

Subspaces

Orientation: We're developing machinery to "almost solve" $Ax=b$ (least squares)

Today: give new names to everything we've been doing

So far, to every matrix A we have associated two spans:

- (1) the span of the columns / all b such that $Ax=b$ is consistent
- (2) the solution set of $Ax=0$

The first arises naturally as a span / it is already in parametric form. The second required Work (elimination) to write as a span - it is a solution set, so it is in implicit form.

The notion of subspaces puts both on the same footing. This formalizes what we mean by "linear space containing 0".

Fast-forward:

↙ same picture

Subspaces
are spans

and

Spans are
subspaces.

Why the new vocabulary word?

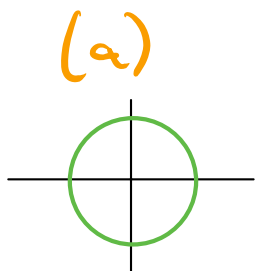
When you say "span" you have a spanning set of vectors in mind (parametric form). This is not the case for the solutions of $Ax=0$.

Subspaces allow us to discuss spans without computing a spanning set. Subspace = Span { ??? }

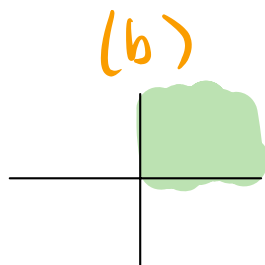
They also give a criterion for a subset to be a span.

Def: A subset of $\mathbb{R}^n$ is any collection of points.

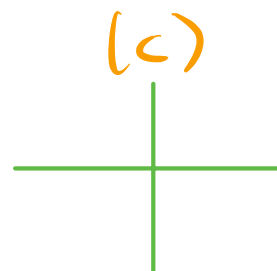
Eg:



$$\{(x, y) : x^2 + y^2 = 1\}$$



$$\{(x, y) : x, y \geq 0\}$$



$$\{(x, y) : xy = 0\}$$

Def: A subspace is a subset V of $\mathbb{R}^n$ satisfying:

(1) [closed under +] If $u, v \in V$ then $u+v \in V$

(2) [closed under scalar $\times$]

If $u \in V$ and $c \in \mathbb{R}$ then $cu \in V$

(3) [contains 0] $0 \in V$

These conditions characterize linear spaces containing 0 among all subsets.

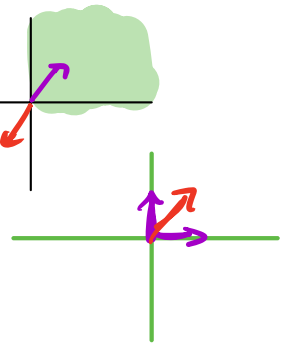
NB: If V is a subspace and $v \in V$ then $0 = 0v$ is in V by (2), so (3) just means V is nonempty

Eg: In the subsets above:

(a) fails (1), (2), (3)

(b) fails (2): $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \in V$ but $-1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin V$

(c) fails (1): $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \in V$ but $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin V$



Here are two "trivial" examples of subspaces:

Eg: $\{0\}$ is a subspace

(1) $0 + 0 = 0 \in \{0\}$ ✓

(2) $c \cdot 0 = 0 \in \{0\}$ ✓

(3) $0 \in \{0\}$ ✓

NB $\{0\} = \text{Span}\{\}$: it is a span

Eg: $\mathbb{R}^n = \{\text{all vectors of size } n\}$ is a subspace

(1) The sum of two vectors is a vector. ✓

(2) A scalar times a vector is a vector. ✓

(3) 0 is a vector. ✓

NB $\mathbb{R}^n = \text{Span}\{e_1, e_2, \dots, e_n\}$

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix} \quad \dots \quad e_n = \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}$$

Eg: $V = \{(x, y, z) : x + y = z\}$ ^{defining condition}

The ^{defining condition} tells you if (x, y, z) is in V or not.

(1) We have to show that if $u = (x_1, y_1, z_1) \in V$ and $v = (x_2, y_2, z_2) \in V$ then their sum is in V .

Know: $x_1 + y_1 = z_1$ $x_2 + y_2 = z_2$
^{defining conditions} for u & v

$$u + v = (x_1 + x_2, y_1 + y_2, z_1 + z_2)$$

Want: $(x_1 + x_2) + (y_1 + y_2) = (z_1 + z_2)$ ✓
^{defining condition} for $u + v$.

Since $u + v$ satisfies the defining condition, $u + v \in V$.

(2) We have to show that if $(x, y, z) \in V$ and $c \in \mathbb{R}$ then $c(x, y, z) = (cx, cy, cz) \in V$.

Know: $x + y = z$ Want: $cx + cy = cz$ ✓

Since cu satisfies the defining condition, $cu \in V$.

(3) Is $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in V$? Does it satisfy the defining condition?

$$0 + 0 = 0 \quad \checkmark$$

Since V satisfies the 3 criteria, it is a subspace. ✓

NB: This means V is a span!

How to find a spanning set?

