

Curves in \mathbb{R}^n

1. LIMITS, CONTINUITY AND DIFFERENTIATION.

Throughout this section, I is an interval, $a \in I$ and

$$\mathbf{r} = (r_1, \dots, r_n) : I \rightarrow \mathbb{R}^n.$$

In 12.5 in the book $n = 3$. Often, for the sake of brevity, we will say \mathbf{r} is a **curve**. Notice the difference between the range of \mathbf{r} (which the book calls the track) and \mathbf{r} itself.

Definition 1.1. Suppose $\mathbf{l} = (l_1, \dots, l_n) \in \mathbb{R}^n$. We say $\mathbf{r}(t)$ approaches \mathbf{l} as t approaches a and write

$$(1) \quad \lim_{t \rightarrow a} \mathbf{r}(t) = \mathbf{l}$$

if for each $\epsilon > 0$ there is $\delta > 0$ such that

$$t \in I \text{ and } 0 < |t - a| < \delta \Rightarrow |\mathbf{r}(t) - \mathbf{l}| < \epsilon.$$

Theorem 1.1. Suppose $\mathbf{l} = (l_1, \dots, l_n) \in \mathbb{R}^n$. Then (1) holds if and only if

$$\lim_{t \rightarrow a} r_i(t) = l_i \quad \text{for } i \in \{1, \dots, n\}.$$

Definition 1.2. We say \mathbf{r} is **differentiable at** a if a is an interior point of I and there is $\mathbf{r}'(a) \in \mathbb{R}^n$ such that

$$(2) \quad \lim_{h \rightarrow 0} \frac{\mathbf{r}(a+h) - \mathbf{r}(a)}{h} = \mathbf{r}'(a).$$

Theorem 1.2. \mathbf{r} is differentiable at \mathbf{a} if and only if r_i is differentiable at a for each $i \in \{1, \dots, n\}$ in which case we have

$$\mathbf{r}'(a) = (r'_1(a), \dots, r'_n(a)).$$

2. LIMIT AND DIFFERENTIATION RULES.

In 12.5 there ought to be limit rules following the pattern of Theorem 2. Let me illustrate by example. Throughout this section I is an open interval, $a \in I$ and

$$\mathbf{u}, \mathbf{v} : I \rightarrow \mathbb{R}^3.$$

Theorem 2.1. Suppose $\lim_{t \rightarrow a} \mathbf{u}(t) = \mathbf{b}$ and $\lim_{t \rightarrow a} \mathbf{v}(t) = \mathbf{c}$. Then

$$\lim_{t \rightarrow a} (\mathbf{u} \times \mathbf{v})(t) = \mathbf{b} \times \mathbf{c}.$$

Proof. Suppose $t \in I$. Then

$$\begin{aligned} & |(\mathbf{u} \times \mathbf{v})(t) - \mathbf{u} \times \mathbf{v}(a)| \\ &= |(\mathbf{u}(t) - \mathbf{u}(a)) \times \mathbf{v}(a) + \mathbf{u}(t) \times (\mathbf{v}(t) - \mathbf{v}(a))| \\ &\leq |(\mathbf{u}(t) - \mathbf{u}(a)) \times \mathbf{v}(a)| + |\mathbf{u}(t) \times (\mathbf{v}(t) - \mathbf{v}(a))| \\ &\leq |(\mathbf{u}(t) - \mathbf{u}(a))| |\mathbf{v}(a)| + |\mathbf{u}(t)|, |\mathbf{v}(t) - \mathbf{v}(a)|; \end{aligned}$$

this last quantity approaches 0 as t approaches a by limit rules from one variable calculus; here we have used the triangle inequality and the fact that the length of a cross product does not exceed the product of the length of the factors. \square

Theorem 2.2. Suppose \mathbf{u} and \mathbf{v} are differentiable at a . Then $\mathbf{u} \times \mathbf{v}$ is differentiable at a and

$$(\mathbf{u} \times \mathbf{v})'(a) = \mathbf{u}'(a) \times \mathbf{v}(a) + \mathbf{u}(a) \times \mathbf{v}'(a).$$

Proof. Suppose $h \in \mathbb{R}$ and $a + h \in I$. Then

$$\begin{aligned} & \frac{1}{h} ((\mathbf{u} \times \mathbf{v})(a + h) - (\mathbf{u} \times \mathbf{v})(a)) \\ &= \left(\frac{\mathbf{u}(a + h) - \mathbf{u}(a)}{h} \right) \times \mathbf{v}(a) + \mathbf{u}(a + h) \times \left(\frac{\mathbf{v}(a + h) - \mathbf{v}(a)}{h} \right); \end{aligned}$$

now apply limit rules to obtain the desired result. \square

3. VELOCITY, ACCELERATION AND SPEED.

Definition 3.1. Suppose \mathbf{r} is a curve. Then

\mathbf{r}' is its **velocity**,

\mathbf{r}'' is its **acceleration**

and

$|\mathbf{r}'|$ is its **speed**.

(So velocity and acceleration are vectors and speed is a scalar. Forgetting this leads to all sorts of confusion.)

4. INTEGRATION.

Suppose \mathbf{r} is a curve. Then its **integral**

$$\int_a^b \mathbf{r}(t) dt$$

can be defined using Riemann sums in the same way one defines the integral of a scalar. Note the stuff on pages 809-811.

5. PROJECTILE MOTION.

Suppose \mathbf{r} is the path of a projectile with mass m which is subject to the force $-g\mathbf{k}$ where g is the gravitational constant for the Earth's surface in units consistent with those of m . Then Newton's Second Law of Motion says

$$(m\mathbf{r}')' = -g\mathbf{k}.$$

If the mass is constant this becomes

$$m\mathbf{r}'' = -g\mathbf{k}.$$

Let $t_0 \in I$, let

$$\mathbf{r}_0 = \mathbf{r}(t_0) \quad \text{and let} \quad \mathbf{v}_0 = \mathbf{r}'(t_0).$$

(That is, \mathbf{r}_0 and \mathbf{v}_0 are the **initial position and velocity**, respectively. Integrating from t_0 to t we obtain

$$m(\mathbf{r}'(t) - \mathbf{v}_0) = -g(t - t_0)\mathbf{k}$$

so

$$\mathbf{r}'(t) = \mathbf{v}_0 - \frac{g}{m}(t - t_0)\mathbf{k}.$$

Integrating one more time from t_0 to t we obtain

$$\mathbf{r}(t) - \mathbf{r}_0 = (t - t_0)\mathbf{v}_0 - \frac{g}{2m}(t - t_0)^2\mathbf{k}$$

so

$$\mathbf{r}(t) = \mathbf{r}_0 + (t - t_0)\mathbf{v}_0 - \frac{g}{2m}(t - t_0)^2\mathbf{k}.$$

In particular, the range of \mathbf{r} lies in any plane containing the initial position, the initial velocity and \mathbf{k} .

6. PROBLEM 62 ON PAGE 815.

As written it makes no sense. What they probably mean is that if in Newton's Second Law

$$\mathbf{F} = m\mathbf{a}$$

(constant mass) where we are moving in \mathbb{R}^3 we have

$$\mathbf{F} \parallel \mathbf{r}$$

then the range (or track in the book) of \mathbf{r} lies in a plane. This is very interesting and useful. It's why, for example, the planetary motion, in the two body version, lies in a plane containing the Sun.