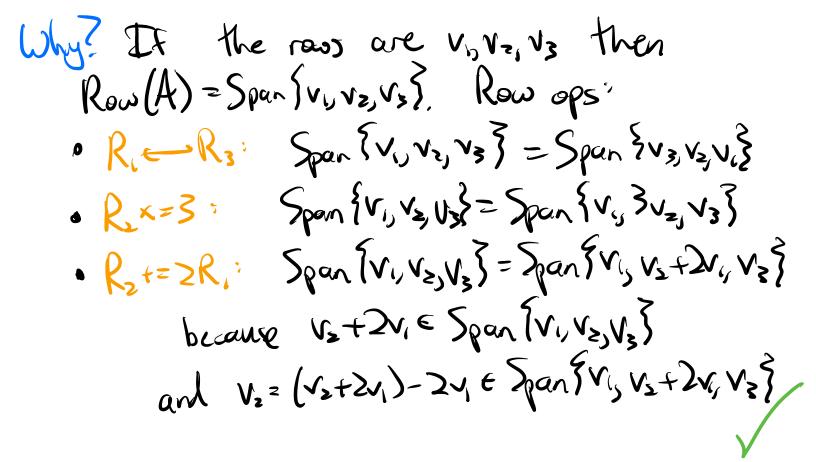
The Four Subspaces Recall: To any matrix A, we can associate: · Col(A); basis = pivot columns of A; dim=rank · Nul(A); basis = vectors in the PVF of Ax=0; din= #fre vars = #cds - rank There are two more subspaces: just replace A by AT, then take Col & Nul. Why? Orthogonality we least \$\Pis\$ (bear with me...) Det The now space of A is Row(A) = Col(AT). This is the subspace spanned by the rows of A, regarded as (row) redoes in R.". This is a subspace of  $\mathbb{R}^n$  n=# columns (n=# each row) ~> row picture

Eg. Row 
$$(456) = Span \{ (\frac{1}{3}), (\frac{1}{4}) \}$$
  
=  $(a) (\frac{1}{3}, \frac{1}{4}) = (a) (\frac{1}{3}, \frac{1}$ 

Fact: Row operations do not change the row space.



This is a col space (of AT), so you know how to compute a basis (pinot columns of AT), But you can also find a basis by doing elimination on A:

Thm: The nonzero rows of any REF of A form a basis for Row(A).

$$\begin{cases}
1 & 2 & 2 & 1 \\
2 & 4 & 1 & -1 \\
1 & 2 & -1 & -2
\end{cases}$$
REF [1 2 2 1]
$$\begin{cases}
0 & 0 & -3 & -3 \\
1 & 2 & -1 & -2
\end{cases}$$
Rays:
$$\begin{cases}
\begin{pmatrix}
1 & 2 & 2 & 1 \\
0 & 0 & -3 & -3
\end{pmatrix}$$
Rays:
$$\begin{cases}
\begin{pmatrix}
1 & 2 & 2 & 1 \\
0 & 0 & -3 & -3
\end{pmatrix}$$

(another) Basis: 
$$\left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

Prof:

(1) Spans' now ops don't change Rowld)
and you can always delete the zero rector
without changing the span

Solve by forward-substitution:

= pivot, so this entry in the sum is just  $(1) \cdot x_1 = 0 \Rightarrow x_1 = 0$ 

= pivot, so this entry in the sum is just  $(-3) \times_2 = 0 \Longrightarrow \times_2 = 0$ 

Consequence: dim Rew(A) = # pivot rows =# pivot = rank.

