

# Subspaces

Orientation: We're developing machinery to "almost solve"  $Ax=b$  (least squares)

So far, to every matrix  $A$  we have associated two spans:

(1) the span of the columns / all  $b$  such that  $Ax=b$  is consistent

(2) the solution set of  $Ax=0$

The first arises naturally as a span / it is already in parametric form. The second required Work (elimination) to write as a span - it is a solution set, so it is in implicit form.

The notion of subspaces puts both on the same footing. This formalizes what we mean by "linear space containing 0".

Fast-forward:

↙ same picture

Subspaces  
are spans

and

Spans are  
subspaces.

Why the new vocabulary word?

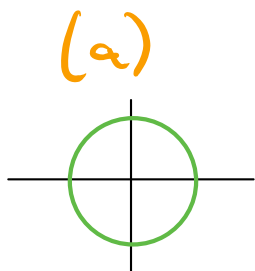
When you say "span" you have a spanning set of vectors in mind (parametric form). This is not the case for the solutions of  $Ax=0$ .

Subspaces allow us to discuss spans without computing a spanning set. Subspace = Span { ??? }

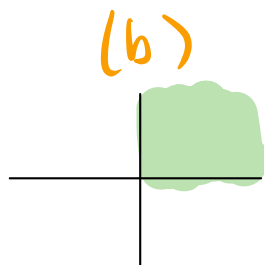
They also give a criterion for a subset to be a span.

Def: A subset of  $\mathbb{R}^n$  is any collection of points.

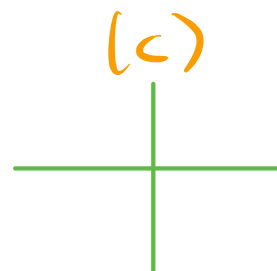
Eg:



$$\{(x, y) : x^2 + y^2 = 1\}$$



$$\{(x, y) : x, y \geq 0\}$$



$$\{(x, y) : xy = 0\}$$

Def: A subspace is a subset  $V$  of  $\mathbb{R}^n$  satisfying:

(1) [closed under +] If  $u, v \in V$  then  $u+v \in V$

(2) [closed under scalar  $\times$ ]

If  $u \in V$  and  $c \in \mathbb{R}$  then  $cu \in V$

(3) [contains 0]  $0 \in V$

These conditions characterize linear spaces containing 0 among all subsets.

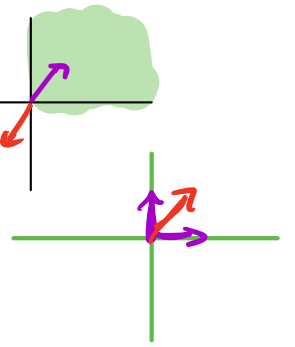
NB: If  $V$  is a subspace and  $v \in V$  then  $0 = 0v$  is in  $V$  by (2), so (3) just means  $V$  is nonempty

Eg: In the subsets above:

(a) fails (1), (2), (3)

(b) fails (2):  $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \in V$  but  $-1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin V$

(c) fails (1):  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \in V$  but  $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin V$



Here are two "trivial" examples of subspaces:

Eg:  $\{0\}$  is a subspace

(1)  $0 + 0 = 0 \in \{0\}$  ✓

(2)  $c \cdot 0 = 0 \in \{0\}$  ✓

(3)  $0 \in \{0\}$  ✓

NB  $\{0\} = \text{Span}\{\}$ : it is a span

Eg:  $\mathbb{R}^n = \{\text{all vectors of size } n\}$  is a subspace

(1) The sum of two vectors is a vector. ✓

(2) A scalar times a vector is a vector. ✓

(3)  $0$  is a vector. ✓

NB  $\mathbb{R}^n = \text{Span}\{e_1, e_2, \dots, e_n\}$

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix} \quad \dots \quad e_n = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ 0 \end{pmatrix}$$

Eg:  $V = \{(x, y, z) : \text{defining condition } x+y=z\}$

The defining condition tells you if  $(x, y, z)$  is in  $V$  or not.

(1) We have to show that if  $(x_1, y_1, z_1) \in V$  and  $(x_2, y_2, z_2) \in V$  then their sum is in  $V$ . That means it also satisfies the defining condition.

$$\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{pmatrix}$$

Is  $z_1 + z_2 = (x_1 + x_2) + (y_1 + y_2)$ ? Yes, because  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  satisfy the defining condition:  $x_1 + y_1 = z_1$ ,  $x_2 + y_2 = z_2$

(2) We have to show that if  $(x, y, z) \in V$  and  $c \in \mathbb{R}$  then  $c(x, y, z) \in V$ .

$$c \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} cx \\ cy \\ cz \end{pmatrix} \quad \text{is} \quad cx + cy = cz?$$

Yes, because  $x + y = z$ .

