Quadratic Optimization: Variant Lost time: we discussed Sinding the extremal (mind max) values of a quadratic form  $q(x) = \sum_{i}^{t} a_{ij} X_{i} X_{j}$ subject to the constraint  $|=||x||^2 = x_1^2 + \dots + x_n^2$ . Procedure:  $q(x) = x^{2}Sx$  for S symmetric orthogonality dissonatize:  $S = QDQ^{T} D = \begin{pmatrix} \lambda_{1} & 0 \\ 0 & \lambda_{n} \end{pmatrix}$ change variables: x = Qy  $\lambda_{1} = \lambda_{2} = - = \lambda_{n}$  $\Rightarrow q(x) = \lambda y_1^2 + \dots + \lambda y_n^2$ Answeri maximum =  $\lambda_{r}$ , achieved at any unit  $\lambda_{r}$ -eigenvector maximum =  $\lambda_{r}$ , achieved at any unit  $\lambda_{r}$ -eigenvector Here's an (almost) equivalent variant of this problem that you can draw. Quadratiz Optimization Problem, Variant: Given a quadrater form q(x), find the minimum & maximum values of IX12 subject to q(x)=1. So we switched the function were extremizing (1|x1|2) and the constraint (qW=1).



IF 
$$\lambda \ge \lambda_2$$
 then  $\lambda \le \lambda_2$ . The vectors  
 $t = (t + \lambda_1, 0)$  and  $t + \lambda_2 = (0, t + \lambda_2)$   
bits lie on the ellipse  $\lambda_1 \times 1^2 + \lambda_2 \times 2^2 = 1$ .  
 $t = 0$  are the shortest  
 $dx \in 1$  vectors on the ellipse  
 $\| \frac{1}{24} \in \|^2 = \frac{1}{4} = minimum \text{ length}^2$   
 $t = 0$  are the longest  
 $\| \frac{1}{24} = 2^2 = \frac{1}{42} = maximum \text{ length}^2$   
In general,  $q(x) = \lambda_1 \times 2^2 + \cdots + \lambda_1 \times 2^2$  (all  $\lambda_1 > 0$ )  
defines an ellipsoid (legg"); extremizing  $\|x\|^2$   
subject to  $q(x) \ge 1$  means binding the shortest  
8 longest vectors.  
 $t = 0$  are the shortest  
 $dx \in 1$  vectors on the ellipsoid  
 $\| \frac{1}{24} \in \|^2 = \frac{1}{4} = minimum \text{ length}^2$ 

= 1 are the longert Then vectors on the ellipsoid  $\| \pm \|_{2}^{2} = \pm = \max(\max \log h^{2})^{2}$  What if gle K not diagonal?

lyuy2)-plane (0, 1)

We still need the condition "All his 0"- otherwise a min or mox may not exist.

Def: A quadratiz form is positive-definite if q(k)>0 for all x+0.

NB: If q(x)=xTSx then q is positive-definite >>> 5 is positive-definite This is the positive energy criterion. Suppose that qui=xTSx is positive-definite. Let  $\lambda \ge \lambda_2 > 0$  be the eigenvalues of S and  $u_1, u_2$  orthonormal eigenvectors. Change mariables: X=Qy Q=(4, 4) q(x) = 1 $\lambda_i y_i^2 + \lambda_2 y_2^2 = 1$ (xyx2)-plane

multiply

by Q

 $u_1 = Q e_1$  $u_2 = Q e_2$ 

1, NI

Upshot: If q is positive-definite, then g(x)=1 defines a (rotated) ellipse. The minor exis is in the u,-direction. -> The shortest vectors are the un The major axis is in the uz-direction. - The longest vectors are the Uz. Orthogonally diagonalizing S=QDQT found the major & mor axes & radii!



