The Four Subspaces Recall: To any matrix A, we can associate: \circ Col(A); basis = pivot columns of A; dim = rank . Nut (A) basis vectors in the PVF of $Ax=Q$ $dm = #frac{area - #cos - rank}{}$ There are two more subspaces: just replace A b_3 A_1^T then take Col a' Nul. Why? Orthogonality us least \Box s (bear with me...) Det: The row space of A is $\text{Row}(A)$ = Col(AT). This is the subspace spanned by the rows of A_j regarded as $(n\omega)$ vectors in $\mathbb R$ This is a subspace of \mathbb{K} n = # columns Ln = #entries in each row us row picture E_g $R_{0\omega} \left(\frac{1}{4} \sum_{7}^{3} \frac{3}{9}\right) = 5$ pan $\left(\frac{1}{3}\right) \left(\frac{4}{9}\right) \left(\frac{7}{9}\right)$ $\mathcal{E} = \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$ Fact: Row operations do not change the row space.

Why If the rows are ^u vav then Row A Span ri ra ^V Row ops Ri Ra SpanTungus Span us ^u Rex 3 Span Uk Us Span ^v 3mV Rat ZR SpanTrina ^V Spanky Ustr us because Ktv ^c SpanTyrus and ^v rata ²⁴ Spanky is 24ns This is ^a cool space of At so you know how to compute ^a basis pivot columns of At But you can also find ^a basis by doing elimination on A

Thm[:] The nonzero rows of any REF of A form ^a basis for Row A $EG - 1221$ $\frac{1}{\sqrt{2}}$ 0 0 - 3 -
0 0 0 0
1 β asis: $\left\{\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 0 \\ -3 \\ -3 \end{pmatrix} \right\}$

$$
or: \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 1 & 2 & -1 & -2 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}
$$
\n
$$
\begin{bmatrix} \text{and then } \text{Basis:} \left\{ \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right\}
$$
\n
$$
\begin{bmatrix} \text{Proof:} \\ \text{and you can always delete the zero vector} \\ \text{with hand changing the span} \end{bmatrix}
$$
\n
$$
\begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ -3 \\ 3 \end{bmatrix} = \begin{bmatrix} x_1 \\ 2x_1 \\ x_1 \end{bmatrix}
$$
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$$
\begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = 0 = x \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ -3 \\ -3 \end{bmatrix} = \begin{bmatrix} x_1 \\ 2x_1 \\ x_1 \end{bmatrix}
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\begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = x \begin{bmatrix} x_1 \\ 2x_1 \\ x_1 \end{bmatrix}
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\begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = x \begin{bmatrix} x_1 \\ 2x_1 \\ x_1 \end{bmatrix}
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\begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = x \begin{bmatrix} x_1 \\ 2x_1 \\ x_1 \end{bmatrix}
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\begin{bmatrix} 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = x \begin{bmatrix} x_1 \\ 2x_1 \\ x_1 \end
$$

Def: The left null speece of A is $\mathcal{N}(\mathcal{A}^T)$. This is the solution set of $A^T x = 0$. Notation: just Nul(AT) (no new notation) This is a subspace of \mathbb{R}^m $m = \#\text{rows}$ $(mz$ # columns of $AT)$ \sim column picture $MS: A^T x = O \iff O = (A^T x)^T = x^T A$ so $Nd(A^T) = \{row\}$ vectors $x^T \in \mathbb{R}^n$: $x^T A = 0$ Nut At is ^a null space so you know how to compute a basis (PVF of Ax=0). You can also find ^a basis by doing elimination on A Thin/Procedure: To compute a basis of Nul (AT): (i) Form the augmented matrix $[A|I_m\rangle$ ² Eliminate to REF (3) The rows on the right side of the line next to zero rows on the left f_{com} a basis of Nal (A^{\dagger}) .

$$
f(x) = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 1 & 2 & -1 & -2 \end{bmatrix}
$$

