

## Math 218D Problem Session - Solutions

Week 8

### 1. Orthogonal matrices

A **orthogonal matrix** is a *square* matrix  $Q$  whose columns form an *orthonormal* set. Alternately, it is a square matrix  $Q$  such that  $Q^T Q = I_n$ .

a)  $Q = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  is not an orthogonal matrix, since  $Q^T Q = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$ .

b)  $Q = \begin{pmatrix} 2 & 1 \\ -2 & 1 \end{pmatrix}$  is not an orthogonal matrix, since  $Q^T Q = \begin{pmatrix} 8 & 0 \\ 0 & 2 \end{pmatrix}$ .

c)  $Q = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$  is an orthogonal matrix, since  $Q^T Q = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .

## 2. Rotation and reflection

$$R_\theta = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}.$$

a)  $R_\theta^T R_\theta = \begin{pmatrix} \cos(\theta)^2 + \sin(\theta)^2 & 0 \\ 0 & \cos(\theta)^2 + \sin(\theta)^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$

b)  $R_{\pi/6} = \begin{pmatrix} \sqrt{3}/2 & -1/2 \\ 1/2 & \sqrt{3}/2 \end{pmatrix}$ , so  $R_{\pi/6}(1, 0) = (\sqrt{3}/2, 1/2)$  and  $R_{\pi/6}(1, 1) = (\frac{\sqrt{3}-1}{2}, \frac{\sqrt{3}+1}{2})$ .

c) The angle between  $(1, 0)$  and  $(1, 1)$  is  $\pi/4$ . We want to confirm that the angle between  $u = (\sqrt{3}/2, 1/2)$  and  $v = (\frac{\sqrt{3}-1}{2}, \frac{\sqrt{3}+1}{2})$  is  $\pi/4$ . We use the formula  $\cos(\theta) = \frac{u \cdot v}{\|u\| \|v\|}$  (note that this is not the same  $\theta$  as the variable from the rotation matrix). Compute that  $\|u\| = 1$ ,  $\|v\| = \sqrt{2}$ , and  $u \cdot v = 1$ . Then  $\cos(\theta) = \sqrt{2}/2$ , so  $\theta = \pi/4$ .

Consider a line  $L = \text{Span}\{v\} \subset \mathbb{R}^3$ , and the orthogonal complement plane  $V = L^\perp$ . The **reflection matrix** for **reflection across**  $V$  is the orthogonal matrix

$$Q = I_3 - 2P_L,$$

where  $P_L$  is the projection matrix for  $L$ .

d) The projection matrix is  $P_L = \frac{(0,1,0)(0,1,0)^T}{(0,1,0) \cdot (0,1,0)} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ , so  $Q = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ .

The line  $L$  is the  $y$ -axis, and the plane  $V$  is the  $xz$ -plane. The projection of  $(1, 1, 0)$  on to the  $y$ -axis is  $(0, 1, 0)$ . The reflection of  $(1, 1, 0)$  across the  $xz$ -plane,  $Q(1, 1, 0)$ , is  $(1, -1, 0)$ .

e)  $Q^T Q = (I_3 - 2P_L)^T (I_3 - 2P_L) = (I_3^T - 2P_L^T)(I_3 - 2P_L) = I_3 - 2P_L^T - 2P_L + 4P_L^T P_L$ . Since  $P_L^T = P_L$ , this becomes  $I_3 - 4P_L + 4(P_L)^2$ . Since  $P_L^2 = P_L$ , this becomes  $I_3 - 4P_L + 4P_L = I_3$ . Therefore  $Q^T Q = I_3$ .

### 3. Gram-Schmidt and QR

The vectors  $v_1 = \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}$ ,  $v_2 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$  are a basis for a plane  $V \subset \mathbb{R}^3$ . Set

$$u_1 = v_1, \quad u_2 = v_2 - \frac{u_1 \cdot v_2}{u_1 \cdot u_1} u_1.$$

a)  $u_1 = (1, 2, -2)$ ,  $u_2 = (1, 1, 1) - \frac{(1,1,1) \cdot (1,2,-2)}{(1,2,-2) \cdot (1,2,-2)}(1, 2, -2) = (1, 1, 1) - \frac{1}{9}(1, 2, -2) = (8/9, 7/9, 11/9)$ .

