Properties of Orthogonal Projections

\nRecall: if V is a subspace of IR' and b=R'',  
\nb = Ly + byL  
\nis its orthogonal decomposition with respect to V.

\nby = orthogonal projection of b onto V'

\n= closest vector in V to b

\nby = orthogonal projection of b onto V'

\n= closest vector in V' to b

\nThe distance from b to V' is

\n
$$
||b-bv|| = ||b v u||
$$

\nIdemos]

Properties of Projectons:

\n(1) 
$$
b_v = b \Leftrightarrow bv = 0 \Leftrightarrow bcV
$$

\n(2)  $b_v = 0 \Leftrightarrow b = b_{v+} \Leftrightarrow b \in V^{\perp}$ 

\n(3)  $(b_v)_v = b_v$ 

(1) 
$$
5a_{35}
$$

\n(2)  $5a_{35}$ 

\n(3)  $5a_{35}$ 

\n5.  $15a_{35}$  and  $15a_{35}$ 

\n6.  $15a_{35}$  and  $15a_{35}$ 

\n7.  $15a_{35}$  and  $15a_{35}$ 

\n8.  $11b_{35}$  and  $15b_{35}$ 

\n9.  $11b_{35}$  and  $15b_{35}$ 

\n10.  $5ac_{35}$  and  $15b_{35}$ 

\n11.  $13b_{35}$ 

\n12.  $5a_{35}$ 

\n13.  $5a_{35}$ 

\n14.  $11b_{35}$  and  $15b_{35}$ 

\n15.  $5a_{35}$ 

\n16.  $11b = (2)$  by  $15b_{35}$ 

\n17.  $11b_{35}$  and  $15b_{35}$ 

\n18.  $5a_{35}$ 

\n19.  $11b_{35}$ 

\n110.  $11b_{35}$ 

\n12.  $5a_{35}$ 

\n13.  $5a_{35}$ 

\n14.  $11b_{35}$ 

\n15.  $5a_{35}$ 

\n16.  $11b_{35}$ 

\n17.  $11b_{35}$ 

\n18.  $5a_{35}$ 

\n19.  $11b_{35}$ 

\n110.  $11b_{35}$ 

\n12.  $11b_{35}$ 

\n13.  $5a_{35}$ 

\n14.  $11b_{35}$ 

\n15.  $5a_{35}$ 

\n16.  $11b_{35}$ 

\n17.  $$ 

Eg: last time if 
$$
b = \begin{pmatrix} 1 \\ 1 \end{pmatrix}
$$
  $V = C_{0} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$   
\nthen we computed  $b_{V} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ , so we should  
\nhau  $b \in V$ . Let's check:  
\n $\begin{pmatrix} 1 & -1 & -1 \\ 2 & -1 & -1 \\ 1 & -1 & 1 \end{pmatrix} = \begin{pmatrix} xy \\ y \end{pmatrix} = \begin{pmatrix} xy \\ x \end{pmatrix} = \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \end{pmatrix} + xy = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}$   
\nTaking  $x_{3} = 0$  gives a solution of the vector eq<sup>n</sup>:  
\n $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \frac{2}{5} \begin{pmatrix} 1 \\ 5 \\ 1 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix}$   
\nSo  $b = 3$  undefined in  $V = C_{0} \begin{pmatrix} 1 & -1 & -1 \\ 2 & -1 & -1 \\ 1 & -1 & 1 \end{pmatrix}$ .

Projection Matrices

Recall: IF V=GI(A) then you compute by  
\nus follows:  
\n(1) Solve the normal equation 
$$
AX=ATb
$$
  
\n(2) by=  $A\hat{x}$  for any solution  $\hat{x}$ .  
\nLemma: A has full column rank if  $\hat{a}$  only if  
\n $ATA \equiv invertide$ .  
\n*Proof:* Note  $ATA \equiv square$ .  
\n $A has FCR$   
\n $\Leftrightarrow Null(A) = \{0\}$  (FQR criteria)  
\n $\Leftrightarrow Null(A) = \{0\}$  (IQR criteria)  
\n $\Leftrightarrow ATA \Rightarrow FGR$  (FGR criteria)  
\n $\Leftrightarrow ATA \Rightarrow FGR$  (FGR criteria)  
\n $\Leftrightarrow ATA \Rightarrow True+ible$  (meribility often)  
\n $\hat{x} = (ATA)^TATb$  s, by=  $A\hat{x} = A(ATA)A^Tb$ .

