The Method of Least Squares

Setup: you have a matrix equation Ax = b which is (generally) inconsistent. What is the best approximate solution?

What do we mean by "best approximate solution"?

Det: & is a least squares solution of Ax=b if 11b-Ax1 is minimized over all vector \hat{x} .

This means Ax is as close as possible to b.

NB: $Col(A) = \{A\hat{x}: \hat{x} \in \mathbb{R}^n\}$ so $A\hat{x}$ is just the closest vector to b in V = Col(A).

closest vector to b in V=Col(A).
This is the orthogonal projection!

Ax=b, & V=61(A)

How do we compute by and \hat{x} ?

→ If \hat{x} is any soln of ATA \hat{x} = ATB, then $A\hat{x}$ = by.

So X is a least-squares solution!

Procedure (Least Squares): To find the least squares solution(s) of Ax=b: (1) Solve the normal equation ATAX=ATB (2) Any solution & is a least-squares solv, and $b_v = A\hat{x}$ for V = G(A). NB: The error is the distance from Ax to b: emor = ||b-Ax|| = ||b-by|| = ||by||Recall that 116-A211 = 116 pell is minimized? if but = (2) then Taztbztcz, or equirelently but but = a2+62+c2 & the minimized quantity.

The least-squares solution(s) minimize but bu

This is why it's called a least squares solution: we're minimizing the sum of the squares of the entries of b-A2.

Eg: Find the least-squares solution of Ax = bfor $A = \begin{pmatrix} 0 & 1 \\ 2 & 1 \end{pmatrix}$ $b = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}$.

(1)
$$ATA = \begin{pmatrix} 5 & 3 \\ 3 & 3 \end{pmatrix} ATB = \begin{pmatrix} 6 \\ 6 \end{pmatrix}$$

$$\begin{pmatrix} 5 & 3 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 5 & 3 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 2 & 1 & -3 \\ 3 & 3 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 2 & 1 & -3 \\ 3 & 3 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 2 & 1 & -3 \\ 5 & 3 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 3 & 3 & | 6 \\ 2 & 1 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 4 & 1 & -3 \\ 5 & 1 & | 6 \end{pmatrix} \text{ mef}$$

$$\begin{pmatrix} 5 & 2 & | 6 & | 6 \\ 2 & 1 & | 6 \end{pmatrix} \text{ mef}$$

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$$\begin{pmatrix} 6 & 1 & | 6 & | 6 & | 6 & | 6 \\ |$$

[demo: where is x?]

Eg: Find the least-squares solutions of
$$Ax=b$$
 for $A=\begin{pmatrix} 1 & -1 & -1 \\ 2 & -1 & -1 \end{pmatrix}$ and $b=\begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

(1) $ATA=\begin{pmatrix} 6 & 6 & 6 \\ 6 & 6 & 18 \end{pmatrix}$ $ATb=\begin{pmatrix} 4 \\ -1 \\ 2 \end{pmatrix}$

(2) $X=\begin{pmatrix} 2/3 \\ -1/3 \\ 0 \end{pmatrix}+X_3\begin{pmatrix} -1 \\ -2 \\ 1 \end{pmatrix}$

In this case there are infinitely many least-squares solutions!

$$b_{v} = A\hat{x}$$
 for any \hat{x} . Take $\hat{x} = \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \end{pmatrix}$

$$b_{v} = \begin{pmatrix} 1 & -1 & -1 \\ 2/3 & -1/3 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

Pr= P-pr= 0

So the error is zero — the equation Ax=b was consistent after all!

(Compare W7L2 pp. 4-5)

Observation 1:

Ax=b has a unique least-squares soh A has full column rank!

This is exactly when ATAX=ATb has a unique solution (ATA is invertible).

Otherwise, there are infinitely many leastsquares solvs. This means 116-A211 is

minimized for any such X: by = A2 for any solution X. (There can't be zero least-squares solutions!