Then  $u_1/\|u_1\| = \frac{1}{3}(1, 2, -2)$ , and  $u_2/\|u_2\| = \frac{1}{\sqrt{234}}(8, 7, 11)$ . The vectors are unit length, and  $(1, 2, -2)$  is orthogonal to  $(8, 7, 11)$ , so these two vectors are orthonormal.

b)  $Q = \begin{pmatrix} 1/3 & 8/\sqrt{234} \\ 2/3 & 7/\sqrt{234} \\ -2/3 & 11/\sqrt{234} \end{pmatrix}$ , and  $A = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -2 & 1 \end{pmatrix}$ .

$$R = Q^T A = \begin{pmatrix} 1/3 & 2/3 & -2/3 \\ 8/\sqrt{234} & 7/\sqrt{234} & 11/\sqrt{234} \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -2 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 1/3 \\ 0 & 26/\sqrt{234} \end{pmatrix}.$$

You could note that  $\sqrt{234} = 3\sqrt{26}$ , to simplify this to  $R = \begin{pmatrix} 3 & 1/3 \\ 0 & \sqrt{26}/3 \end{pmatrix}$ .

You can check  $QR = \begin{pmatrix} 1/3 & 8/\sqrt{234} \\ 2/3 & 7/\sqrt{234} \\ -2/3 & 11/\sqrt{234} \end{pmatrix} \begin{pmatrix} 3 & 1/3 \\ 0 & 26/\sqrt{234} \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -2 & 1 \end{pmatrix}$  to

make sure  $R$  is correct.

c) If  $A = QR$ , then  $Q^T A = Q^T QR$ . Since  $Q^T Q = I$ , this simplifies to  $Q^T A = R$ .

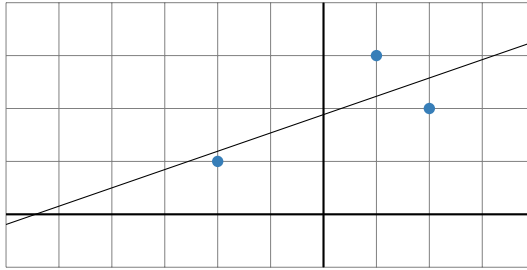
#### 4. Least squares

$$A = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -2 & 1 \end{pmatrix}, \text{ the the least-squares equation is } A^T A \hat{x} = A^T \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}.$$

a)  $A^T A = \begin{pmatrix} 9 & 1 \\ 1 & 3 \end{pmatrix}$  and  $A^T \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \end{pmatrix}$ . The RREF of  $\begin{pmatrix} 9 & 1 & | & 5 \\ 1 & 3 & | & 6 \end{pmatrix}$  is  $\begin{pmatrix} 1 & 0 & | & 9/26 \\ 0 & 1 & | & 49/26 \end{pmatrix}$ .

Therefore  $C = 9/26, D = 49/26$ .

- b) We plot the data points and the least-squares line  $y = \frac{9}{26}x + \frac{49}{26}$ . It may help to note that this line has  $x$ -intercept  $-49/9 \approx -5.44$  and  $y$ -intercept  $49/26 \approx 1.88$



c)  $A \hat{x} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 9/26 \\ 49/26 \end{pmatrix} = \begin{pmatrix} 58/26 \\ 65/26 \\ 31/26 \end{pmatrix}$ . The numbers in the vector  $A \hat{x}$  are the vertical distances between the data points and the best-fit line.

d) The error  $\|A \hat{x} - (3, 2, 1)\|^2$  equals  $\|((58-78)/26, (65-52)/26, (31-26)/26)\|^2 = \frac{1}{676}(20^2 + 13^2 + 5^2) = \frac{400+169+25}{676} = \frac{594}{676} \approx 0.879$ .

e) We solve  $R \hat{x} = Q^T (3, 2, 1)$ , where  $R = \begin{pmatrix} 3 & 1/3 \\ 0 & 26/\sqrt{234} \end{pmatrix}$  and  $Q = \begin{pmatrix} 1/3 & 8/\sqrt{234} \\ 2/3 & 7/\sqrt{234} \\ -2/3 & 11/\sqrt{234} \end{pmatrix}$ .

First,  $Q^T (3, 2, 1) = \begin{pmatrix} 1/3 & 2/3 & -2/3 \\ 8/\sqrt{234} & 7/\sqrt{234} & 11/\sqrt{234} \end{pmatrix} (3, 2, 1) = (5/3, 49/\sqrt{234})$ .

We find the RREF of  $\begin{pmatrix} 3 & 1/3 & | & 5/3 \\ 0 & 26/\sqrt{234} & | & 49/\sqrt{234} \end{pmatrix}$ . We can immediately get

rid of all the denominators by row scaling:  $\begin{pmatrix} 9 & 1 & | & 5 \\ 0 & 26 & | & 49 \end{pmatrix}$ . Then  $\begin{pmatrix} 9 & 0 & | & 81/26 \\ 0 & 26 & | & 49 \end{pmatrix}$ .

Therefore  $C = 9/26, D = 49/26$ .

