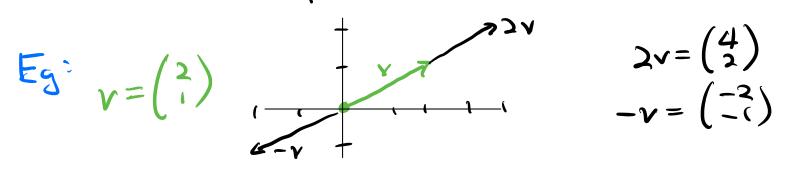
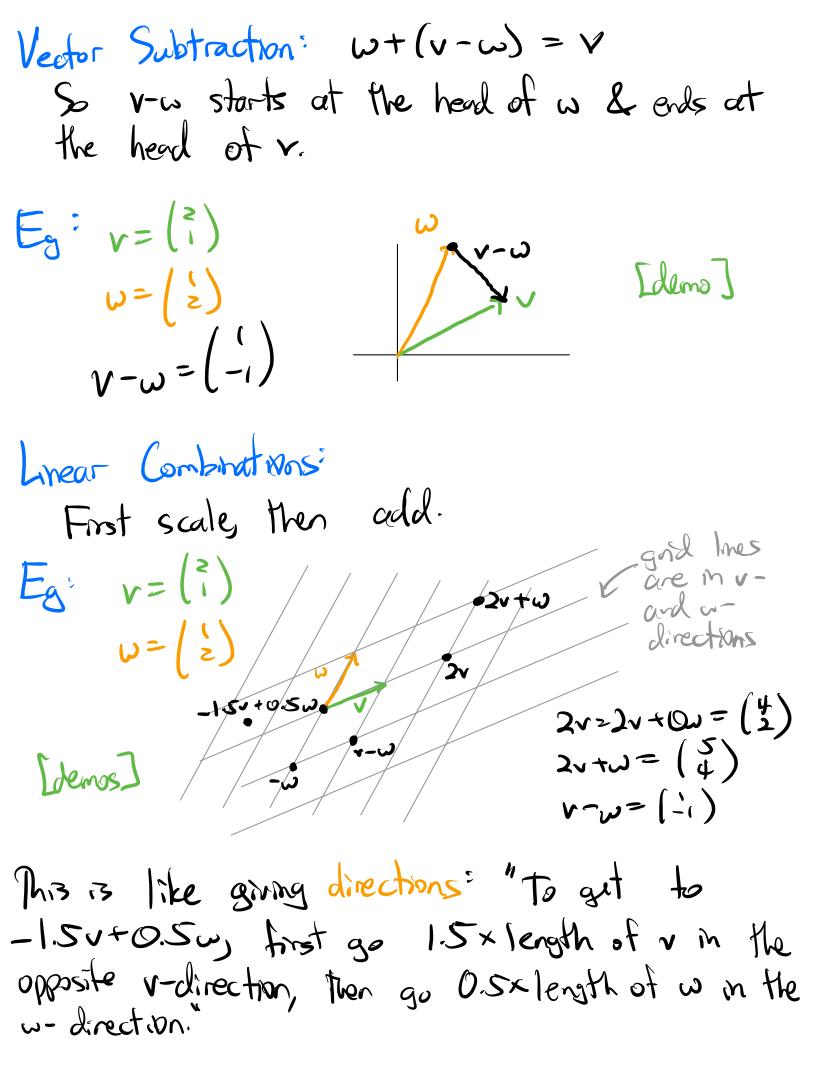


How de algebraic operations behave geometrizally? We'll describe in terms of arrows. Scalar Multiplication:

the length of cv is lcl× the length of v
the direction of cv is
→ the same as v if c>0
Leno]
→ the opposite from v if c<0



Vector Addition: This just adds the displacements. Paralellogram Law: to draw vtw, draw the tail of v at the head of w (or vice-versa); the head of v is at マナシ [demo] splacement $E_{q}: v = \binom{2}{1}$ $\omega = \begin{pmatrix} z \\ z \end{pmatrix}$ $VTW = \begin{pmatrix} 3 \\ 3 \end{pmatrix}$ add displacements



What do spans look like? It's the smallest "linear space" (line, plane, etc.) containing all your vectors & the origin. Eg: Span {v} = {cr: ce R} -> IF v=0 get the line thru 0 & v -> Span {0} = {c·0: c=RZ = }0} [demo] = the set containing only O Eg: Span Sv, w3 = Scv+dw: GdeR3 -> If v, w are not collinear, get the plane defined by 0, v, and w \rightarrow If v, v are collinear and nonzero, get the line three v, w, and O. [demo] -> IF v=u=0 get {0}

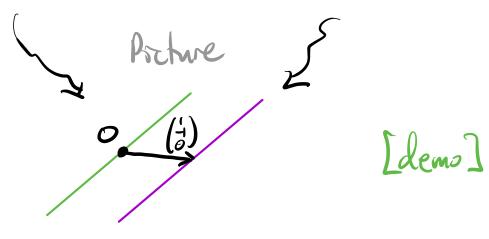
Let's solve this vector equation:

$$\begin{bmatrix} 1 & -2 & | & | & | \\ 6 & -1 & | & | & | \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 0 & | & -1 \\ 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{Y_{2}=-1} \xrightarrow{Y_{2}=-9}$$
Answer: yes
This example is just the "E" of the statement:
Ax=b is consistent is be Spen Scals of AB
Column Protone Criterian for Consistency: Compt
* $\begin{pmatrix} 1 & -1 \\ 6 & -1 \end{pmatrix} x = \begin{pmatrix} 8 \\ 16 \end{pmatrix}$ is consistent because
 $\begin{pmatrix} 16 \\ 6 & -1 \end{pmatrix} x = \begin{pmatrix} 8 \\ 16 \end{pmatrix}$ is consistent because
 $\begin{pmatrix} 16 \\ -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because
 $\begin{pmatrix} 1 & -2 \\ 6 & -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because
 $\begin{pmatrix} 1 & -2 \\ 6 & -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because
 $\begin{pmatrix} 1 & -2 \\ 6 & -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because
 $\begin{pmatrix} 1 & -2 \\ 6 & -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because
 $\begin{pmatrix} 1 & -2 \\ 7 \\ -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because
 $\begin{pmatrix} 1 & -2 \\ 7 \\ -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix} x = \begin{pmatrix} 7 \\ -1 \end{pmatrix}$ is inconsistent because

