Solving Systems of Equations using Elimination

Here's a system of 3 equations in 3 variables:

$$\begin{cases} x_1 + 2x_2 + 3x_3 = 6 \\ 2x_1 - 3x_2 + 2x_3 = 14 \\ 3x_1 + x_2 - x_3 = -2 \end{cases}$$

How to salve it?

- Substitution: solve $1^{\frac{5t}{2}}$ equation for x_i , substitute into $2^{\frac{nd}{2}}$ & $3^{\frac{nd}{2}}$, continue.
- · Elimination: "combine" the equations to eliminate

Elimination turns out to scale much better (to more equations & variables), so we'll focus on that.

"replace the 2rd equation with the 2rd minus Dotte 1st"

Eg:
$$x_1 + 2x_2 + 3x_3 = 6$$

$$2x_1 - 3x_2 + 2x_3 = 14$$

$$3x_1 + x_2 - x_3 = -2$$

$$3x_1 + x_2 - x_3 = -2$$

$$3x_1 + x_2 - x_3 = -2$$

$$R_{3}=3R_{1}$$

$$X_{1}+2x_{2}+3x_{3}=6$$

$$-7x_{2}-4x_{3}=2$$

$$-5x_{2}-10x_{3}=-20$$

Now we have eliminated x, from the 2rd 23rd eq.5

These now form 2 equations in 2 variables: simple! $x_1 + 2x_2 + 3x_3 = 6$ $R_3 = \frac{5}{7}R_2$ $x_1 + 2x_2 + 3x_3 = 6$ $-7x_2-4x_3=2$ $-7x_2-4x_3=2$ $-5x_2-10x_3=-20$ We eliminated x_n from the last equation: now it's one equation in one variable. Easy! We can now some ma back substitution: $-\frac{50}{7}x_3 = -\frac{150}{7}$ $\implies x_3 = 3$. Substitute into 2nd equation: $-7x_{2}-4x_{3}=2$ \longrightarrow $-7x_{2}-4-3=2$ Now solve for xz -7x2-12=2 => -7x2=14=> x2=-2 Substitute both into 1st equation: $x_1 + 2x_2 + 3x_3 = 6 \longrightarrow x_1 + 2 - (-2) + 3 - 3 = 6$ Now solve for x, $x_1 - 4 + 9 = 0$ \Rightarrow $x_1 = 1$ Check: | + 2(-2) + 3(3) = 6 $| 2 \cdot | - 3(-2) + 2(3) = 14$ $| 3 \cdot | + (-1) - 3 = -2$

NB: In this case there was one solution - since we could

isolate each variable, all values were determined.

Does this always work?

Eg:
$$4x_1 + 3x_3 = 25$$

 $x_1 + x_2 - x_3 = 3$
 $2x_1 - 3x_2 - 6x_3 = -3$

Now eliminate as before:

$$x_1 + x_2 - x_3 = 3$$
 $4x_1 + 3x_3 = 2$
 $2x_1 - 3x_2 - 6x_3 = -3$

$$x_1 + x_2 - x_3 = 3$$
 $4x_1 + 3x_3 = 2$
 $-5x_2 - 4x_3 = -9$

$$x_1 + x_2 - x_3 = 3$$
 $4x_1 + 3x_3 = 2$
 $-\frac{1}{4}x_3 = -\frac{13}{2}$

Solve using back-substitution:

$$-\frac{1}{4}x_3 = -\frac{13}{2} \implies x_3 = 26$$

Substitute into 2nd equation:

$$4x_1 + 3(26) = 2 \implies x_2 = -19$$

Substitute both into 1st equations

there is one solution: each variable was isolated in one equation.

Check:
$$4x_{2} + 3x_{3} = 2$$
 $x_{1} + x_{2} - x_{3} = 3$
 $2x_{1} - 3x_{2} - 6x_{3} = -3$
 $2x_{1} + 2x_{2} + 3x_{3} = 1$
 $2x_{1} + 5x_{2} + 6x_{3} = 0$
 $2x_{2} - 6x_{3} = -4$
 $2x_{1} + 7x_{2} + 7x_{3} = -1$
 $2x_{2} - 6x_{3} = -4$
 $2x_{1} + 7x_{2} + 7x_{3} = -1$
 $2x_{2} - 6x_{3} = -4$
 $2x_{1} - 3x_{2} - 6x_{3} = -4$
 $2x_{2} - 6x_{3}$

We'll deal with this in Week 3.