(3) Is  $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in V$ ? Does it satisfy the defining condition?

$$0 + 0 = 0$$

Since  $V$  satisfies the 3 criteria, it is a subspace. ✓



defining condition

Eg:  $V = \{(x, y) : x \geq 0, y \geq 0\}$

(1) We have to show that if  $(x_1, y_1) \in V$  and  $(x_2, y_2) \in V$  then  $(x_1 + x_2, y_1 + y_2) \in V$ .

Is  $x_1 + x_2 \geq 0$ ? Yes, because  $x_1 \geq 0, x_2 \geq 0$

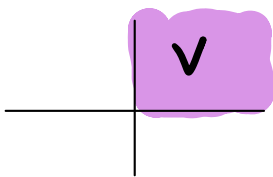
Is  $y_1 + y_2 \geq 0$ ? Yes, because  $y_1 \geq 0, y_2 \geq 0$ .

(3) Is  $(0, 0) \in V$ ? Yes:  $0 \geq 0$  and  $0 \geq 0$ .

(2) We have to show that if  $(x, y) \in V$  and  $c \in \mathbb{R}$  then  $(cx, cy) \in V$ .

Is  $cx \geq 0$ ? Not necessarily!

Fails if  $c < 0, x > 0$ .



Good: this is not a picture of a span.

In practice you will rarely check that a subset is a subspace by verifying the axioms.

**Fact:** A span is a subspace

**Proof:** Let  $V = \text{Span}\{v_1, \dots, v_n\}$ .

Here the defining condition for a vector to be in  $V$  is that it is a linear combination of  $v_1, \dots, v_n$ .

(1) We need to show that if  $c_1v_1 + \dots + c_nv_n \in V$  &  $d_1v_1 + \dots + d_nv_n \in V$  then their sum is in  $V$ : the sum of two linear combos of  $v_1, \dots, v_n$  is a linear combo.

$$(c_1v_1 + \dots + c_nv_n) + (d_1v_1 + \dots + d_nv_n) \\ = (c_1 + d_1)v_1 + \dots + (c_n + d_n)v_n \in V \quad \checkmark$$

(2) We need to show that if  $c_1v_1 + \dots + c_nv_n \in V$  and  $d \in \mathbb{R}$  then the product is in  $V$ .

$$d(c_1v_1 + \dots + c_nv_n) = (dc_1)v_1 + \dots + (dc_n)v_n \in V \quad \checkmark$$

(3) Every span contains  $0$ :

$$0 = 0v_1 + \dots + 0v_n \quad \checkmark$$

**Conversely,** suppose  $V$  is a subspace.

If  $v_1, \dots, v_n \in V$  and  $c_1, \dots, c_n \in \mathbb{R}$  then:

$$c_1v_1, \dots, c_nv_n \in V \quad \text{by (2)}$$

$$c_1v_1 + c_2v_2 \in V \quad \text{by (1)}$$

$$(c_1v_1 + c_2v_2) + c_3v_3 \in V \quad \text{by (1)}$$

$\vdots$

$$c_1v_1 + \dots + c_nv_n \in V$$

So  $\text{Span}\{v_1, \dots, v_n\}$  is contained in  $V$ .

Choose enough  $v_i$ 's to fill up  $V$ , and you get:

Subspaces  
are spans

and

Spans are  
subspaces.

Def: The **column space** of a matrix  $A$  is the span of its columns.

Notation:  $\text{Col}(A) = \text{Span}\{\text{cols of } A\}$

This is a subspace of  $\mathbb{R}^m$   $m = \# \text{ rows}$   
(each column has  $m$  entries)

$\rightsquigarrow$  **column picture.**

Since a column space is a span & a span is a subspace, a **column space** is a **subspace**.

Eg:  $\text{Col} \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \right\}$

It's easy to translate between spans & column spaces.

Eg:  $\text{Span} \left\{ \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\} = \text{Col} \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$

NB:  $\text{Col}(A) = \{Ax : x \in \mathbb{R}^n\}$

because " $Ax$ " is just a LC of the cols of  $A$ .

Translation of the column picture criterion for consistency:

$$Ax=b \text{ is consistent} \iff b \in \text{Col}(A)$$

(this is just substituting "Col(A)" for "the span of the columns of A")

Def: The null space of a matrix A is the solution set of  $Ax=0$ .

Notation:  $\text{Nul}(A) = \{x \in \mathbb{R}^n : Ax=0\}$

This is a subspace of  $\mathbb{R}^n$   $n = \# \text{columns}$   
( $n = \# \text{variables}$  and  $\text{Nul}(A)$  is a solution set)

$\rightsquigarrow$  row picture

Fact:  $\text{Nul}(A)$  is a subspace

Of course we also know  $\text{Nul}(A)$  is a span, but we can verify this directly.