If A has FCR and V=6(M) then  

$$
b_v = A(A^T A)^T A^T b
$$
.

Eg: V = 
$$
Col(A) A = \begin{pmatrix} 1 & 1 \ 1 & 0 \end{pmatrix}
$$
  
\n $A^TA = \begin{pmatrix} 1 & 1 & 0 \ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \ 1 & 0 \end{pmatrix} = \begin{pmatrix} 3 & 2 \ 2 & 2 \end{pmatrix}$   
\n $(A^TA)^{-1} = \frac{1}{6-4} \begin{pmatrix} 2 & -2 \ -2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & -1 \ -1 & 3/2 \end{pmatrix}$   
\n $A(A^TA)^{-1}A^T = \begin{pmatrix} 1 & 1 \ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \ -1 & 3/2 \end{pmatrix} \begin{pmatrix} 1 & 1 \ 1 & 0 \end{pmatrix}$   
\n $= \begin{pmatrix} 0 & 1/2 \ 0 & 1/2 \end{pmatrix} \begin{pmatrix} 1 & 1 \ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1/2 & 1/2 & 0 \ 1/2 & 1/2 & 0 \ 0 & 0 & 1 \end{pmatrix}$   
\nSo  $A^T$  b =  $\begin{pmatrix} 1 \ 0 \ 0 \end{pmatrix}$  then  
\n $b_T = \begin{pmatrix} 1/2 & 1/2 & 0 \ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \ 0 \ 0 \end{pmatrix} = \begin{pmatrix} 1/2 \ 0 \ 0 \end{pmatrix}$   
\n $= \begin{pmatrix} 0 & 1/2 \ 0 & 1/2 \ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1/2 & 0 \ 0 \ 0 \end{pmatrix} = \begin{pmatrix} 1/2 \ 0/2 \ 0 \end{pmatrix}$   
\n $= \begin{pmatrix} 0 & 1/2 \ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1/2 & 0 \ 0 \ 0 \end{pmatrix} = \begin{pmatrix} 1/2 \ 0/2 \ 0 \end{pmatrix}$   
\n $= \begin{pmatrix} 0/2 & 1/2 \ 1/2 & 1/2 \ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1/2 & 0 \ 0 \ 0 \$ 

Def: Let V be a subspace of 
$$
\mathbb{R}^n
$$
. The projection matrix onto V is the maximum matrix.  $P_V$  such that  $P_V b = b_V$  for all  $b \in \mathbb{R}^m$ .

\nNB: The matrix  $P_V$  is defined by the equality for all vectors b. This uniquely characterizes  $P_V$  by the Euler algebra. Use the above equation to answer questions about  $P_V$ ! (This is the first time we're defined a matrix by its action on  $\mathbb{R}^m$ .)

Fact: If  $A$  &  $B$  are men matries and  $Ax = Bx$  for all  $x$ , then  $A = B$ .

Indeed,  $Ae = i\frac{\pi}{4}$  col of  $A_2$  so actually a matrix is determined by its action on the unit coordinate vectors

What if  $V = Col(A)$  but  $A$  does not have full column rank? How to compute Pv?

Eg: V=6/(A) 
$$
A = \begin{pmatrix} 1 & -1 & -1 \\ 2 & -1 & \frac{1}{2} \end{pmatrix}
$$
  
\nThis A does not have full column rank:  
\n $A = \begin{pmatrix} 0 & -1 & -1 \\ 0 & 0 & 0 \end{pmatrix}$  plus  
\nThis says that  $\begin{pmatrix} 1 & -1 & -1 \\ 0 & 0 & 0 \end{pmatrix}$  is a basis  
\nfor V. This means:  
\n(1) V=Span  $\begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix}$   $\begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix}$   $\begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix}$   
\n(2)  $\begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix}$  has full column rank.  
\nSo replace A by B= $\begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix}$ :  
\n $B^T B = \begin{pmatrix} 1 & 2 & 1 \\ -1 & 2 & -1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 6 & 0 \\ 0 & 3 \end{pmatrix}$   
\n(B^T B)<sup>-1</sup>= $\begin{pmatrix} 1/6 & 0 \\ 0 & 1/3 \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ 

$$
P_{v} = B(B^{T}B)^{-1}B^{T} = \frac{1}{6} \begin{pmatrix} 1 & -1 \\ 2 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ -1 & 1 & -1 \end{pmatrix}
$$
  