Eg: $X_1 + 2x_2 + 3x_3 = 1$ $4x_1 + 5x_2 + 6x_3 = 0$ $7x_1 + 9x_2 + 9x_3 = 0$ $8x_3 - 2R_2$ $8x_4 - 6x_3 = -4$ $8x_4 - 6x_3 = -4$ $8x_4 - 6x_3 = -7$ $8x_4 - 6x_4 = -7$

If our original equations were trues then O=1. Thus our system has no solutions. (last 2 eqns are parallel planes)

Row Operations are the allowed manipulations we can perform on our equations.

(1) $x_1 + 3x_2 + 3x_3 = 6$ $2x_1 - 3x_2 + 2x_3 = 14$ $3x_1 + x_2 - x_3 = -2$ $3x_1 + x_2 - x_3 = -2$ $3x_1 + x_2 - x_3 = -2$

row replacement replace Rz by Rz-2R,

(2) $x_1 + 2x_2 + 3x_3 = 6$ $2x_1 - 3x_2 + 2x_3 = 14$ $2x_1 - 3x_2 + 2x_3 = 14$ $3x_1 + x_2 - x_3 = -2$ $3x_1 + x_2 - x_3 = -2$ $3x_1 + x_2 - x_3 = -2$

row swap (change order)

(3)
$$x_1 + 3x_2 + 3x_3 = 6$$
 $R_1 \times = 2$ $2x_1 + 4x_2 + 6x_3 = 12$ $2x_1 - 3x_2 + 2x_3 = 14$ $3x_1 + x_2 - x_3 = -2$ $3x_1 + x_2 - x_3 = -2$ 5 calar multiplication (by nonzero scalar)

Obviously if (xyxxxxx) is a solution before doing a row operation, then it is true after Eg-row replacement:

 $x_1+2x_2+3x_3 \longrightarrow 6 = 6$ $2x_1-3x_2+2x_3-314=14$ $x_1+2x_2+3x_3 \longrightarrow 6=6$ $-7x_2-4x_3 \longrightarrow 2=2$

Fact: All these operations are reversible: if you have a solution (x, x, x,) after doing a row operation, then it's also a solution before.

This was the whole point: we wanted to solve our loriginal) system of equations!

Questions: How do you undo (reverse):

- · R, += Rz? R, -= Rz · R, x= 2? R, += 2
- · R. -R.? R. R.

The variables $x_0 \times x_2 - \cdot \cdot$ are just placeholders; only their coefficients matter. Let's extract them into a matrix. Three Ways to Write System of Linear Equations (1) As a system of equations: $x_1 + 2x_2 + 3x_3 = 6$ $2x_1 - 3x_2 + 2x_3 = 14$ (2) As a matrix equation Ax = b $\begin{bmatrix} 1 & 2 & 3 \\ 1 & -3 & 2 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$ A × b It you expand out the product you get

which is what we had before.

The coefficient matrix A comes from the coefficients of the variables:

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & -3 & 2 \end{bmatrix} \iff \begin{bmatrix} 1x_1 + 2x_2 + 3x_3 \\ 2x_1 + 3x_2 + 2x_3 \end{bmatrix}$$

The vector
$$x = \begin{bmatrix} x_i \\ x_s \end{bmatrix}$$
 contains the unknowns or variables.

NB: A is an max matrix where
$$m = H$$
 equations $b \in \mathbb{R}^n = size m$ $n = H$ variables $x \in \mathbb{R}^n = size n$

(3) As an augmented matrix This is a notational convenience: just squash A & b together and separate with a line. $\begin{bmatrix} 1 & 2 & 3 & | & 6 \\ 2 & -3 & 2 & | & 14 \end{bmatrix} \longrightarrow \begin{bmatrix} 1x_1 + 2x_2 + 3x_3 = 6 \\ 2x_1 + 3x_2 + 2x_3 = 14 \end{bmatrix}$

$$\frac{2}{2}$$
 -3 $\frac{1}{4}$ $\frac{4}{3}$ $\frac{4}{2}$ $\frac{4}{3}$ \frac

[A I b]

Angmented matrices are good for row operations, which only affect the coefficients (not the variables):

$$x_1 + 3x_2 + 3x_3 = 6$$
 $2x_1 - 3x_2 + 2x_3 = 14$
 $R_2 = 2R_1$
 $x_1 + 3x_2 + 3x_3 = 6$
 $-7x_2 - 4x_3 = 2$

