

Math 621 HW 1 - Outline of Solutions

Note Title

1/24/2018

1. For $(z_1, \dots, z_{n+1}) \in \mathbb{C}^{n+1} - 0$, write $[z_1, \dots, z_{n+1}]$ for the equivalence class of $(z_1, \dots, z_{n+1})$ in $\mathbb{CP}^n$. $\mathbb{CP}^n$ is covered by
- $$V_j = \{[z_1, \dots, z_{n+1}] \mid z_j \neq 0\} \subset \mathbb{CP}^n, \quad 1 \leq j \leq n+1.$$

We have coord charts

$$f_j : U_j = \mathbb{C}^n \cong \mathbb{R}^{2n} \longrightarrow V_j \subset \mathbb{CP}^n$$

$$(x_1, y_1, \dots, x_n, y_n) \longmapsto [x_1 + iy_1, \dots, x_{j-1} + iy_{j-1}, 1, x_j + iy_j, \dots, x_n + iy_n]$$

(think of this as $(z_1, \dots, z_n)$ where $z_k = x_k + iy_k$)

(note not $\sqrt{-1}$)

We'll calculate transition function $f_j^{-1} \circ f_i$ for $i > j$ ($i < j$ is similar).

$$f_j^{-1} \circ f_i : f_i^{-1}(V_i \cap V_j) \longrightarrow f_j^{-1}(V_i \cap V_j)$$

$$\{(x_1, y_1, \dots, x_n, y_n) \mid (x_j, y_j) \neq (0, 0)\} \longrightarrow \{(x_1, y_1, \dots, x_n, y_n) \mid (x_{i-1}, y_{i-1}) \neq (0, 0)\}$$

$$\begin{aligned} f_j^{-1} \circ f_i (x_1, y_1, \dots, x_n, y_n) &= f_j^{-1}([x_1 + iy_1, \dots, x_{i-1} + iy_{i-1}, 1, x_i + iy_i, \dots, x_n + iy_n]) \\ &= \frac{1}{x_j + iy_j} (x_1 + iy_1, \dots, x_{j-1} + iy_{j-1}, x_j + iy_j, \dots, x_{i-1} + iy_{i-1}, 1, \\ &\quad x_i + iy_i, \dots, x_n + iy_n) \in \mathbb{C}^n \\ &= \frac{1}{x_j^2 + y_j^2} (x_1 x_j + y_1 y_j, x_j y_i - x_i y_j, \dots, x_{j-1} x_j + y_{j-1} y_j, x_j y_{i-1} - x_{i-1} y_j, \\ &\quad x_j x_j + y_j y_j, x_j y_{j+1} - x_{j+1} y_j, \dots, x_{i-1} x_j + y_{i-1} y_j, x_j y_i - x_i y_j, \\ &\quad x_j, -y_j, x_i x_j + y_i y_j, x_j y_i - x_i y_j, \dots, \\ &\quad x_n x_j + y_n y_j, x_j y_n - x_n y_j). \end{aligned}$$

Note this is smooth for $(x_j, y_j) \neq (0, 0)$.

2. (a) Cover $\mathbb{R}P^2$ by three coord. charts $\mathbb{R}^2 \rightarrow \mathbb{R}P^2$

$$(x, y) \mapsto \begin{bmatrix} x, y, 1 \\ x, 1, y \\ 1, x, y \end{bmatrix}$$

The first chart f_1 gives

$$F \circ f_1(x, y) = \frac{1}{1+x^2+y^2} (x^2-y^2, xy, x, y).$$

The derivative matrix for this is

$$\frac{1}{(1+x^2+y^2)^2} \begin{pmatrix} 2x(1+y^2) & y(1-x^2+y^2) & 1-x^2+y^2 & -2xy \\ -2y(1+x^2) & x(1+x^2-y^2) & -2xy & 1+x^2-y^2 \end{pmatrix}$$

and it's straightforward to check this has rank 2 $\forall (x, y)$;
Similarly for the other two charts.

(b) Show directly that $F(x, y, z) = F(x', y', z') \Rightarrow (x, y, z) = \pm (x', y', z')$
can-by-construction, depending on which of x, y, z, x', y', z' are zero
and which are nonzero.

3. (a) $\Leftarrow$: Given an oriented atlas for M such that all φ_g 's preserve orientation, construct an atlas for M/G as in class (or Ex 0.4.8). Tracing through the construction, we see that the transition functions on M/G are of the form

$h_g^{-1} \circ h_p = f_g^{-1} \circ \varphi_g \circ f_p$, and since φ_g preserves orientation, by definition $\det d(h_g^{-1} \circ h_p) > 0$. Thus this atlas for M/G is oriented.

$\Rightarrow$: Suppose M/G has an oriented atlas $\{(f_\alpha, U_\alpha, V_\alpha)\}$. For any $p \in M$, let $V_p \subset M$ be a nbd. of p as in the def. of properly discontinuous ($V_p \cap \varphi_g(V_p) = \emptyset \ \forall g \neq id$). Choose α such that $\pi(p) \in V_\alpha$. Then π is a bijection

$$V_p \cap \pi^{-1}(V_\alpha) \longrightarrow \pi(V_p) \cap V_\alpha$$

3. (a) and we can define a chart

Cart. d.

$$\pi^{-1} \circ f_\alpha : f_\alpha^{-1}(\pi(U_p)) \longrightarrow V_p \cap \pi^{-1}(U_\alpha)$$

$U_\alpha \subset \mathbb{R}^n$ $\hat{M}$

The collection of all such charts over all $p \in M$ gives an atlas for M , and this is oriented since the atlas for M/G is oriented. Furthermore, straightforward arrow chasing shows that φ_g preserves orientation $\forall g \in G$.