\n
$$
\begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 1 & 2 & -1 & -2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2x-2R & 1 & 2 & 1 \\ 0 & -8 & -3 & -3 \\ 0 & 0 & -3 & -3 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ -1 & 0 \\ 0 & 1 & 0 \end{bmatrix}
$$

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$$
\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}
$$

\n
$$
\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}
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\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}
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\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}
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$$
\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & -1 \\ 0 & 1 & 2 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}
$$

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\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}
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\n
$$
\begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 & 1 \\
$$

S the result of performing elimination on
\n(A) I in
$$
U
$$
 is in REF and the last
\n $m-r$ rows are zero then we claim:
\n $Nu(Ut) = Span\{e_{m1}, e_{m2}, \dots, e_{m}\}$
\n Ne knows $U^T e_i = \text{the } i^{tr} \text{ row of } U$.
\n De knows from before that the nonzero rows
\nof U are LL. So if $(x_0...,x_m) \in Nu(U^T)$ then
\n $O=U^T\begin{pmatrix} x_1 \\ x_m \end{pmatrix} = x_1U^T e_1 + \dots + x_rU^T e_r$
\n $+ x_{rn}U^T e_{rn} + \dots + x_rU^T e_m$
\n 1 These are 0 because the best
\n $m-r$ rows of U are O.
\n $= x_1U^T e_1 + \dots + x_rU^T e_r = 0$
\n $= x_1U^T e_1 + \dots + x_rU^T e_r = 0$
\n 1 This implies $x_1 = -x_1 = 0$ because
\n 1 the first r rows of U are LT
\nSo $0 = (I^T[x_1, x_2, x_3) \in Span\{e_{rn}, e_{rn} = \dots \infty\}$

This proves the claim.
\nNow,
$$
U = EA \Rightarrow U^T = ATE^T
$$
, so
\n $A^T E^T x = 0 \Leftrightarrow U^T x = 0$
\n $\Leftrightarrow x = \alpha_{r+1}C_{r+1} + \alpha_{r+2}C_{r+2} + \cdots + \alpha_{n}E_{n}$
\n $E^T x = \alpha_{r+1}E^T e_{r+1} + \alpha_{r+2}E^T e_{r+2} + \cdots + \alpha_{n}E^T e_{r+1}$
\n $= \alpha LC \text{ of the last max } \text{ as } E$
\n $\Rightarrow A^T E^T x = 0$
\n $\Rightarrow E^T x \in Span\{\text{last max } \text{ has a } E\}$
\n $(\text{Use left null space})s$ changed by
\n $P \Rightarrow \text{ operations:}$
\n $A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 1 & 2 & -1 & -2 \end{bmatrix}$ $Nu1(A^T) = Span\{(\frac{1}{i})\}$
\n $(\frac{1}{i})^2 = \frac{1}{i} \Rightarrow \frac{1}{i} \Rightarrow \frac{1}{i} \Rightarrow Mu1(W^T) = Span\{(\frac{1}{i})\}$

 N

The row picture subspaces (Nul(A), Row(A)) are unchanged by now operations The col picture subspaces $\bigl(\text{Col}(A), \text{Nu}(A^T)\bigr)$ are changed by new operations. at dam Rowlf dat dinColla dA \Box row picture Rⁿ Col Dicture Rn

off the row space lives in the row picture The null space lives in the row picture The other two live in the column picture That's how you keep them straight Consequences Row Rank Column Rank dim Raw A rank din Colla So A At have the same pivots in completely different positions Hw 5 Rank Nullity dim Col A dm Nal A ⁿ cols dm Row A dm Nal At ^m rows demos NB You can compute bases for all four subspaces by doing elimination once As A In US RREFCASIE Get the pivots of Aus Col A Get RREFCA us PVF of Ax O Nal A Get nonzero rows of RREFCA Row A Get rows of ^E us Nal At