\n
$$
= \frac{1}{6} \begin{pmatrix} 1 & -2 \\ 2 & 2 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ -1 & 1 & -1 \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 3 & 0 & 3 \\ 0 & 6 & 0 \\ 3 & 0 & 3 \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} V_{2} & -1/2 \\ 0 & 1 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} V_{2} & -1/2 \\ 0 & 1 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix} \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix} \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0/2 & 0 & 1/2 \\ V_{2} & 0 & V_{2} \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1/2 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} 1/2 & 0 & 0 \\ 0 & 1/2 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1/2 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1/2 & 0 \\ V_{2} & 0 & V_{2} \end{pmatrix}
$$
  
\n
$$
= \begin{pmatrix} 1/2 & 0 & 1/2 \\ 0 & 1/2 &
$$

E  
\nE  
\nE  
\n
$$
V = Span\{(1)\}
$$
  
\n $P_v = \frac{1}{(1)(1)} (1)(11) = \frac{1}{2} (\begin{matrix} 1 & 1 \\ 1 & 1 \end{matrix}) = (\begin{matrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{matrix})$   
\n $S_o$  if  $b = (\begin{matrix} 1 \\ 0 \end{matrix})$  then  $bx = Rb = (\begin{matrix} 1/2 \\ 1/2 \end{matrix})$  (c) L11)

(1) Find a basis 
$$
\{v_1, ..., v_n\}
$$
 of V  
\n(2)  $B = (v_1 \cdots v_n)$  For example, if  
\n(3)  $P_v = B(B^TB)^{-1}B^T$  use the product columns  
\n $E_g$ : Suppose  $V = S_{par} \{v\}$  is a line.  
\n $B=v$  (matrix with one column)  
\n $B(B^TB) = v \cdot v$  (a scalar)  
\n $B(B^TB)^{-1}B^T = v(v \cdot v)^{-1}v^T = \frac{vv^T}{v \cdot v}$ 

Procedure for Computing R.:

Properties of Projecton Matrices:	
Let V be a subspace of RN and let R	
be its projection matrix.	
(1) $G_1(P_v) = V$	(3) $P_v^2 = R_v$
(2) $N_u I(P_v) = V^{\perp}$	(4) $P_v + P_{v^{\perp}} = \mathbb{I}_m$
(5) $P_v = P_v^{\top}$	
(6) $P_{IR} = \mathbb{I}_m$	(7) $P_{is} = O$
Recall: A (square) matrix S is symmetric of S=S	
Proofs of the Properties:	
This is a translation of properties of projects:	
(1) $G_1(P_v) = fR_v : b \in R^m$ ?	= {b_v : b \in R^m}
(1) $G_2(P_v) = fR_v : b \in R^m$ ?	= {b_v : b \in R^m}
Exercise 4) $F_v$ any $b_v$	
and $b_v = b$ for any $b \in V$ .	
(2) $N_u I(P_v) = \{bc \in R^m : p_v b = O\}$	= {bcR^m : b_v = O}?
But we know $b_v > O$ (the V <sup>2</sup> ).	

(3) For any vector b,  
\n
$$
P_v^2 = P_v(P_v b) = P_v(b_v) = (b_v)_v
$$
\n
$$
T_{hs}
$$
\nequals by because  $b_v \in V$  already

\n
$$
= b_v = Rv b
$$
\nSince  $P_v^2 b = Rv b$  for all vectors b,  $P_v^2 = P_v$ .