Proof: The defining condition for  $v \in \text{Nul}(A)$  is that  $Av=0$ .

(1) Say  $u, v \in \text{Nul}(A)$ . Is  $u+v \in \text{Nul}(A)$ ?

$$A(u+v) = Au + Av = 0 + 0 = 0 \quad \checkmark$$

(2) Say  $u \in \text{Nul}(A)$  and  $c \in \mathbb{R}$ .

Is  $cu \in \text{Nul}(A)$ ?

$$A(cu) = c(Au) = c \cdot 0 = 0 \quad \checkmark$$

(3) Is  $0 \in \text{Nul}(A)$ ?

$$A0 = 0 \quad \checkmark$$

This is an example of a **subspace** that does **not** come with a **spanning set**!

→ It's much more natural to consider it as a subspace when reasoning about it.

How to produce a spanning set for a null space?

$\text{Nul}(A)$

parametric  
vector form

(Gauss-Jordan  
elimination)

Work

$\text{Span}\{\dots\}$

Eg: Write  $\text{Nul}(A)$  as a span for

$$A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \end{bmatrix}$$

This means solving  $Ax = 0$  (homogeneous equation).

$$\left[ \begin{array}{cccc|c} 1 & 2 & 2 & 1 & 0 \\ 2 & 4 & 1 & -1 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc|c} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{array} \right]$$

parametric form  $\rightarrow \begin{cases} x_1 = -2x_2 + x_4 \\ x_2 = x_2 \\ x_3 = -x_4 \\ x_4 = x_4 \end{cases}$

PVF  $\rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 1 \\ 0 \\ -1 \\ 1 \end{pmatrix}$

$$\Rightarrow \text{Nul}(A) = \text{Span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -1 \\ 1 \end{pmatrix} \right\}$$

**NB:** Any two non-collinear vectors span a plane, so  $\text{Nul}(A)$  will have many different spanning sets.

eg  $\text{Nul}(A) = \text{Span} \left\{ \underset{\substack{\uparrow \\ \text{sum}}}{\begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}}, \underset{\substack{\uparrow \\ \text{difference}}}{\begin{pmatrix} -3 \\ 1 \\ -1 \\ 1 \end{pmatrix}} \right\}$

More on this later.

**NB:** Likewise for the column space: eg.

$$\text{Col} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \text{Col} \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} = \text{Col} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \text{(xy-plane)}$$

## Implicit vs Parametric form:

- $\text{Col}(A)$  is a **span**:

$$\text{Col}(A) = \{ x_1 v_1 + \dots + x_n v_n : \overset{\text{parameters}}{x_1, \dots, x_n} \in \mathbb{R} \}$$

where  $v_1, \dots, v_n$  are the columns of  $A$ .

↪ **parametric form**

- $\text{Nul}(A)$  is a **solution set**:

$$\text{Nul} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \end{bmatrix}$$

$$= \left\{ (x_1, x_2, x_3, x_4) : \begin{array}{l} x_1 + 2x_2 + 2x_3 + x_4 = 0 \\ 2x_1 + 4x_2 + x_3 - x_4 = 0 \end{array} \right\}$$

↪ **implicit form**

In practice you will (almost) always write a subspace as a column space/span or a null space. **Which one?**

- **parameters?** ↪  $\text{Col}(A)$  / Span
- **equations?** ↪  $\text{Nul}(A)$

Once you're done this, you can ask a **computer** to do computations on it!

Eg:  $V = \{(x, y, z) : x + y = z\}$

This is defined by the equation  $x + y = z$ .

rewrite:  $x + y - z = 0$

$$\leadsto V = \text{Nul} \begin{bmatrix} 1 & 1 & -1 \end{bmatrix}$$

Eg:  $V = \left\{ \begin{pmatrix} 3a+b \\ a-b \\ b \end{pmatrix} : a, b \in \mathbb{R} \right\}$

This is described by parameters. Rewrite:

$$\begin{pmatrix} 3a+b \\ a-b \\ b \end{pmatrix} = a \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\leadsto V = \text{Span} \left\{ \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right\} = \text{Col} \begin{bmatrix} 3 & 1 \\ 1 & -1 \\ 0 & 1 \end{bmatrix}$$

This is also how you should verify that a subset is a subspace.

Of course, if  $V$  is not a subspace then you can't write it as  $\text{Col}(A)$  or  $\text{Nul}(A)$ . In this case you should check that it fails one of the axioms.

Eg: Is  $V = \{(x, y, z) : x + y = z + 1\}$  a subspace?

No, (P3) fails:  $0 + 0 \neq 0 + 1$ , so  $0 \notin V$ .