(a nonzer row of an REF matrix has a pivot)

Det: The left null spece of A is Nul(AT).
This is the solution set of $A^{T}x=0$ .
Notation: Just Nul (AT) (no new notation)
This is a subspace of IRM m= # 18005
(m= #columns of AT)
~> column picture

MB:  $A^{T}x = 0 \iff 0 = (A^{T}x)^{T} = x^{T}A$ So  $Nul(A^{T}) = \{\text{now vectors } x^{T} \in \mathbb{R}^{m}: x^{T}A = 0\}$ 

Nul(AT) is a null space, so you know how to compute a basis (PVF of ATX=0). You can also find a basis by doing elimination on A:

Thm/Procedure: To compute a basis of Nul (AT):

- (1) Form the augmented matrix (A)Im)
- (2) Eliminate to REF
- (3) The rows on the right side of the line next to zero rows on the left form a basis of Null(AT).

$$A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 1 & 2 & -1 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 2 & 1 & | & 0 & 0 \\ 2 & 4 & 1 & -1 & | & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 = 2R_1} \begin{bmatrix} 1 & 2 & 2 & 1 & | & 0 & 0 \\ 0 & 0 & -3 & -3 & | & -2 & 1 & 0 \end{bmatrix}$$

$$R_3 = R_1 \begin{bmatrix} 1 & 2 & 2 & 1 & | & 0 & 0 & 0 \\ 0 & 0 & -3 & -3 & | & -2 & 1 & 0 \end{bmatrix}$$

$$R_3 = R_2 \begin{bmatrix} 1 & 2 & 2 & 1 & | & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & -1 & 1 & 0 \end{bmatrix}$$

$$R_3 = R_2 \begin{bmatrix} 1 & 2 & 2 & 1 & | & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & -1 & 1 & 0 \end{bmatrix}$$

$$R_3 = R_2 \begin{bmatrix} 1 & 2 & 2 & 1 & | & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & -1 & 1 & 0 \end{bmatrix}$$

$$R_3 = R_2 \begin{bmatrix} 1 & 2 & 2 & 1 & | & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & | & -1 & 1 & 0 \end{bmatrix}$$

Check: 
$$(1 - (1)) \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 - 1 \\ 1 & 2 & -1 & -2 \end{bmatrix} = (0 & 0 & 0)$$
so at least  $(-1) \in \text{Nul}(AT)$ 

Consequence:

Proof of the Thm: Suppose AREF U. Then

$$U = E \cdot A$$
 $E = product$  of elementary matrices

 $E \cdot (A \mid Im) = (EA \mid EIm)$ 
 $= (U \mid E)$ 

So the result of performing elimination on (AIIm) is (UIE).

If U is in REF and the last m-r rows are zero then we claim:

Nul(ut) = Spansen, enz, moen]:

We know We: = the ith now of U.

We know from before that the nonzero rows of U are LI. So if (xv...,xm) & Wal (UT) Hen

 $O=U^{T}\begin{pmatrix} x_{m} \\ x_{m} \end{pmatrix} = x_{1}U^{T}e_{1} + \cdots + x_{r}U^{T}e_{r}$ +xru UTer, + ··· + xn UTem.

These are 0 because the last m-r rows of U are O.

= x, UTe, + ... + x, UTer =0

This implies  $x_1 = x = 0$  because the first rooms of U are LI

So ()= (1 (x,,,xm) (=> x,=...=xr=0) (x,, x,) E Spangery, errz, ..., em?

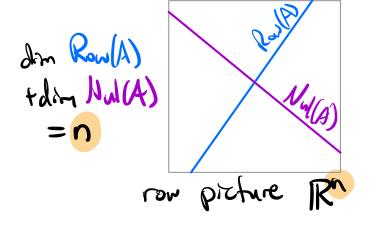
This proves the claim. Now, U=EA => UT=ATET, So ATEX=0 => UTX=0 = X= arelly + arestrest "+ amen But Ete: is the it row of E, so Ex=ani ETeni+ane ETenz+...+an Etem = a LC of the last mor rows of E 50 ATE X 20 ⇒ Ex € Span } last mor rows of E} (I've left out some details at the end) NB: The left null space is changed by row operations, Nul (AT) = Span { (1)}  $A = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 1 & -1 \\ 1 & 2 & -1 & -2 \end{bmatrix}$ Nul (ut) = Span { ( ) }  $U = \begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ 

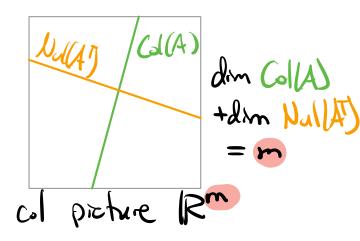
## Summary: Four Subspaces A: on man matrix of rank r

Subspace	et.	(O)	din	basis
Col(A)	Rm	col	r	pivot colo d'A  # pivot colo
Nul (A)	R"	<b>100</b>	n-r	rectors in PVF three vars
Rau (A)	R"	നംപ	r	norzero rous of REF
Nul (AT)	Rm	col	m-C	tepirations  last m-r rows of E  tero rows in REF

The row picture subspaces (NullA), Ros(A)) are unchanged by row operations.

