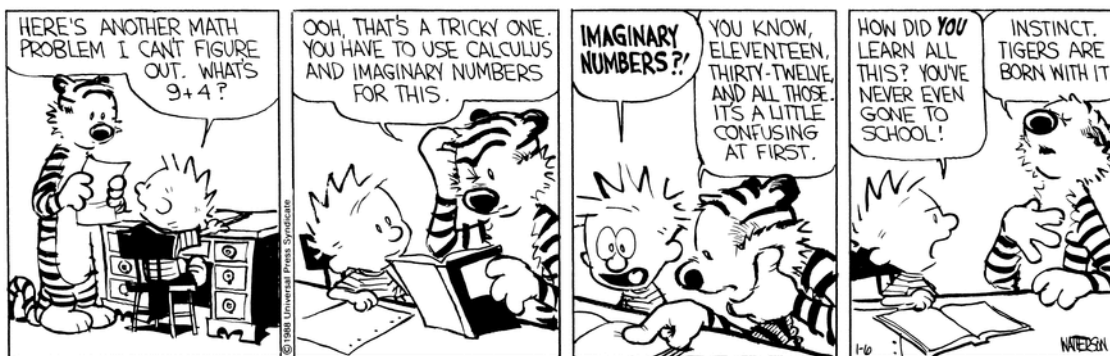


MATH 218D-1
MIDTERM EXAMINATION 2

Name		Duke Email	
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Please **read all instructions** carefully before beginning.

- Do not open this test booklet until you are directed to do so.
- You have 75 minutes to complete this exam.
- If you finish early, go back and check your work.
- The graders will only see the work on the **printed pages** (front and back). You may use other scratch paper, but the graders will not see anything written there.
- You may use a **simple calculator** for doing arithmetic, but you should not need one. You may bring a **3 × 5-inch note card** covered with anything you want. All other materials and aids are strictly prohibited.
- For full credit you must **show your work** so that your reasoning is clear, unless otherwise indicated.
- Do not spend too much time on any one problem. Read them all through first and attack them in an order that allows you to make the most progress.
- Good luck!



Problem 1.

[18 points]

Consider the matrix

$$A = \begin{pmatrix} 1 & -1 & 0 & 2 & 1 \\ -2 & 1 & 1 & 0 & 1 \end{pmatrix}.$$

- a) The row space of A is a (circle one) $\begin{pmatrix} \text{line} \\ \text{plane} \\ \text{space} \end{pmatrix}$ in (fill in the blank) $\mathbf{R}^{\boxed{5}}$.

The row space is spanned by the two rows of A . The rows are not collinear, so they span a plane, and each row has 5 entries, so they are vectors in \mathbf{R}^5 .

- b) Compute the orthogonal projection of $b = (3, 0, 0, 0, -1)$ onto $\text{Row}(A)$.

$$b_{\text{Row}(A)} = \begin{pmatrix} 2 \\ -1 \\ -1 \\ 0 \\ -1 \end{pmatrix}.$$

The easiest way to do this is by solving the normal equation $AA^T x = Ab$. (Note that $\text{Row}(A) = \text{Col}(A^T)$.)

- c) Compute the orthogonal projection of $b = (3, 0, 0, 0, -1)$ onto $\text{Nul}(A)$.

$$b_{\text{Nul}(A)} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}.$$

Since $\text{Nul}(A) = \text{Row}(A)^\perp$, if your answers to **b)** and **c)** sum to b , you'll get full credit.

Now consider the matrix

$$B = \begin{pmatrix} 1 & -1 & 0 & 2 & 1 \\ -2 & 2 & 0 & -4 & -2 \end{pmatrix}.$$

- d) The row space of B is a (circle one) $\begin{pmatrix} \text{line} \\ \text{plane} \\ \text{space} \end{pmatrix}$ in (fill in the blank) $\mathbf{R}^{\boxed{5}}$.

This is exactly the same as **a)**, except in this case, the rows *are* collinear, so they span a line.