More on this later.

In order to show that a subset is **not** a subspace, you just have to produce **one** counterexample to one of the axioms.

defining condition

Eg: $V = \{(x, y) : x \geq 0, y \geq 0\}$

(2) is false: $(1, 1) \in V$ ($1 \geq 0, 1 \geq 0$)

but $(-1)(1, 1) \notin V$ ($-1 < 0, -1 < 0$)

In practice you will rarely check that a subset is a subspace by verifying the axioms — but you'll show it's **not** a subspace by finding a counter-example.

Fact: A span is a subspace

Proof: Let $V = \text{Span}\{v_1, \dots, v_n\}$.

Here the **defining condition** for a vector to be in V is that it is a **linear combination** of $v_1, \dots, v_n$.

(1) We need to show that if $c_1v_1 + \dots + c_nv_n \in V$ & $d_1v_1 + \dots + d_nv_n \in V$ then their sum is in V : the sum of two linear combos of $v_1, \dots, v_n$ is a linear combo.

$$(c_1v_1 + \dots + c_nv_n) + (d_1v_1 + \dots + d_nv_n) \\ = (c_1 + d_1)v_1 + \dots + (c_n + d_n)v_n \in V \quad \checkmark$$

(2) We need to show that if $c_1v_1 + \dots + c_nv_n \in V$ and $d \in \mathbb{R}$ then the product is in V .

$$d(c_1v_1 + \dots + c_nv_n) = (dc_1)v_1 + \dots + (dc_n)v_n \in V \quad \checkmark$$

(3) Every span contains 0 :

$$0 = 0v_1 + \dots + 0v_n \quad \checkmark$$

Conversely, suppose V is a subspace.

If $v_1, \dots, v_n \in V$ and $c_1, \dots, c_n \in \mathbb{R}$ then:

$$c_1v_1, \dots, c_nv_n \in V \quad \text{by (2)}$$

$$c_1v_1 + c_2v_2 \in V \quad \text{by (1)}$$

$$(c_1v_1 + c_2v_2) + c_3v_3 \in V \quad \text{by (1)}$$

$$\vdots$$

$$c_1v_1 + \dots + c_nv_n \in V$$

So $\text{Span}\{v_1, \dots, v_n\}$ is contained in V .

Choose enough v_i 's to fill up V , and you get:

Subspaces
are spans

and

Spans are
subspaces.

Def: The **column space** of a matrix A is the span of its columns.

Notation: $\text{Col}(A) = \text{Span}\{\text{cols of } A\}$

This is a subspace of $\mathbb{R}^m$ $m = \# \text{rows}$
(each column has m entries)

↪ **column picture.**

Since a column space is a span & a span is a subspace, a **column space** is a **subspace**.

Eg: $\text{Col} \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \right\}$

Spans & Col spaces are **interchangeable**:

Eg: $\text{Span} \left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\} = \text{Col} \begin{bmatrix} 2 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$

NB: $\text{Col}(A) = \{Ax : x \in \mathbb{R}^n\}$

because " Ax " is just a LC of the cols of A .

Translation of the column picture criterion for consistency:

$$Ax=b \text{ is consistent} \iff b \in \text{Col}(A)$$

"b can be written as $Ax \iff b \in \text{Col}(A)$ "

Def: The null space of a matrix A is the solution set of $Ax=0$.

Notation: $\text{Nul}(A) = \{x \in \mathbb{R}^n : Ax=0\}$

This is a subspace of $\mathbb{R}^n$ $n = \# \text{columns}$
($n = \# \text{variables}$ and $\text{Nul}(A)$ is a solution set)
 $\rightsquigarrow$ row picture

Fact: $\text{Nul}(A)$ is a subspace

Of course we also know $\text{Nul}(A)$ is a span, but we can verify this directly.

Proof: The defining condition for $v \in \text{Nul}(A)$ is that $Av=0$.

(1) Say $u, v \in \text{Nul}(A)$. Is $u+v \in \text{Nul}(A)$?

$$A(u+v) = Au + Av = 0 + 0 = 0 \quad \checkmark$$

(2) Say $u \in \text{Nul}(A)$ and $c \in \mathbb{R}$.

Is $cu \in \text{Nul}(A)$?

