

### Green's Theorem.

Suppose

(1)

$$\mathbf{r} : [a, b] \times [0, 1] \rightarrow \mathbf{R}^2$$

is one to one and continuously differentiable and

$$\det \begin{bmatrix} x_s & x_t \\ y_s & y_t \end{bmatrix} > 0$$

where  $x, y$  are such that  $\mathbf{r}(s, t) = (x(s, t), y(s, t))$ ;

(2)

$$\mathbf{F} = P\mathbf{i} + Q\mathbf{j}$$

is a continuously differentiable vector field defined on  $D$  where  $D$  is the range of  $\mathbf{r}$  and

(3)  $C$  is the closed curve in  $\mathbf{R}^2$  obtained by applying  $\mathbf{r}$  to the boundary of  $[a, b] \times [0, 1]$  traversed in the counterclockwise sense: First apply  $\mathbf{r}$  to the points  $(s, 0)$  as  $s$  increases from  $a$  to  $b$ ; then apply  $\mathbf{r}$  to the points  $(b, t)$  as  $t$  increases from 0 to 1; then apply  $\mathbf{r}$  to the points  $(s, 1)$  as  $s$  decreases from  $b$  to  $a$ ; finally, apply  $\mathbf{r}$  to the points  $(a, t)$  as  $t$  decreases from 1 to 0.

Then

$$(4) \quad \iint_D Q_x - P_y dA = \int_C \mathbf{F} \bullet \mathbf{T} ds \left( = \int_C P dx + Q dy. \right)$$

**Remark.** The argument we give will also work to give Stokes' Theorem, but more computation is required. Try it and see what I mean.

**Proof.** Let  $L$  be the right hand side of (4) let  $R$  be the left hand side of (4). Set

$$I_1 = \int_a^b P(x(s, t)) \frac{\partial x}{\partial s}(s, t) + Q(x(s, t)) \frac{\partial y}{\partial s}(s, t) \Big|_{t=0}^{t=1} ds$$

and set

$$I_2 = \int_0^1 P(x(s, t)) \frac{\partial x}{\partial t}(s, t) + Q(x(s, t)) \frac{\partial y}{\partial t}(s, t) \Big|_{s=a}^{s=b} dt.$$

Note that

$$R = I_2 - I_1.$$

Using the Fundamental Theorem of Calculus we obtain

$$I_1 = \int_a^b \int_0^1 \frac{\partial}{\partial t} [P(x(s, t)) \frac{\partial x}{\partial s}(s, t) + Q(x(s, t)) \frac{\partial y}{\partial s}(s, t)] dt ds$$

and

$$I_2 = \int_0^1 \int_a^b \frac{\partial}{\partial s} [P(x(s, t)) \frac{\partial x}{\partial t}(s, t) + Q(x(s, t)) \frac{\partial y}{\partial t}(s, t)] ds dt.$$

Now

$$[Px_s + Qy_s]_t = P_x x_t x_s + P_y y_t x_s + P x_{st} + Q_x x_t y_s + Q_y y_t y_s + Q y_{ts}$$

and

$$[Px_t + Qy_t]_s = P_x x_s x_t + P_y y_s x_t + P x_{ts} + Q_x x_s y_t + Q_y y_s y_t + Q y_{ts}.$$

Using the equality of mixed partial derivatives and the fact that  $\int_a^b \int_0^1 = \int_0^1 \int_a^b$  we find that

$$R = \int \int_{[a,b] \times [0,1]} [Q_x(x(s, t), y(s, t)) - P_y(x(s, t), y(s, t))] [x_s(s, t)y_t(s, t) - x_t(s, t)y_s(s, t)] dA.$$

The proof may now be completed using the change of variables formula for double integrals.  $\square$