(b), (c). $\mathbb{RP}^n$: The antipodal map $a: S^n \rightarrow S^n$ satisfies

$$\pi_S \circ a \circ \pi_N^{-1}(x) = -x \quad \forall x \in \mathbb{R}^n$$

$\uparrow$
stereographic projection

Since $\{\pi_N^{-1}, \pi_S^{-1} \circ h\}$ is an oriented atlas for S^n , and
 $\det d(\pi_S^{-1} \circ h^{-1} \circ a \circ \pi_N^{-1}) = \det d(h \circ (\pi_S \circ a \circ \pi_N^{-1})) = (-1)^{n+1}$,
 a is orientation preserving if and only if n is odd.
 Thus by (a), $\mathbb{RP}^n$ is orientable $\Leftrightarrow n$ is odd.

Möbius band: Möbius = $(\mathbb{R} \times (0,1)) / (\text{group generated by } \varphi)$

where $\varphi(x,y) = (x+1, 1-y)$.

Since $\det(d\varphi) = -1$, φ is orientation reversing, so
 by (a), the Möbius band is nonorientable.

4. (a) For the usual atlas $\{f_i: \mathbb{R}^n \rightarrow \mathbb{RP}^n\}$ with $f_i(y_1, \dots, y_n) = [y_1, \dots, y_{i-1}, 1, y_{i+1}, \dots, y_n]$
 and $i > j$, we have:

4. (a)
Cont'd.

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\begin{bmatrix} df_1 \\ \vdots \\ df_n \end{bmatrix}$$

$$d(f_j^{-1} \circ f_i) = \begin{bmatrix} \boxed{\frac{1}{y_j}} & 0 & \dots & 0 & -\frac{y_{j+1}}{y_j^2} & \dots & -\frac{y_n}{y_j^2} \\ \vdots & \ddots & & \vdots & -\frac{y_{j+1}}{y_j^2} & \ddots & -\frac{y_n}{y_j^2} \\ 0 & \dots & \boxed{\frac{1}{y_j}} & 0 & -\frac{y_{j+1}}{y_j^2} & \dots & -\frac{y_n}{y_j^2} \\ \vdots & & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \dots & \boxed{-\frac{1}{y_j^2}} & 0 & \dots & 0 \\ \vdots & & \vdots & & -\frac{y_{j+1}}{y_j^3} & \ddots & -\frac{y_n}{y_j^3} & \vdots \\ 0 & \dots & 0 & \dots & 0 & \dots & \boxed{\frac{1}{y_j}} & 0 \\ \vdots & & \vdots & & \vdots & & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \dots & 0 & \dots & 0 & \dots & \boxed{\frac{1}{y_j}} \end{bmatrix}$$

And linear algebra gives $\det d(f_j^{-1} \circ f_i) = \frac{(-1)^{i+j}}{y_j^{n+1}}$

(the only entries contributing to this are circled in green).

So define $\tilde{f}_i: \mathbb{R}^n \rightarrow \mathbb{R}P^n$ by $\tilde{f}_i = \begin{cases} f_i & i \text{ even} \\ f_i \circ h & i \text{ odd} \end{cases}$

with $h(x_1, \dots, x_n) = (x_1, \dots, x_{n-1}, -x_n)$; then

$$\det d(\tilde{f}_j^{-1} \circ \tilde{f}_i) = \frac{1}{y_j^{n+1}} > 0 \quad \text{and } \tilde{f}_i \text{ is an oriented atlas.}$$

(b) Use the atlas from #1. The Jacobian $d(f_j^{-1} \circ f_i)$ is a $2n \times 2n$ matrix, of the same form as in (a) but with each entry in the matrix from (a) replaced by a 2×2 matrix; and this 2×2 matrix is 0 if the corresponding entry from (a) is 0. Furthermore, each of the circled entries is replaced by a matrix as follows:

$$\boxed{\frac{1}{y_j}} \rightarrow \frac{1}{x_j^2 + y_j^2} \begin{bmatrix} x_j & y_j \\ -y_j & x_j \end{bmatrix} \quad (\det = \frac{1}{x_j^2 + y_j^2})$$

$$\boxed{-\frac{1}{y_j^2}} \rightarrow \frac{1}{(x_j^2 + y_j^2)^2} \begin{bmatrix} y_j^2 - x_j^2 & -2x_j y_j \\ 2x_j y_j & y_j^2 - x_j^2 \end{bmatrix} \quad (\det = \frac{1}{(x_j^2 + y_j^2)^2}).$$

Because of the form of the matrix, a bit of linear algebra gives

$$\det d(f_j^{-1} \circ f_i) = \frac{1}{(x_j^2 + y_j^2)^{n+1}} > 0$$

So the atlas from #1 is oriented.