Full-Rank Matrix will have largest rank possible.
\nThis is an important special case.
\nDef: An max matrix A of rank r has:
\n• full column rank if r=n eq.
$$
\begin{pmatrix} 1000 \\ 0010 \\ 0001 \end{pmatrix}
$$

\n[cemy down has a pivot) \n\n- full row rank if r=n eq. $\begin{pmatrix} 1000 \\ 0010 \\ 0000 \end{pmatrix}$
\n- Full row rank if r=m eq. $\begin{pmatrix} 16000 \\ 01000 \\ 0000 \end{pmatrix}$
\n- Full row rank if r=m eq. $\begin{pmatrix} 16000 \\ 010000 \\ 0000 \end{pmatrix}$
\n- Heiry now has a pivot) \n[See part 4 min $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$
\n- Here, full ny/column rank means full rank
\n[See largest possible rank.

 $NB: A$ has full column rank $\Rightarrow p = r \in M$ $\Rightarrow A$ is tall f_{at} least as many rows as cold A has full road rank \Rightarrow m=r $\leq n$ $\Rightarrow A$ is wide lat least as many cols as rows)

We've seen several properties of matrices that translate into there's ^a prot ^m every column Thin: The Following Are Equivalent (TFAE): (for a given matrix A, all are true or all are false) ¹ A has full column rank $(i \wedge A$ has a pivot in every column (1) A has no free columns. (2) Nul (4) = { 03 $2')$ $Ax = O$ has only the trivial solution. 2 ") $Ax = b$ has O or 1 soln for every $b \in \mathbb{R}^n$ 3 The columns of A are LI (4) dim $Col(A) = n$ (5) din Row (A) = n (s') Rav $(k) = \mathbb{R}^n$ $NB: |S\rangle \Longleftrightarrow |S\rangle$ because: The only n-dimensional subspace of $\mathbb R$ \overline{B} all of \overline{K} E_8 . There is no plane in \mathbb{R}^2 that doesn't fill up all $of \mathbb{R}^2$

Write seen several properties of methods that
\nfranslate into "thees a pivot m every row".

\nThm: TFAE:
\n(1) A has full row rank
\n(1') A REP of A has no zero rows
\n(2)
$$
dm
$$
 $Col(A) = m$

\n(2') $Col(A) = R^m$

\n \forall (2') $Ax = b$ is consistent for every b \in R^m

\n \forall (3') $Ax = b$ is consistent for every b \in R^m

\n(4) dm $R\omega(A) = m$

\n(5) $Nu(A) = f \circ f$

Again, $(2) \in (2)$ because the only m-dimensional subspace of $\mathbb R$ is all of $\mathbb R$

If A has full column rank and full row rank then $D = r = m$ \Rightarrow A is square and has n pivots: invertible. Thm: For an non matrix A, TFAE: (1) A \approx muentible (2) A has full column root (3) A has full row rank (4) RREF(A)= T (5) There is a matrix β with $AB = \Gamma_n$ (6) There is a matrix β with $\beta A = I_n$ $x+7$ Ax=b has exactly one solution for every b (8) A^T is invertible unamely, $x=$ A⁻¹b C ran $\text{rank} = \text{col}$ ank)

Consequence: Let
$$
\{v_{y-y}v_0\}
$$
 be vector in \mathbb{R}^n

\nas $A = \{\psi_1 \cdots \psi_n\}$ is an even matrix.

\n(1) $\{v_{y-y}v_0\} = \mathbb{R}^n \iff G_0(A) = \mathbb{R}^n$

\n $\iff A$ has FRR

\n $\iff A$ is invertible

\n(1) $\{v_{y-y}v_0\}$ is LT

\n(2) $A \times = 0$ has only the initial solution

A has FCR As invertible

Of course, $(1)+(2)$ means $\{v_0,...,v_n\}$ is a b asis for \mathbb{R}^n , so

$$
\left(\begin{array}{cc}\n\text{base} & \text{base} \\
\text{linear:} & \text{base} \\
\text{where} & \text{linear:} & \text{base}\n\end{array}\right)
$$