The col picture subspaces (CollA), Null(AT)) are changed by row operations.





The null space lives in the ... row proture!
The null space lives in the ... column protuc!
The other two live in the ... column protuc!
That's how you keep them straight.
Consequences:

Row Rank = Column Rank dm Row (A) = rank = dm (0.1/A)

So A & AT have the same # pivots in completely different positions! (HW#5)

> Rank - Nullity dim Col(A) + dim Nul(A) = n = # cols dim Row(A) + dim Nul(AT) = m = # rows

> > [demos]

NB: You can compute bases for all four subspaces by doing elimination once.

A~ [A|Im] ~ [RREF(A)|E]

- · Get the pivots of A-s Col(A)
- · Get RREF(A) ~> PVF of Ax=0 -> Nul(A)
- · Get nonzero rows of RREF(A) ~> Row(A)
- . Get rows of E -> Nul(AT)

## Full-Rank Matrices

A "rondom" matrix will have largest rank possible. This is an important special case.

Def: An man matrix A of rank - has:

- full column rank it r=n eg. (010)

  (every column has a pivot)
- full row rank if r=m eg. (000)

  (every row has a prot)

118: Each row & column has at most one pivot so r = min 3 min 3

Henre full nou/column rank means full rank ie. largest possible rank.

NB: A has full column rank >> n=rem

I A is tall lat least as many rows = rest

A has full row rank >> m=ren

I A is wide lat least as many ask as rows)

We've seen several properties of matrices that translate into "there's a privat in every column". Thm? The Following Are Equivalent (TFAE): (for a given matrix A, all are true or all are false) (1) A has full column rank (11) A has a pivot in every column (1") A has no free columns. (2) Nul(A) = 503 (2') Ax = 0 has only the trivial solution. \$\frac{1}{2}\text{ (2')} Ax = \text{b has 0 or 1 solution for every be \$\mathbb{R}^m\$ (3) The columns of A are LI (4) dim (ol(A) = n(5) din Row(A)=n (5') Row (A) = R" NB: (5) (5') because: The only n-dimensional subspace of 1Rn is all of 1Rn

Est There is no plane in IR? that abosin't fill up all of IR?

We're seen several properties of matrices that translate into "there's a proof in every row".

Thm: TFAE:

(1) A has full row rank

(1) A has a pivot in every row

(1") A REP of A has no zero nows

(2) dm Col(A)= m

(2') GI(A)= RM

A(2'') Ax=b is consistent for every  $b \in \mathbb{R}^m$  What 1 or  $\infty$  solutions)

(3) The columns of A span IRM

(4) dm Kow(A) = m

(5) Nul (AT) = {0}

Again, (2)=(2') because the only m-dimensional subspace of Rm is all of Rm.

IF A has full column rank and full row rank then
n=r=m
=> A is square and has a pivots: inventible
Thm: For an non matrix A TFAE:
(1) A is invertible
(2) A has full column rank
(3) A has full now mank
(4) RREF(A)=In
(5) There is a matrix B with AB=In
(6) There is a matrix B with BA = In
\$(7) Ax=b has exactly one solution for every b
(8) AT is invertible snamely, x=A-b
(s (row rank = col rank)

Consequence: Let {vo-vn} be rector in R ~ A= (vi... vn) & an matrix. (1) Span {v,, , vn}= R" => G/(A)=1R" A has FRR => A is invertible (1) SV,..., V, 3 3 LI Ax=0 has only the trivial soln A has FCR => A is invertible Of course, (1)+(2) means {v,..., v,3 is a boisis for Ry so (basis for) = (columns of an invertible nxn matrix)

More on this next time (Basis Theorem).