shortest redors: 
$$\pm \frac{1}{12}u_1 = \pm \frac{1}{16}\begin{pmatrix} -1 \\ 1 \end{pmatrix}$$
 length? = 1/3  
langest rectors:  $\pm \frac{1}{15}u_1 = \pm \frac{1}{16}\begin{pmatrix} -1 \\ 1 \end{pmatrix}$  length? = 1/2 >  $\frac{1}{3}$   
(subject to  $q(x)=1$ )  
The orthogonal disagonalization procedure took the  
ellipse  
 $q(x_1, x_2) = \sum_{n=1}^{\infty} x_1^2 + \sum_{n=1}^{\infty} x_n^2 - x_1 x_2$   
and found its region 4 minor axes & radii: the  
change of variables  
 $x=Qy = \frac{1}{12}\begin{pmatrix} -1 \\ 1 \end{pmatrix} \begin{pmatrix} 91 \\ 92 \end{pmatrix}$  is  $x_1 = \frac{1}{12}(-9x+9x)$   
 $x_2 = \frac{1}{12}\begin{pmatrix} -1 \\ 1 \end{pmatrix} \begin{pmatrix} 91 \\ 92 \end{pmatrix}$  is  $x_1 = \frac{1}{12}(-9x+9x)$   
 $x_2 = \frac{1}{12}\begin{pmatrix} -1 \\ 1 \end{pmatrix} \begin{pmatrix} 91 \\ 92 \end{pmatrix}$  is  $x_1 = \frac{1}{12}(-9x+9x)$   
made  $q(x)=1$  into the standard (non-rotated) ellipse  
 $3y_1^2 + 2y_2^2 = 1$ .

Relationship to the original QO problem:  
How is this "almost equivalent" to extremizing qbd subject to  
$$|bd| = 1?$$
  
Recall:  $q(cx) = c^2 q(x)$ 

Fact: If q is positive - definite then  
U maximizes 
$$q(u)$$
  
subject to  $\|u\| = 1$   
with maximum  
value  $\lambda_1$   
U minimizes  $q(u)$   
subject to  $\|u\| = 1$   
with minimum  
value  $\lambda_1$ .  
and  
 $x = J\lambda_1 u$  minimizes  
 $q(x) = q(u)$   
subject to  $\|u\| = 1$   
with minimum  
value  $\lambda_n$   
 $x = J\lambda_1 u$  maximum  
value  $\lambda_1$ .  
and  
 $x = J\lambda_1 u$  maximum  
value  $\lambda_1$ .  
 $y(x) = q(u) = \lambda > 0$  and  $x = J\lambda_1 u$  then  
 $\|x\|^2 = \lambda_1$   
 $q(x) = q(J\lambda_1 u) = \lambda_1 q(u) = \lambda_1 \lambda = 1$ .  
IF  $\lambda$  is minimized then  $\|x\|^2 = \lambda_1$  is minimized

and vice-versa.

So the QO variant gles us a picture of the original QO problem, at least when 9 is positivedefaulter where just fondary axes & radii of ellipsoids. Additional Constraints

These come up naturally in practice (see the spectral graph theory problem on the HW) and in the PCA. "Second-largest value:

Suppose qlx) is maximized (subject to ||x||=1) at U.. What is the maximum value of qlx) subject to ||x||=1 and x L U.?

This rules out the maximum value -> get "second largest" value.

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NB: If 
$$\lambda_1 > \lambda_2$$
 then  $u_2 \perp U_1$  automotically.  
Why?  
• If  $q = \lambda_1 y^2 + \dots + \lambda_n y_n^2$  is diagonal then  
 $u_1 = e_1 = (1, 9)_n$  so  $x \perp u_1$  means  $y_1 = 0$   
 $u_2$  extremizing  $\lambda_2 y^2 + \lambda_3 y^2 + \dots + \lambda_n y_n^2$ .  
• Otherwise, change variables  $x = Qy$ .  
Q is orthogonal, so  
 $y \cdot q = 0 \implies 0 = (Qy) \cdot (Qe_1) = x \cdot u_1$   
 $\|y_1\| = 1 \implies 1 = \|Qy\| = \|x\|$   
(relate constraints on  $x \neq y$ )  
Eq: Find the largest and second-largest values of  
 $q(x) = 2x_1^2 + 2x_2^2 + 5x_3^2 + 2x_2 - 8x_1x_3 + 8x_1x_3$   
subject to  $x_1^2 + x_3^2 + x_3^2 = 1$ .  
•  $q = x^T 5x$  for  $S = \begin{pmatrix} 2 & 1 & -4 \\ -4 & 4 & 5 \end{pmatrix}$   
•  $S = QDQT$  for  
 $Q = \begin{pmatrix} -1/R & V_1 & 1/S \\ V_16 & V_15 & -1/V_3 \end{pmatrix} D = \begin{pmatrix} 9 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -3 \end{pmatrix}$ 

