## HOMEWORK 6

## DUE FRI. OCT. 9

**Reading:** Ready the "Notes on style and best practices" posted to Piazza.

For a head start, also skim the GitHub slides and create a repository. You may want to then use it for this homework (optional here; required next week!).

**Computational problems.** Note: you may want to refer to the trapezoidal rule example code from class. The 'ratio' calculations aren't required here, as you have exact solutions.

Q1 (Simpson's rule). Implement Simpson's rule using N subintervals (as simp(f,a,b,n). Then:

a) Test it on the integral

$$\int_0^2 (1-x^2)^2 \, dx = \frac{46}{15}$$

using  $n = 4, 8, \dots, 2^M$  sub intervals. Calculate the error and make a log-log plot (use enough points that you get near machine precision for the largest n).

The error behaves like  $Cn^{-p}$  for a certain value of p. Identify it from your plot and add a reference line [see e.g. the trapz.py lecture code).

b) Now test it on the integral

$$\int_0^\pi \frac{1}{4\sin^2(2x) + 1} \, dx \approx 1.404962946208145$$

Use equally spaced *n*-values  $n = 2, 4, 6, \dots, 200$ . Make a log-log and semi-log plot and figure out if the error like  $Cn^{-p}$  or like  $r^n$ .

Note: 'like' here really means 'bounded by' - there may be variation under this upper bound  $(e.g. \sin(x)/x^2 \text{ is } O(x^2) \text{ but oscillates})$ . You should only look at the error where its above machine precision - you may have to cut n off from the suggested values. It may also help to 'thin out' the n values (skip by more than 2)

Q2 (Adaptive integration). Review the given code for adaptive integration.

a) Using your Simpson's rule code, try computing the integral of

$$f(x) = 5e^{-50x} + \sin(x)$$

from x = 0 to  $x = \pi$  (get the exact value by any means e.g. Wolfram alpha or by hand). Verify the adaptive method uses less points to get the same error with a tolerance of  $10^{-5}$ .

b) Create an example where the situation is more extreme, e.g. the adpative method is better by a factor of 100 and an example where the adaptive method isn't much better .

Your "main" function should contain the code used to testat least part (b) (this can just be a print of the errors; you don't need plots).

Q3 (derivatives and rounding error). Note: we did a similar example weeks ago, which you can find in the 3\_numerics folder.

One formula for the third derivative<sup>1</sup> is the following:

$$f'''(x) \approx \frac{f(x+2h) - 2f(x+h) + 2f(x-h) - f(x-2h)}{2h^3}.$$

Suppose you need to approximate  $f''(x_0)$  where

$$x_0 = 1, \qquad f(x) = \cos 2x$$

as accurately as possible.

a) According to theory, the error satisfies

 $E \sim Ch^p$  as  $h \to 0$ 

for a certain value of p. Estimate this value numerically.

b) What, approximately, is the best choice of h and what is the minimum error? (note that you don't have to be very precise here - the right order of magnitude is acceptable). (question to think about: how does this differ from estimating an integral as accurately as possible, given your work in Q1?).

Have code that creates a plot or otherwise shows that your answer makes sense (but you can just put your answer in a comment).

c) (optional): When h is small enough, bad things happen. What is the behavior of the error like when h is small (in Big-O terms)? Does this makes sense?

<sup>&</sup>lt;sup>1</sup>You can derive this by using the formula (f(x+h) - f(x))/h to estimate f', then use the formula to estimate  $f''(x) \approx (f'(x+h) - f'(x))/h$  and so on.