Homogeneous Equations If the solution set of Ax=b = a span => () is a solution levery span contains () $\Rightarrow AO=b \Rightarrow b=0$ Let's study this case. Def: Ax=b is called homogeneous if b=0. E_{3} $X_{1}+2X_{2}+2X_{3}+X_{4}=0$ $2x_1 + 4x_2 + x_3 - x_4 = 0$ NB: A homogeneous equation is always consistent since 0 is a solution: $A \cdot 0 = 0$ Def: The trivial solution of a homogeneous equation Ax=0 is the zero vector. Ey: Let's solve the homogeneous system $\begin{array}{c} \chi_{1}+2\chi_{2}+2\chi_{3}+\chi_{4}=0 \\ \chi_{1}+4\chi_{2}+\chi_{3}-\chi_{4}=0 \\ \chi_{4}+4\chi_{2}+\chi_{3}-\chi_{4}=0 \end{array} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 2 & 4 & 1 & -1 \\ 0 \end{bmatrix}$ $\begin{array}{c} R_{2} = 2R_{1} \\ R_{2} = -3R_{1} \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq = -3 \\ R_{2} \neq = -3 \\ R_{1} \neq = -3 \\ R_{2} \neq =$ $R = 2R_2 \begin{bmatrix} 1 & 2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix}$

Fact: The PVF of a homogeneous system always has particular solution=0. The solution set is the span of the other vectors you've produced.

Inhomogeneous Equations Def: Ax=b is called inhomogeneous if b=0. What's the difference from homogeneous equations? NB: It can be inconsistent! Let's solve the inhomogeneous & homogeneous versions." Eg: inhomogeneous homogeneous $\begin{bmatrix} 2 & 1 & 12 \\ 1 & 2 & q \end{bmatrix} X^{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 12 \\ 1 & 2 & q \end{bmatrix} X^{2} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ S (augmented) matrix S $\begin{bmatrix} 2 & 1 & 12 \\ 1 & 2 & 9 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 12 \\ 1 & 2 & 9 \\ -1 & -1 \end{bmatrix}$ RREF ţ $\begin{bmatrix} 1 & 0 & 5 \\ 0 & 1 & 2 \\ 1 & -1 \end{bmatrix} \xrightarrow{PVF} \begin{bmatrix} 1 & 0 & 5 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$ $X^{2} \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \neq Z \begin{pmatrix} -S \\ -2 \\ 1 \end{pmatrix} \qquad X^{2} Z \begin{pmatrix} -S \\ -2 \\ 1 \end{pmatrix}$ { Solution set {



The only difference is the particular solution! Otherwise they're parallel lines.

Facts: (1) The solution set of Ax= O is a span. (2) The solution set of Ax=bis not a year for b = 0: it is a translate of the solution set of Ax=0 by a particular solution. (Or it is empty.)

(solutions) = + Span { from PVF } (zero) Same vectors! 2 (solutions) = (porticular) + Span { from PVF}

In fact, to get the solutions of Ax=b you
can translate the colutions of Ax=0 by
any single solution of Ax=b.
Say p is some solution of Ax=b, so Ap=b.
Then Ax=0
$$\Longrightarrow$$
 Ap+Ax=b \Longrightarrow Alp+x=b
vectors of the form p+ (coln of Ax=0)
NB: Expressing a solution set as a (translate of a)
spen means writing it in paremetric form:
 $x \in {\binom{-1}{0}} + Span \{ {\binom{-2}{0}}, {\binom{-1}{0}} \}$
 $\Longrightarrow x = {\binom{-1}{0}} + c {\binom{-2}{0}} + d {\binom{0}{-1}}$
So think:
Spans \Longrightarrow Ap+Ax=b \Longrightarrow Alp+x=b
vectors of the form p+ (coln of Ax=0)
NB: Expressing a solution set as a (translate of a)
spen means writing it in paremetric form:
 $x \in {\binom{-1}{0}} + Span \{ {\binom{-2}{0}}, {\binom{-1}{0}} \}$
 $\Longrightarrow x = {\binom{-1}{0}} + c {\binom{-2}{0}} + d {\binom{0}{-1}}$
 $parameters$

Row & Column Picture We now know: (i) (All solutions) subtle concept span of Ax=b) #2 (All solutions) $= \left(\begin{array}{c} \text{Some solution} \\ \text{of } Ax=b \end{array} \right) + \left(\begin{array}{c} \text{All solutions} \\ \text{of } Ax=o \end{array} \right)$ Yos 30 or is empty. In particular, all nonempty solution sets are parallel and look the same f(z) A x = b is consistent f(z) b is in subtle the span of the columns of A. f(z) = f(z) + f(zJet L We can draw these both at the same time: Respirator (x) Multiply by A [deno] Mar R^m Subtle Su In this picture, we think of A as a function: xEIR" is the input low pictures Axe Rn is the output (colum picture) Solving Ax=b means fonding all inputs with output=b.

The solution set lives in the ... now picture! The b-vectors live in the ... column picture! The columns all live in the ... column picture! That's how you keep them straight.