Largest value is q(x)=9 at  $x=\pm f_0(\frac{1}{2})=\pm u_1$ Second-largest value: The maximum value of q(x) subject to  $\|x\||=1$  &  $x\pm u_1$  is q(x)=3 achieved at  $x=\pm f_0(\frac{1}{2})$ This also varks for minimizing.

Second-smallest value: Suppose qlx) is minimized (subject to IIXII=1) at Un. What is the minimum value of qlx) subject to IIXII=1 and x\_Un? Answer: The minimum value of qlx) subject to IIXII=1 & x\_Un is  $\lambda_{mi}$ . It is achieved at any unit  $\lambda_{mi}$  ergenvector  $U_{m-1}$  that is  $\_U_{m}$ . (automatic if  $\lambda_{mi} > \lambda_{m}$ ) You can keep going: Third-lergest value: Suppose q/x) is maximized (subject to 1/x11=1) at u. and q(x) is maximized (subject to ||x||=1 and x-ly.) at Uz. What is the maximum value of 96c) subject to |x|=1 and x L u, and x L uz? NB: This "rules out" the largest & second-largest relues. Answer: The maximum value of qlx) subject to IIXII=1 & x+u, & x+uz is >3. It is achieved at any unit No-eigenvector Us that is LU, and uz. (automatic it  $\lambda_2 > \lambda_3$ ) This also works for the variant problem, except you have to take reciprocals.

Et cetera...

Quadratiz Optimization for S=ATA This is what we'll use for PCA. Let S=ATA and g(x)=xTSx. Then  $q(x) = x^T S x = x^T (A^T A) x = (x^T A^T) (Ax)$  $= (A_{x})^{T}(A_{x}) = (A_{x}) \cdot (A_{x}) = |A_{x}|^{2}$ gb)= ||Ax|12 is a guadratic form with S=ATA In this case, extremizing g(x) subject to ||x||=1 means extremizing ||Ax||<sup>2</sup> subject to ||x||=1. Procedure: to extremize ||Ax||<sup>2</sup> subject to ||x||=1: Orthogonally diagonalize S=ATA is orthonormal eigenboss {us...,un?, ATA is we-semidefinite eigenvalues λ, ≥···>> h ≥0~ • The largest value is  $\lambda$ , achieved at any unit & - eigenvector U. • The smallest value is  $\lambda_n$ , achieved at any unit & - ergenvector Un. · The second-largest value is N2, achieved at any unit  $\lambda_2$ -eigenvector  $u_2 \perp u_1$ . o . etc.

NB: these are eigenvectors/eigenvalues of S=ATA,  
not of A (which need not be square).  
Def: The matrix non of a matrix A is  
NAI = the newimum value of NAXI subject to  
NXII=1.  
So NAI= 
$$\int_{X_1} = |argest eigenvalue of ATA.$$
  
Eg: Compute NAII for  $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .  
 $ATA = \begin{pmatrix} 2 & 3 \\ 2 & 3 \end{pmatrix} p(\lambda) = \lambda^2 - 6\lambda + S = (\lambda - S)(\lambda - 1)$   
the largest eigenvalue is  $\lambda = S$ , so  $|AII| = IS$ .  
Eigenvector:  $\begin{pmatrix} -b \\ a - \lambda \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \end{pmatrix}$   
Unit eigenvector:  $u_1 = \int_{S=1}^{S=1} \begin{pmatrix} -2 \\ -2 \end{pmatrix} = \int_{S=1}^{L} \begin{pmatrix} -1 \\ -1 \end{pmatrix}$   
has length  $\int_{S=1}^{L} \int_{T^2+\lambda^2+3^2+1}^{Z^2} = \int_{S=1}^{TO} = \int_{S}^{TS} \sqrt{12}$