## 5. Another Gram–Schmidt

$$v_1 = (1, 1, 0), v_2 = (1, 0, 1), v_3 = (0, 1, 1)$$

a) We do Gram–Schmidt:

$$u_1 = (1, 1, 0),$$

$$\begin{aligned} u_2 &= (1, 0, 1) - \frac{(1, 1, 0) \cdot (1, 0, 1)}{(1, 1, 0) \cdot (1, 1, 0)}(1, 1, 0) \\ &= (1, 0, 1) - \frac{1}{2}(1, 1, 0) \\ &= (1/2, -1/2, 1), \end{aligned}$$

$$\begin{aligned} u_3 &= (0, 1, 1) - \frac{(1, 1, 0) \cdot (0, 1, 1)}{(1, 1, 0) \cdot (1, 1, 0)}(1, 1, 0) - \frac{(1/2, -1/2, 1) \cdot (0, 1, 1)}{(1/2, -1/2, 1) \cdot (1/2, -1/2, 1)}(1/2, -1/2, 1) \\ &= (0, 1, 1) - \frac{1}{2}(1, 1, 0) - \frac{1}{3}(1/2, -1/2, 1) \\ &= (-2/3, 2/3, 2/3). \end{aligned}$$

b) The orthonormal vectors are  $\frac{1}{\sqrt{2}}(1, 1, 0)$ ,  $\frac{1}{\sqrt{6}}(1, -1, 2)$ ,  $\frac{1}{\sqrt{3}}(-1, 1, 1)$ . Therefore

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \text{ and } Q = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{6} \\ -1/\sqrt{3} & -1/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & 2/\sqrt{6} & 1/\sqrt{3} \end{pmatrix}.$$

We compute

$$\begin{aligned} R &= Q^T A = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 1/\sqrt{6} & -1/\sqrt{6} & 2/\sqrt{6} \\ -1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 2/\sqrt{2} & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & 3/\sqrt{6} & 1/\sqrt{6} \\ 0 & 0 & 2/\sqrt{3} \end{pmatrix}. \end{aligned}$$

c) Consider the vector  $b = (1, 1, 1)$ . There are three equations

$$b \cdot u_1 = (x_1 u_1 + x_2 u_2 + x_3 u_3) \cdot u_1,$$

$$b \cdot u_2 = (x_1 u_1 + x_2 u_2 + x_3 u_3) \cdot u_2,$$

$$b \cdot u_3 = (x_1 u_1 + x_2 u_2 + x_3 u_3) \cdot u_3.$$

This simplifies to

$$b \cdot u_1 = \|u_1\|^2 x_1,$$

$$b \cdot u_2 = \|u_2\|^2 x_2,$$

$$b \cdot u_3 = \|u_3\|^2 x_3.$$

since  $u_1, u_2, u_3$  are an orthogonal set of vectors.

Recall that  $u_1 = (1, 1, 0)$ ,  $u_2 = (1/2, -1/2, 1)$ ,  $u_3 = (-2/3, 2/3, 2/3)$ . We can solve for  $x_1, x_2$ , and  $x_3$  now:

$$x_1 = \frac{b \cdot u_1}{\|u_1\|^2} = \frac{2}{2} = 1,$$

$$x_2 = \frac{b \cdot u_2}{\|u_2\|^2} = \frac{1}{(3/2)} = 2/3,$$

$$x_3 = \frac{b \cdot u_3}{\|u_3\|^2} = (2/3)/(4/3) = 1/2.$$

In other words,  $(1, 1, 1) = (1, 1, 0) + \frac{2}{3}(1/2, -1/2, 1) + \frac{1}{2}(-2/3, 2/3, 2/3)$ .

**d)** How you could instead solve for these scalars using the formula  $QQ^T = P_{\mathbb{R}^3} =$

$I_3$ ? First, compute  $a = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = Q^T b$ . The formula  $QQ^T = I$  implies that  $Qa =$

$Q(Q^T b) = b$ . Since  $Q$  has columns  $u_1/\|u_1\|, u_2/\|u_2\|, u_3/\|u_3\|$ , this implies that

$$b = Qa = a_1 \frac{u_1}{\|u_1\|} + a_2 \frac{u_2}{\|u_2\|} + a_3 \frac{u_3}{\|u_3\|}.$$

In other words,

$$b = \frac{a_1}{\|u_1\|} u_1 + \frac{a_2}{\|u_2\|} u_2 + \frac{a_3}{\|u_3\|} u_3.$$

Therefore, if you compute  $a = Q^T b$ , and then  $\frac{a_1}{\|u_1\|}, \frac{a_2}{\|u_2\|}, \frac{a_3}{\|u_3\|}$ , you would find scalars which make  $b$  into a linear combination of  $u_1, u_2$ , and  $u_3$ .