 $\begin{bmatrix} 1 & 2 & 3 & | & 6 \\ 2 & -3 & 2 & | & 14 \end{bmatrix} \xrightarrow{R_2=2R_1} \begin{bmatrix} 1 & 2 & 3 & | & 6 \\ 0 & -7 & -4 & | & 2 \end{bmatrix}$

Eg: Let's solve the system from before using augmented matrices:

$$\begin{cases} x_1 + 2x_2 + 3x_3 = 6 \\ 2x_1 - 3x_2 + 2x_3 = 14 \end{cases} = \begin{cases} 1 & 2 & 3 & | 6 & | \\ 2 & -3 & 2 & | 14 & | \\ 3x_1 + x_2 - x_3 = -2 & | & 3 & | & | & | & | \\ 3x_1 + x_2 - x_3 = -2 & | & & | & | & | & | \\ \end{cases}$$

$$\begin{bmatrix} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{bmatrix} \xrightarrow{R_2-22R_1} \begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & -7 & -4 & 2 \\ 3 & 1 & -1 & -2 \end{bmatrix}$$

$$\begin{array}{c|c} 1 & 2 & 3 & 6 \\ \hline 0 & -7 & -4 & 2 \\ \hline 0 & -5 & -10 & -20 \end{array}$$

$$R_{3} = \frac{5}{2}R_{3} \begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & -7 & -4 & 2 \\ 0 & 0 & -\frac{50}{7} & -\frac{150}{7} \end{bmatrix}$$

$$\begin{cases} x_1 + 2x_2 + 3x_3 = 6 \\ -7x_2 - 4x_3 = 2 \\ -\frac{59}{7}x_3 = -\frac{159}{7} \end{cases}$$

Now use back-substitution like before.

What does it mean to be "done? (in terms of augmented matrices)

Def: A matrix is in row echelon form (REF) if

(1) The first monzero entry of each now is to

the right of the now above it

(2) All zero nows are at the bottom

Important: When checking if an augmented matrix is in REF, ignore the augmentation line.

Think: REF means there's nothing left to eliminate! Each variable is eliminated in later equations, or can't be isolated.

Upshot: The elimination procedure terminates when your (augmented) natrix is in REF.

Solving a

linear system = Putting an
augmented matrix
into REF using
row operations

Det: The pirot positions (pivots) of a matrix are the positions of the 1st nonzero entries of each now after you put it into REF.

$$\begin{bmatrix} 1 & 1 & -1 & 4 \\ 0 & 0 & 3 & 12 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & 7 & 4 & 2 \\ 0 & 0 & 7 & 7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & 0 & 7 & 7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 & 6 \\ 0 & 0 & 7 & 7 \end{bmatrix}$$

Remarkaldy, this is well-defined!

Def: The rank of a matrix is the number of pivots it has (in REF).

Egi [1 2 3 6]
$$\begin{bmatrix}
1 & 2 & 3 & 6 \\
2 & -3 & 2 & 14
\end{bmatrix}$$

$$\begin{bmatrix}
1 & 2 & 3 & 6 \\
3 & 1 & -1 & -2
\end{bmatrix}$$

$$\begin{bmatrix}
1 & 2 & 3 & 6 \\
0 & 7 & 4 & 2
\end{bmatrix}$$

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0 & 7 & 4 & 2
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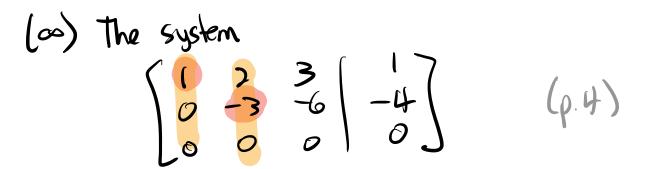
Member of Solutions (in terms of pivots)

The most basic question you can ask debout a system of equations is: how many solutions does it have? This is entirely determined by the pivot positions pivot columns (columns with a pivot)

had one solution. It has a pivot in every column except the augmented column. This means every variable will be soluted when doing back-substitution.

(a) The system
$$\begin{bmatrix}
0 & 3 & 6 & 6 \\
0 & 0 & 0 & 6
\end{bmatrix}$$
(p.5)

had no solutions. It has a pivot in the originated column, which leads to the equation 0=1.



had infinitely many solutions. If has no pivot in the augmented column and no pivot in the column for the variable xs. You can't isolate xs, so you can choose any value.

NB: You have to put the system on REF to find its pivots, so you have to do cook to know how many solutions there all.

Def. A system is consistent if it has at least 1 solution (so 1 or as). It is inconsistent otherwise.