- e) Compute the orthogonal projection of $b = (2, 0, 0, 3, -1)$ onto $\text{Row}(B)$.

$$b_{\text{Row}(B)} = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 2 \\ 1 \end{pmatrix}.$$

Use the formula for projection onto a line: $b_{\text{Row}(B)} = \frac{b \cdot v}{v \cdot v} v$. You can take v to be either row of B .

f) Compute the projection matrix P_V for $V = \text{Nul}(B)$.

$$P_V = \frac{1}{7} \begin{pmatrix} 6 & 1 & 0 & -2 & -1 \\ 1 & 6 & 0 & 2 & 1 \\ 0 & 0 & 7 & 0 & 0 \\ -2 & 2 & 0 & 3 & -2 \\ -1 & 1 & 0 & -2 & 6 \end{pmatrix}.$$

Since $V^\perp = \text{Row}(B)$ is a line, it's easy to compute $P_{V^\perp} = \frac{vv^T}{v \cdot v}$; then $P_V = I_5 - P_{V^\perp}$.

g) Find a basis for $\text{Nul}(P_V)$.

$$\left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \\ 2 \\ 1 \end{pmatrix} \right\}.$$

We have $\text{Nul}(P_V) = V^\perp = \text{Nul}(B)^\perp = \text{Row}(B)$, so you just have to write a multiple of either row of B .

Problem 2.

[17 points]

Consider the matrix

$$A = \begin{pmatrix} 1 & 4 & 1 \\ 1 & 4 & -1 \\ 1 & 2 & 5 \\ 1 & 2 & 3 \end{pmatrix}.$$

Applying the Gram-Schmidt procedure to its columns gives:

$$\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 2 \\ 2 \end{pmatrix} - 3 \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 5 \\ 3 \end{pmatrix} - 2 \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} + 2 \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix}.$$

a) Compute the QR decomposition of A .

$$Q = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & -1 & -1 \end{pmatrix} \quad R = \begin{pmatrix} 2 & 6 & 4 \\ 0 & 2 & -4 \\ 0 & 0 & 2 \end{pmatrix}$$

(Check your work! Does $A = QR$? Does Q have orthonormal columns? The rest of the problem will be much easier if so.)

b) Find the least-squares solution of $Ax = (2, 0, -4, 2)$.

$$\hat{x} = \begin{pmatrix} 5 \\ -1 \\ -1 \end{pmatrix}$$

It's easiest to solve $R\hat{x} = Q^T b$ by back-substitution.

c) Compute the orthogonal projection of $b = (2, 0, -4, 2)$ onto $V = \text{Col}(A)$.

$$b_V = \begin{pmatrix} 0 \\ 2 \\ -2 \\ 0 \end{pmatrix}.$$

If you multiply A by your answer to **b)** you get full credit.

d) Find a nonzero vector v in $\text{Nul}(A^T)$.

$$v = \begin{pmatrix} 1 \\ -1 \\ -1 \\ 1 \end{pmatrix}.$$

We have $\text{Nul}(A^T) = \text{Col}(A)^\perp$, so you just have to subtract your answer to **c)** from b .

e) Compute the projection matrix P_V onto $V = \text{Col}(A)$. $P_V = \frac{1}{4} \begin{pmatrix} 3 & 1 & 1 & -1 \\ 1 & 3 & -1 & 1 \\ 1 & -1 & 3 & 1 \\ -1 & 1 & 1 & 3 \end{pmatrix}$

It's probably easiest to compute $P_V = QQ^T$ since you already know Q .

f) Find an eigenbasis for P_V . $\left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 5 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ -1 \\ 1 \end{pmatrix} \right\}$

The 1-eigenspace of P_V is $V = \text{Col}(A)$, and the columns of A (or of Q) form a basis for $\text{Col}(A)$. This gives you 3 basis vectors, so you need one more. The 0-eigenspace is $V^\perp = \text{Nul}(A^T)$, and you found a basis for that in **d**). Combining these gives an eigenbasis.

Problem 3.