$$A(cu) = c(Au) = c \cdot 0 = 0 \quad \checkmark$$

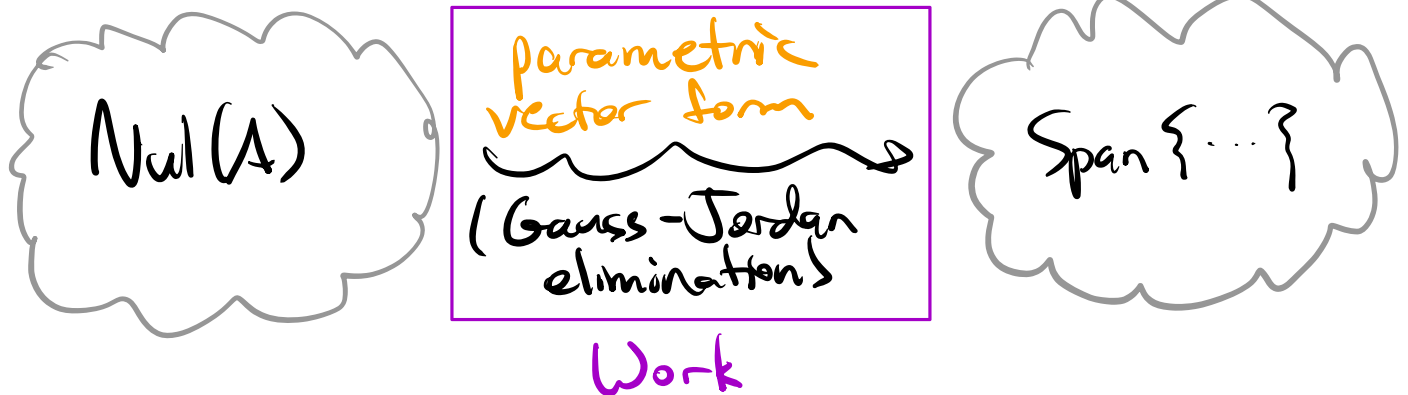
(3) Is $0 \in \text{Nul}(A)$?

$$A0 = 0 \quad \checkmark$$

This is an example of a **subspace** that does **not** come with a **spanning set**!

→ It's much more natural to consider it as a subspace when reasoning about it.

How to produce a spanning set for a null space?



Eg: Write $\text{Nul}(A)$ as a span for

$$A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \end{bmatrix}$$

This means solving $Ax = 0$ (homogeneous equation).

$$\left[\begin{array}{cccc|c} 1 & 2 & 2 & 1 & 0 \\ 2 & 4 & 1 & -1 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{cccc|c} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{array} \right]$$

parametric form $\rightarrow \begin{cases} x_1 = -2x_2 + x_4 \\ x_2 = x_2 \\ x_3 = -x_4 \\ x_4 = x_4 \end{cases}$

PVF $\rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 1 \\ 0 \\ -1 \\ 1 \end{pmatrix}$

$$\Rightarrow \text{Nul}(A) = \text{Span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -1 \\ 1 \end{pmatrix} \right\}$$

NB: Any two non-collinear vectors span a plane, so $\text{Nul}(A)$ will have many different spanning sets.

eg $\text{Nul}(A) = \text{Span} \left\{ \underset{\substack{\uparrow \\ \text{sum}}}{\begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix}}, \underset{\substack{\uparrow \\ \text{difference}}}{\begin{pmatrix} -3 \\ 1 \\ -1 \\ 1 \end{pmatrix}} \right\}$

More on this later.

NB: Likewise for the column space: eg.

$$\text{Col} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \text{Col} \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} = \text{Col} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \text{(xy-plane)}$$

Implicit vs Parametric form:

- $\text{Col}(A)$ is a **span**:

$$\text{Col} \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix} = \text{vectors of the form } x_1 \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + x_2 \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} + x_3 \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix}$$

parameters

↪ **parametric form**

- $\text{Nul}(A)$ is a **solution set**:

$$\text{Nul} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \end{bmatrix}$$

$$= \{ (x_1, x_2, x_3, x_4) : \begin{matrix} x_1 + 2x_2 + 2x_3 + x_4 = 0 \\ 2x_1 + 4x_2 + x_3 - x_4 = 0 \end{matrix} \}$$

equations

↪ **implicit form**

In practice you will (almost) always write a subspace as a column space/span or a null space. **Which one?**

- **parameters**? ↪ $\text{Col}(A)$ / Span
- **equations**? ↪ $\text{Nul}(A)$

Once you're done this, you can ask a **computer** to do computations on it!

Eg: $V = \{(x, y, z) : x + y = z\}$

This is defined by the equation $x + y = z$.

rewrite: $x + y - z = 0$

$$\leadsto V = \text{Nul} \begin{bmatrix} 1 & 1 & -1 \end{bmatrix}$$

Eg: $V = \left\{ \begin{pmatrix} 3a+b \\ a-b \\ b \end{pmatrix} : a, b \in \mathbb{R} \right\}$

This is described by parameters. Rewrite:

$$\begin{pmatrix} 3a+b \\ a-b \\ b \end{pmatrix} = a \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\leadsto V = \text{Span} \left\{ \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right\} = \text{Col} \begin{bmatrix} 3 & 1 \\ 1 & -1 \\ 0 & 1 \end{bmatrix}$$

This is also how you should verify that a subset is a subspace.

Of course, if V is not a subspace then you can't write it as $\text{Col}(A)$ or $\text{Nul}(A)$. In this case you should check that it fails one of the axioms.

Eg: Is $V = \{(x, y, z) : x + y = z + 1\}$ a subspace?

No, (P3) fails: $0 + 0 \neq 0 + 1$, so $0 \notin V$.