\n(4) For any vector b,  
\n
$$
(P_v \in R_v b) = Rv b + R_v b = b_v + b_v b
$$
\n
$$
= b - \sum_{v} b
$$
\nSince  $(R_v + P_v b) = T_{\text{in}} b$ 

\n
$$
= b - \sum_{v} b
$$
\nSince  $(R_v + P_v b) = T_{\text{in}} b$  for all vectors b,  
\n
$$
P_v + P_v b = T_{\text{in}}
$$
\n(5) Choose a basis for  $V \rightarrow P_v = B(Pv b^c)B^T$ 

\n
$$
= B(v^2 - v^2)B^T
$$
\n
$$
= B((Bv^2 - v^2)^T)B^T = B(v^2 - v^2)B^T = P_v
$$

6 For any invertible matrix A,  
\n
$$
(A^{-1})T = (A^{T})^{-1}
$$
 because  
\n $(A^{-1})T + A^{T} = (AA^{-1})T = LT = T$ ,  
\n $(6) \text{IF } V=IR^{n}$  then beV for all b, so  
\n $R_{V} b = b_{V} = b$  for all b.  
\nAlso  $T_{r}b = b_{r}b_{r}$  and b, so  $R_{r} = T_{r}$ .  
\n $(7) \text{IF } V=583$  then  $R_{V}b$  must be O for every  
\nb, because O is the only vector in V:  
\n $R_{V}b = b_{V} = 0$  for all b.  
\n $A_{S0} 0b = 0$  for all b, so  $R_{V} = 0$ .

Let the number if 
$$
V = N_u(A)
$$
, we computed by by  
\nfirst computing the projection onto  $V^{\perp} = G/(At)$ ,  
\nthen using  $b_v = b - b_v$ .

We can do the same for projection matrices,  $us_{wd}$   $\sim$ 

Product: To compute 
$$
P_v
$$
 for  $V = N_v(A)$ :

\n(1) Compute  $P_vL$  for  $V^2 = C_v(A^T)$ 

\n(2)  $P_v = Im - P_vL$ 

\n
$$
E_v
$$
 Compute  $P_v$  for  $V = N_u(A \mid 2 + 1)$ .

\nThus  $cos \theta$ ,  $V^{\perp} = C_v(A^T)$ 

\n
$$
P_{vL} = \frac{1}{(\frac{1}{2})(\frac{1}{2})(\frac{1}{2})(\frac{1}{2} + 1)} = \frac{1}{6} \left(\frac{1}{2} + \frac{2}{2} + \frac{1}{2}\right)
$$
\n
$$
P_{vL} = \frac{1}{(\frac{1}{2})(\frac{1}{2})(\frac{1}{2})(\frac{1}{2} + 1)} = \frac{1}{6} \left(\frac{2}{2} + \frac{1}{2}\right)
$$
\n
$$
P_{vL} = \frac{1}{(\frac{1}{2})(\frac{1}{2})(\frac{1}{2})(\frac{1}{2} + 1)} = \frac{1}{6} \left(\frac{5}{2} - \frac{2}{2} - \frac{1}{2}\right)
$$
\nThus  $cos \theta$  much easier than finding  $\alpha$  beak for  $V$  using  $Pr$ , then  $cos \theta$   $Pr$  =  $\beta$  ( $8^TB)^{-1}B^T$ .

\n
$$
X_1 = -2X_2 - X_3 \implies Y_2 = X_3 \implies Y_3 = X_2 \implies Y_4 = X_3 \implies Y_5 = X_4 \implies Y_6 = \frac{1}{6} \left(\frac{1}{2} - \frac{1}{2}\right)
$$
\nThus  $|8^TB|^{-1} = \frac{1}{(2 - \frac{1}{2})}$ 

\n
$$
E = \begin{pmatrix} -2 & -1 \\ 3 & 0 \end{pmatrix} \implies E^TB = \begin{pmatrix} 5 & 2 \\ 2 & 2 \end{pmatrix}
$$
\nThus  $|8^TB|^{-1} = \frac{1}{(2 - \frac{1}{2})} = \frac{1}{6} \left(\frac{2}{2} - \frac{2}{5}\right)$ 

\n
$$
E = \begin{
$$

$$
= \frac{1}{6} \begin{pmatrix} -2 & -1 \\ 2 & -2 \\ -2 & 5 \end{pmatrix} \begin{pmatrix} -2 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix}
$$

$$
= \frac{1}{6} \begin{pmatrix} 5 & -2 & -1 \\ -2 & 2 & -2 \\ -1 & -2 & 5 \end{pmatrix}
$$

Be intelligent about what you actually have to compute! Ask yourself: "is it easier to compute Vu or Pus