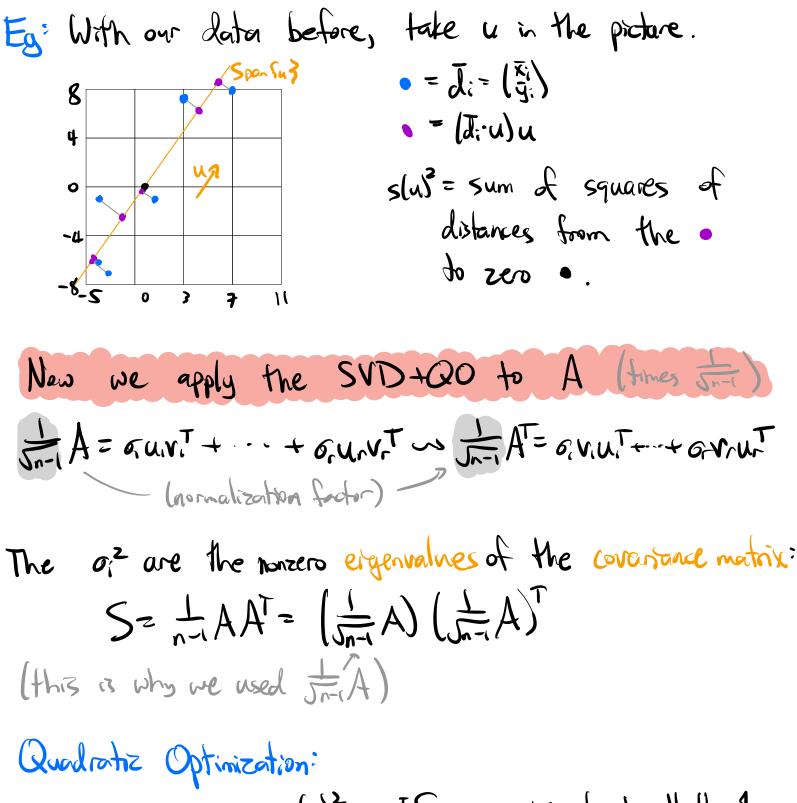
$$S(u)^{2} = u^{T} S u$$
NB: $S(u)^{2} = u^{T} Lat = \frac{1}{n-1} (u^{T}A)(A^{T}u) = \frac{1}{n-1} (A^{T}u)^{T} (A^{T}u)$

$$= \frac{1}{n-1} (A^{T}u) \cdot (A^{T}u) = \frac{1}{n-1} (u^{T}A)(A^{T}u) = \frac{1}{n-1} (A^{T}u)^{T} (A^{T}u)$$

$$Since A^{T}u = \begin{pmatrix} -J^{T} \\ -J^{T} \\ -J^{T} \end{pmatrix} u = \begin{pmatrix} J_{1} \cdot u \\ J_{n} \cdot u \end{pmatrix} we get$$

$$S(u)^{2} = u^{T} Su = \frac{1}{n-1} ((J_{1} \cdot u)^{2} + \dots + (J_{n} \cdot u)^{2})$$$$$$

$$NB: The mean of dis..., dn is zero, so $0=d_1+...+d_n$
(each coordinate has mean $0 \implies sums to 0$).
Hence $0 = 0 \cdot u = (d_1+...+d_n) \cdot u = (d_1\cdot u) + ...+(d_n\cdot u)$
so it makes serve to compute the variance of
these numbers $(d_1\cdot u)_{1}, (d_1\cdot u)$ with mean $2ero:$
 $s(u)^2 = \frac{1}{n-1}((d_1\cdot u)^2 + ...+(d_n\cdot u)^2)$
Eq: If $u = (b) = e_1$ then $d_1\cdot u = (\frac{x}{3}; b) \cdot (b) = x_{1,3}$ so
 $s(u)^2 = s(e_1)^2 = \frac{1}{n-1}(x^2 + ...+x_n^2) = s_1^2$
This is just the variance of the xis.
In general, $s(e_1)^2 = s_1^2$
Produce: Recall that if u is a unit vector then
 $|v\cdot u|u = projection of v onto Spanful
 $\implies (v\cdot u)^2 = (v\cdot u)^2 |u|u|^2 = |u|v\cdot u|u|^2 = |ergth^2 of the
projection of v onto Spanful
 $(\frac{1}{2}u)u = \frac{1}{n-1}u^2$
 $(\frac{1}{2}u)u = \frac{1}{2}(\frac{1}{2}u)^2$
 $(\frac{1}{2}u)u = \frac{1}{2}(\frac{1}{2}u)^2$$$$$



Us maximizes $s(u)^2 = u^T S u$ subject to ||u|| = 1with maximum value σ_i^2

Therefore:

U, is the direction of greatest variance $G_1^2 = s(u_1)^2 = variance$ in the u_-direction