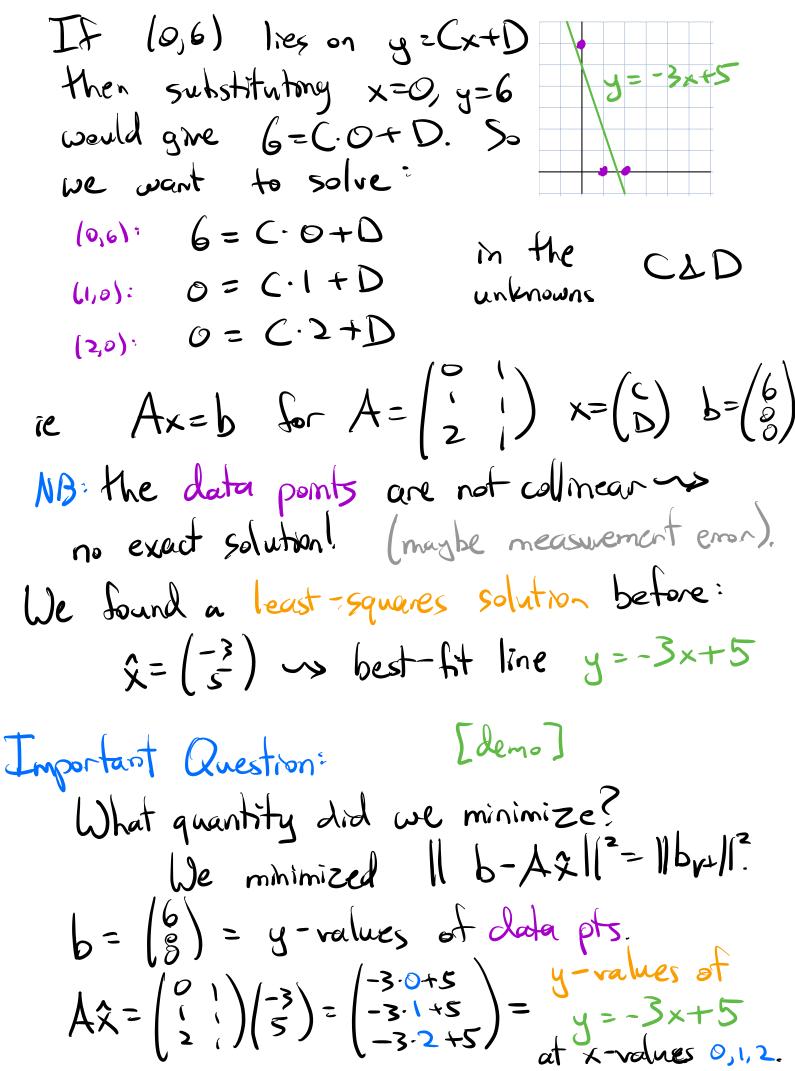
ATAX = ATB is always consistent.) Observation 2: If Ax=b is consistent, then (least squares) = (ordinary) - solutions). Indeed, a least-squares soln is just a

Indeed, a least-squares soln is just a soln of $A\hat{x}=bv$ (V=G(A)), and $b=bv \Longrightarrow b\in G(A) \Longleftrightarrow Ax=b$ is consistent.

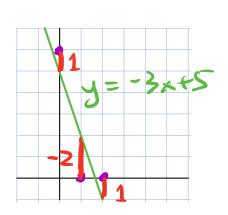
Least-squares is often weful for fitting dated to a model.

Eg (linear regression):

Find the best-fit line y= (x+D) thru the data points (0,6), (1,0), (2,0).



So
$$b_{v1}=b-A\hat{x}=\begin{pmatrix} -\frac{1}{2} \\ vertical distances \\ from $y=-3x+5$ to the data points$$



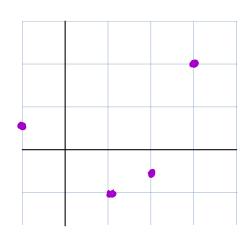
We minimized the sum of the squares of the vertical distances (the error).

Eg (best-fit parabola):

Find the best-fit parabola $g = Bx^2 + Cx + D$ thru the data points (-1,1/2), (1,-1), (2,-1/2), (3,2)

Substitute the data points for x & yes want to solve

$$(3,2)$$
: $2 = \beta(3)^2 + C(3) + D$



Let's find the least-squares solution.