[15 points]

The matrix

$$A = \begin{pmatrix} 61/2 & 12 & -7/2 \\ -51 & -20 & 6 \\ 75 & 30 & -8 \end{pmatrix}$$

has eigenvectors

$$w_1 = \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix} \quad w_2 = \begin{pmatrix} 1 \\ -1 \\ 5 \end{pmatrix} \quad w_3 = \begin{pmatrix} -2 \\ 3 \\ -6 \end{pmatrix}.$$

a) Find the eigenvalue associated to each of these eigenvectors.

$$\lambda_1 = \boxed{-\frac{1}{2}} \quad \lambda_2 = \boxed{1} \quad \lambda_3 = \boxed{2}$$

Just compute Aw_i and see what scalar you have to multiply w_i by to get Aw_i . In fact, since you're told that w_1, w_2, w_3 are eigenvectors, you really just need to compute the first coordinate of Aw_i . For instance,

$$Aw_1 = \begin{pmatrix} -1/2 \\ ? \\ ? \end{pmatrix} = \lambda_1 \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix},$$

so $\lambda_1 = -1/2$.

b) Compute the characteristic polynomial of A . (You need not expand a product of polynomials.)

$$p(\lambda) = -(\lambda + \frac{1}{2})(\lambda - 1)(\lambda - 2)$$

Its linear factors are $\lambda - \lambda_1, \lambda - \lambda_2, \lambda - \lambda_3$, but its λ^3 -coefficient is $(-1)^3 = -1$.

c) Find an invertible matrix C and a diagonal matrix D such that $A = CDC^{-1}$.

$$C = \begin{pmatrix} 1 & 1 & -2 \\ -2 & -1 & 3 \\ 2 & 5 & -6 \end{pmatrix} \quad D = \begin{pmatrix} 1/2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

The columns of C are w_1, w_2, w_3 and the diagonal entries of D are your answers to a).

d) If $v = (-1, 3, 2)$, compute $A^{100}v$. (You can write your answer in terms of w_1, w_2, w_3 .)

$$A^{100}v = -(-\frac{1}{2})^{100}w_1 + 2w_2 + 2^{100}w_3$$

First you have to expand in the eigenbasis: you solve $v = x_1w_1 + x_2w_2 + x_3w_3$ to get $x_1 = -1, x_2 = 2, x_3 = 1$ so that $v = -w_1 + 2w_2 + w_3$. Then multiply by A^{100} .

e) For which vectors u does $\|A^k u\|$ not approach ∞ as $k \rightarrow \infty$?

When you expand $u = x_1w_1 + x_2w_2 + x_3w_3$ in the eigenbasis, you get

$$A^n u = \left(-\frac{1}{2}\right)^n x_1 w_1 + x_2 w_2 + 2^{100} x_3 w_3.$$

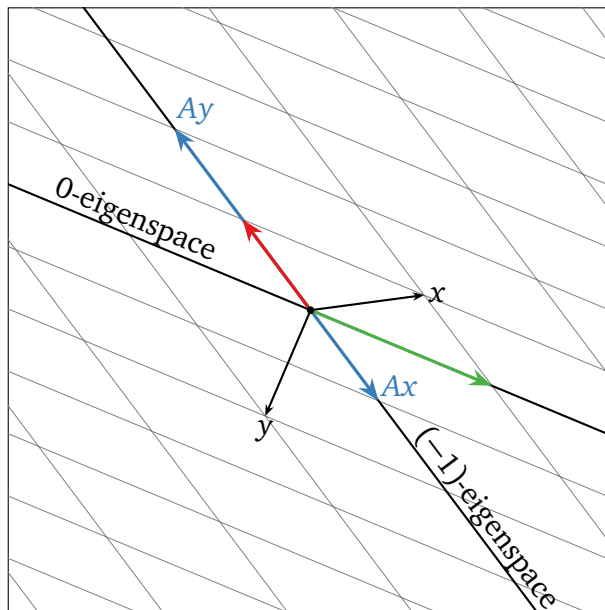
If $x_3 = 0$ then this approaches $x_2 w_2$; otherwise it becomes arbitrarily long. So the answer is "all $u \in \text{Span}\{w_1, w_2\}$ ".

Problem 4.

[10 points]

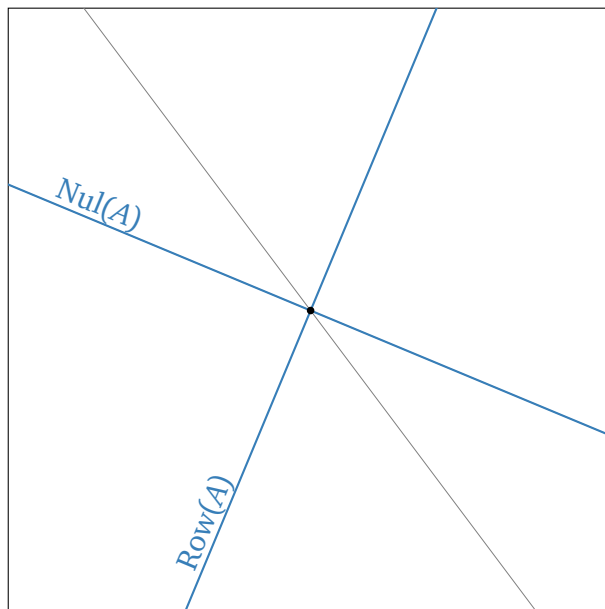
A certain 2×2 matrix A has eigenvalues 0 and -1 , with corresponding eigenspaces drawn below.

- a) Draw and label Ax and Ay .



Write x as the sum of the red vector and the green vector. When you multiply by A , the green vector goes to 0 (it's in the null space), and the red vector gets negated. Likewise for y .

- b) Draw and label $\text{Nul}(A)$ and $\text{Row}(A)$. (The eigenspaces are reproduced in gray.)



The null space is the 0 -eigenspace. The row space is its orthogonal complement.

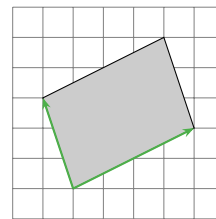
Problem 5.

[20 points]

Short-answer questions: no explanation is needed unless indicated otherwise.

a) Compute the area of the parallelogram. (Grid marks are one unit apart.)

This is the parallelogram determined by the vectors $\begin{pmatrix} -1 \\ 3 \end{pmatrix}$ and $\begin{pmatrix} 4 \\ 2 \end{pmatrix}$ (in green), so the area is $|\det\begin{pmatrix} -1 & 3 \\ 4 & 2 \end{pmatrix}|$.



area =

b) For which value(s) of k , if any, is the following matrix not invertible?

Compute $\det(A)$ by expanding cofactors. It helps to do the row operation $R_3 \leftarrow 2R_1$ first.

$$A = \begin{pmatrix} 1 & 0 & 3 & 2 \\ 0 & 1 & k & 4 \\ 2 & 1 & -1 & 2 \\ 0 & 3 & 2 & 0 \end{pmatrix}$$

$k =$

c) Suppose that A is an $n \times n$ matrix with characteristic polynomial

$$p(\lambda) = \lambda(\lambda - 1)(\lambda - 2)^2.$$

Which of the following can you determine from this information?

- The number n .
- The trace of A .
- The determinant of A .
- The eigenvalues of A .
- Whether A is invertible.
- Whether A is diagonalizable.

The number n is the degree of $p(\lambda)$; $\text{Tr}(A)$ is the λ^2 -coefficient; $\det(A)$ is the constant coefficient; the eigenvalues are the roots; A is invertible if $\det(A) \neq 0$. You don't know if A is diagonalizable because $\text{GM}(2)$ could be 1 or 2.

d) Suppose that v is a 3-eigenvector of A . Briefly explain why $v \in \text{Col}(A)$.

If $Av = 3v$ then $v = A\left(\frac{1}{3}v\right)$.

Problem 6.

[20 points]

In each part, either provide an example, or explain why no example exists. (No explanation is required if an example does exist.)

- a) A 2×2 *non-diagonalizable* matrix with eigenvalues 1 and -1 .

Impossible: a 2×2 matrix with two eigenvalues is diagonalizable.

- b) A 2×2 matrix whose 1-eigenspace is the line $x + 2y = 0$ and whose 2-eigenspace is the line $x + 3y = 0$.

$$CDC^{-1} \quad \text{for} \quad C = \begin{pmatrix} -2 & -3 \\ 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$$

- c) A 3×2 matrix A and a vector b such that $Ax = b$ does not have a least-squares solution.

Impossible: $Ax = b$ always has a least-squares solution.

- d) A 2×2 matrix that is *orthogonal* but has no zero entries.

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

for most values of θ .