$$b = \begin{pmatrix} 1/2 \\ -1 \\ -1/2 \end{pmatrix} = y - values et data pts.$$

$$Ax = \begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & 1 \\ 4 & 2 & 1 \\ 9 & 3 & 1 \end{pmatrix} \begin{pmatrix} 53/88 \\ -39/440 \\ -41/44 \end{pmatrix} = \begin{pmatrix} 53/88(-1)^{2} + \frac{329}{490}(-1) - \frac{4}{44} \\ 53/88(-1)^{2} + \frac{32$$

$$= \frac{y - values}{y = \frac{53}{82}x^2 - \frac{379}{440}x - \frac{41}{44}} \text{ at } x - values$$

$$= \frac{53}{82}x^2 - \frac{379}{440}x - \frac{41}{44} \text{ at } x - values$$

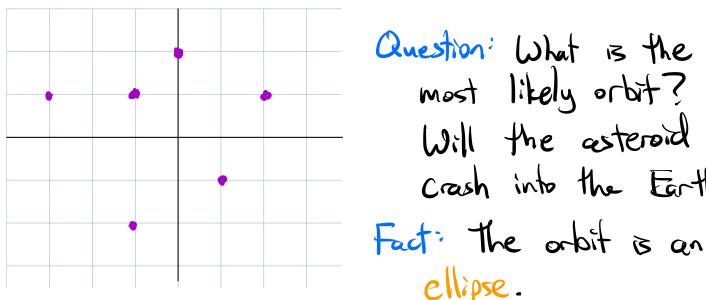
So by = b-Ax = vertical distances from the graph to the data points, like before.

This same method works to find a best-fit function of the form y=Af+Bg+Ch+... where figh,are really any functions! Just plug the x-values of your data points into figh - I mear equations In A,B, C, --

Eg (best-fit trogonometric function): see \$6.5 in ILA for an example.

This real-life example of Gauss was in the first lecture:

Eg: An asteroid has been observed at condinates: (0,2), (2,1), (1,-1), (-1,-2), (-3,1), (-1,1)



Question: What is the most likely orbit?
Will the exteroid crash into the Earth?

ellipse.

Equation for an ellipse: $X^2 + By^2 + Cxy + Dx + Ey + F = 0$ For our points to lie on the ellipse, substitute the wordinates into (x,y) us these should hald:

Move the constants to the RHS us this is Ax=b

$$A = \begin{pmatrix} 4 & 0 & 0 & 1 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & 1 & -3 & 1 \\ 1 & -1 & -1 & 1 & 1 \end{pmatrix} \quad X = \begin{pmatrix} 3 \\ -4 \\ -1 \\ -9 \\ -1 \end{pmatrix}$$

Least-squares solution: [demo]
$$\hat{X} = \begin{pmatrix} \frac{4.65}{266} & \frac{89}{133} & \frac{201}{133} & \frac{123}{266} & \frac{687}{133} \end{pmatrix}$$

$$\rightarrow x^2 + \frac{405}{266}y^2 - \frac{89}{133}xy + \frac{201}{133}x - \frac{123}{266}y - \frac{687}{133} = 0$$

What quantity did we minimize? 16-A2) or 14x-611

$$A\hat{x} - b = \begin{pmatrix} 4 & 0 & 0 & 1 & 1 \\ 1 & 2 & 2 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 4 & 2 & -1 & -2 & 1 \\ 1 & -3 & 1 & -3 & 1 \\ 1 & -1 & -1 & 1 & 1 \end{pmatrix} \hat{x} - \begin{pmatrix} -4 \\ -1 \\ -1 \\ -9 \\ -1 \end{pmatrix}$$

$$\begin{pmatrix} 0^{2} + \frac{465}{266}(2)^{2} - \frac{89}{133}(9)(2) + \frac{261}{133}(9) - \frac{123}{266}(2) - \frac{687}{133} \\ 2^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(2)(1) + \frac{261}{133}(1) - \frac{123}{266}(1) - \frac{687}{133} \\ 1^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(2) + \frac{261}{133}(-1) - \frac{123}{266}(2) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1) - \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{261}{133}(-1)(1) + \frac{123}{266}(1) - \frac{687}{133} \\ (-1)^{2} + \frac{465}{266}(1)^{2} - \frac{89}{133}(-1)(1) + \frac{89}{133}(-1)(1) + \frac{123}{133}(-1)(1) + \frac{123}{133}(-1)(1) + \frac{123}{133}(-1)(1) + \frac{123}{133}(-1)(1) + \frac$$

This was what you get by substituting the x- and y-values of the data points into the LHS of

$$x^{2} + \frac{405}{266}y^{2} - \frac{89}{133}xy + \frac{201}{133}x - \frac{123}{266}y - \frac{687}{133} = 0$$

It's the distance from zero. [demo]

Upshot: You're minimizing 116-AxI; it's up to you to interpret that quantity in your original problem.